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**ULTIMATE STRENGTH
OF
SCHIFFLERIZED ANGLES**

by

SESHU MADHAVA RAO ADLURI

A Thesis
submitted to the
Faculty of Graduate Studies and Research
through the Department of
Civil and Environmental Engineering
in Partial Fulfillment of the requirements for
the Degree of Master of Applied Science at
the University of Windsor

Windsor, Ontario, Canada
June 1990



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ABSTRACT

Latticed triangular-base steel towers have been used as communication structures for a long time. Since these triangular-base towers are economical, they are also being increasingly used as electrical transmission line towers. The legs of these towers generally consist of 60° equal leg angles (either 90° rolled angles bent to 60° or rolled 60° angles) which are primarily compression members.

Results of experimental investigation on eighteen equal-leg schifflerized angles (90° angles bent to 60°) under concentric axial compressive loading with hinge-hinge end conditions are presented. Five sizes of angles viz. 5x5x5/16, 4x4x1/4, $3\frac{1}{2}\times 3\frac{1}{2}\times 5/16$, 3x3x3/8, 3x3x1/4 in., of 300 and 400 MPa nominal yield strength with slenderness ratios varying between 50 and 95 are included in the investigation. The nominal width-thickness ratios of legs ranged between 8 and 16. The experimental failure loads are compared with loads obtained from a finite element model. The analytical problem has been solved for failure loads under geometric and material nonlinearity. A Newtonian approach with eight-node shell elements has been employed for the nonlinear solution using commercially available software "ABAQUS". Residual stress variations along the cross-section and through-the-thickness are included. All results are compared with those obtained from CAN/CSA-S37-M86, ASCE Manual No.52 and other specifications. The value of the flat width to be used in the width-thickness ratio calculations is discussed and recommendations are made.

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NOTATION

The following symbols are used in the thesis :

A = Area of cross-section

a = Length of un-bent portion of schifflerized angle leg

b = length of bent portion of schifflerized angle leg

c = fillet radius

C_r = Compressive strength

C_w = Warping constant

d = total leg width

E = Young's modulus

F_{cr} = Critical compressive stress

F_y = Yield stress of steel

G = Shear modulus

I_{pc} = Polar moment of inertia about centroid

I_{ps} = Polar moment of inertia about shear center

J = St. Venant's torsion constant

K_u = Effective length factor in u-u (major) axis

K_v = Effective length factor in v-v (minor) axis

K_ϕ = Effective length factor in torsion

$L = l$ = Length of the column

P_{cr} = Critical load of column

P_u = Euler buckling load about u-u (major) axis

P_v = Euler buckling load about v-v (minor) axis

P_ϕ = Torsional buckling load

r = Radius of gyration

r_e = Equivalent radius of gyration for torsional-flexural mode

r_u = Radius of gyration about u-u axis

r_v = Radius of gyration about v-v axis

r_ϕ = Radius of gyration for torsional mode

t = Thickness of the leg of angle member

w = Flat width of angle member

λ = Column slenderness parameter

ν = Poisson's ratio

ϕ = Resistance factor

Chapter 1

INTRODUCTION

1.1 General

The steel angle is one of the primary members used in structural engineering. It is present in almost all steel structures playing a crucial role in resisting the direct forces, moments and shears or acting as a connection piece or as a plate stiffener. Of particular importance is its near universal usage in latticed communication structures and electrical transmission towers. The main legs of these structures are primarily fabricated from steel angles which serve to transmit the gravity loads and loads due to wind, earthquake, differential wire tensions and broken wire conditions as direct forces to the foundation. The main legs are always arranged in one of the following two ways:

1. Rectangular plan with one leg at each corner of a square or a rectangle. This arrangement is generally adopted for self-supporting electrical transmission towers. The square plan makes the analysis and design relatively simple because of the ease with which the torsional and lateral loads can be resolved into in-plane forces.
2. Triangular plan with one leg member at each of the three corners. This is employed in guyed towers, self-supporting microwave towers and sometimes in electrical transmission towers. Triangular-base towers result in a significant reduction in the weight of the structure. Several

guyed and self-supporting towers of this type with heights ranging up to 600 m have been successfully designed and erected. (Figs. 1.1 and 1.2)

In the case of triangular-base towers and guyed masts, the main legs are located at the vertices of an equilateral triangle. In order to have smooth bracing connections, the included angle between the two legs of the angle members should be 60° . This is achieved by schifflerizing the hot-rolled 90° angles. Each leg is bent inwards by 15° so that the angle between the leg and the center-line of the section is 30° instead of 45° as shown in Fig. 1.3. The process involves either re-rolling or brake-pressing a 90° angle (Figs. 1.4 and 1.5). The finished member is called a schifflerized angle. This process increases the moment of inertia of the cross-section about the minor principal axis. Consequently, the member is stronger in flexural buckling and is slightly weaker in torsional-flexural buckling when compared to the regular 90° angle. The process also introduces additional residual stresses into the section which add to the existing residual stresses due to the differential cooling of hot-rolled angles. The schifflerization process, while bending the legs inward by 15° each, cannot deform the heel (or root) portion of the original regular angle because of its high rigidity. As a result, every 60° angle will have a 90° unchanged root portion of length ranging from 16 to 40 mm depending upon the leg thickness. Strengths and behaviour of these angles will be different from the regular 90° angles.

1.2 Need for Investigation

Singly-symmetric sections such as angles, tees and channels have been studied for their compressive strengths for more than a century. However, non-standard shapes, manufacturing processes and new technology do necessitate renewed investigation from time to time [SSRC 1988]. Although 60° angles are extensively used in triangular-base towers and occasionally in triangulated open web joists, no published literature is available concerning their behaviour. Various specification-writing bodies that deal with schifflerized angles have thus far depended on knowledge extrapolated from the published literature about the regular 90° angles.

The compressive strength of schifflerized angles depends on the slenderness ratio and width-thickness ratio among other things. The only reference in CAN/CSA-S37-M86 [Canadian Standards Association 1986] to width-thickness ratios for analysis is contained in clause 6.1.1, which references CAN3-S16.1-M84 [Canadian Standards Association 1984] clause 11. However S16.1 clause 11 limits the w/t ratio to $200/\sqrt{F_y}$. Many of the steel angles used as leg members in communication and transmission-line towers have width-thickness ratios in excess of $200/\sqrt{F_y}$. Therefore there is a need for studying the behaviour of members with w/t greater than $200/\sqrt{F_y}$.

There is no unanimity about the flat width to be used in the computation of width-thickness ratios. With reference to Fig. 1.3, this value can be variously taken as dimension b , $(a+b)$, $(a+b-t)$ and $(a+b-t-c)$. There is therefore an urgent need to clearly define the width of the leg to be used in the width-thickness ratio calculations.

1.3 Objectives

The present study has the following objectives:

1. To conduct compression tests on different sizes of schifflerized steel angles. In general, the formulae given in various standard specifications cover flexural buckling and are applicable for many practical cases. However since the panels in towers, especially guyed towers, are relatively short, the 60° angles are more susceptible to the torsional-flexural buckling mode. The smaller major axis flexural capacity reduces its strength in torsional-flexural mode when compared to regular angle strength. Hence it was decided that the experiments should cover the flexural and torsional-flexural buckling modes.
2. Compare the experimental failure loads with values computed from various existing standard specifications.
3. Recommend the width w to be used to compute width-thickness ratios for schifflerized angles.
4. Investigate the possibility of developing a numerical model that will serve the purpose of actual testing by using finite element method to predict the ultimate strength of the schifflerized angles.
5. Using a finite element analysis, account for the effect of residual stresses on the axial compressive strength of the schifflerized angles.

Chapter 2

LITERATURE REVIEW

2.1 General

As already mentioned in section 1.2, there is no published literature on schifflerized angles. Engineers dealing with schifflerized angles depend on the general column formulae. Therefore, literature on concentrically loaded compression members, especially 90° equal leg angles, is reviewed.

2.2 Classical Column Research

Structural steel angles have been in constant use by engineers for more than 300 years. Their use as bracing members and main leg members is extensively recognized and studied. The theory of elastic buckling of concentrically loaded columns was initiated by Euler in 1744. The earliest column capacity studies were carried out in the early years of the nineteenth century by J. Robinson on non-steel columns and by E. Hodgkinson on iron columns [Todhunter 1960]. These tests showed that the well-known Euler formula does not correspond to the actual strengths. Considère conducted 32 column tests in 1889 and suggested modifications to Euler formula. In the same year, Engesser and Considère developed the theory of column buckling based on tangent modulus

$$P_T = \frac{\pi^2 E_T A}{\left(\frac{l}{r}\right)^2} \quad (2.1)$$

where E_T is the slope of the tangent to stress-strain curve at any particular stress in the nonlinear range, A is the area of cross-section and l/r is the slenderness ratio.

In 1895, Engesser modified his theory to define reduced modulus which lies in between E and E_T depending upon the shape of the cross section. In 1905, Johnson, Bryan and Turneaure [Johnson 1905] suggested the usage of Euler formula modified by a constant. In 1910, von Kármán improved the reduced modulus theory and illustrated it by several examples.

Templin et al. [Templin 1938] studied the column buckling phenomenon under very carefully designed laboratory conditions and found that their results showed column failure at tangent modulus loads. Shanley [Shanley 1948] came up with an important explanation to the two column theories and proved that buckling starts at the tangent modulus load.

Wagner in 1929 was the first to investigate the torsional buckling of open thin walled sections. In his work, he arbitrarily assumed that the centre of rotation coincides with the shear centre which was proved to be incorrect. Ostenfeld in 1931 was the first to derive the exact solutions for torsional-flexural buckling of angle sections [Madugula and Kennedy 1985]. Bleich [Bleich 1936,1952], Lundquist and Fligg [Lundquist 1937], Vlasov [Vlasov 1940], Goodier [Goodier 1942], Timoshenko [Timoshenko 1945,1970] and Kappus, among others, have

studied the theory of torsional-flexural buckling from various view points. Since then, the behaviour of angles has been the subject of several extensive studies.

Axially loaded equal-leg single angles can fail by either of the following modes:

1. Flexural buckling by bending about the asymmetric weaker principal axis.
2. Torsional-flexural buckling by simultaneous bending and twisting about the symmetric stronger principal axis.

The section buckles in one of the two modes depending on the length, cross-sectional dimensions and end conditions of the member. If the ends of the member are prevented from twisting, the column capacities can be computed as :

$$P_v = \frac{\pi^2 E (A r_v^2)}{(K_v L)^2} \quad (2.2)$$

$$P_u = \frac{\pi^2 E (A r_u^2)}{(K_u L)^2} \quad (2.3)$$

$$P_\phi = \frac{\pi^2 E (A r_\phi^2)}{(K_\phi L)^2} \quad (2.4)$$

in which,

$$r_\phi = \sqrt{\frac{1}{I_{ps}} \left(\frac{J (k_\phi L)^2}{2\pi^2 (1 + \nu)} + C_w \right)} \quad (2.5)$$

where P_v, P_ϕ etc. are as defined in the notation.

The critical torsional-flexural buckling load P_{cr} can be deduced from the quadratic equation [Timoshenko 1970] :

$$\frac{I_{pc}}{I_{ps}} P_{cr}^2 - (P_u + P_\phi) P_{cr} + P_u P_\phi = 0 \quad (2.6)$$

where I_{pc} is the polar moment of inertia of the cross-section about centroid.

An examination of the above equation reveals that when the ratio $\frac{P_\phi}{P_u}$ is relatively small, theoretical load P_{cr} is very close to P_ϕ and the mode of buckling is essentially torsional. For larger values of $\frac{P_\phi}{P_u}$ the critical load P_{cr} is close to P_u and the member buckles essentially in flexural mode. For an equal leg schifflerized angle the ratio $\frac{I_{pc}}{I_{ps}}$ is approximately 0.5. Substituting this value, the critical load can be calculated as:

$$P_{cr} = P_u + P_\phi - \sqrt{(P_u + P_\phi)^2 - 2 P_u P_\phi} \quad (2.7)$$

In torsional-flexural buckling, the cross-section rotates about a point called the centre of rotation, which lies on the axis of symmetry close to the shear centre. The shear center of a 90° equal-leg angle lies at the point of intersection of the two legs. For a schifflerized angle, the shear center lies at a small distance from this point on the axis of symmetry away from the centroid.

2.3 Experimental Investigation of Angles

Equal leg hot-rolled 90 x 90 x 7 mm 90° angles have been studied under concentric loading for different slenderness ratios by Wakabayashi and Nonaka [Wakabayashi and Nonaka 1965].

Yokoo, Wakabayashi and Nonaka [Yokoo et al. 1968] have studied mild-steel equal-leg single angles under concentric loading and torsional deformations. Torsional deformations were predominant in concentrically loaded specimens. They also showed that boundary conditions for twisting do not significantly effect the failure load.

Equal leg semi-killed high strength steel angles of size 75 x 75 x 6 mm and 65 x 65 x 6 mm were tested by Ishida [Ishida 1968]. The tests showed that the load carrying capacity of mild steel angles is generally higher compared to hot-rolled high-strength steel angles which contain residual stresses.

Short [Short 1977] investigated the behaviour of single angles which buckled about the rectangular "x-x" axis and the weak "v-v" axis. The minor axis buckling loads were found to be in good agreement with ECCS recommendations [ECCS 1978].

Kennedy and Madugula [Kennedy and Madugula 1972] tested 72 angle struts with different end conditions under axial loads. All specimens were reported to have failed in the inelastic range. A procedure to estimate the realistic permissible stresses for a given angle was discussed.

Haaijer, Carskadden and Grubb [Haaijer et al. 1981] explored the feasibility of using a finite element analysis as an alternative to a physical experiment. The study included elastic behaviour.

2.4 Design Specifications

Canadian National Standard CAN/CSA-S37-M86 for towers and antenna-supporting structures deals with triangular-base towers and 60° angles. The proposed amendment No.12 dated May 8, 1990 specifies formulae similar to ASCE Manual No. 52 to include the effect of w/t ratio.

ASCE Manual No. 52 "Guide for the Design of Steel Transmission Towers " is extensively used for the design of hot-rolled angle members including 60° schifflerized sections that are used in steel transmission towers and communication structures. The formulae given for ultimate capacity are based on Euler buckling in the elastic range and on the basic strength curves of the Structural Stability Research Council in the inelastic range.

The European practice for the design of angle members is found in the " Recommendations for Angles in Lattice Towers " published by the European Convention for Constructional Steelwork [ECCS 1985]. Design procedures are included for concentrically loaded angles used in towers. The North American and the European specifications are summarized below.

2.4.1 CAN/CSA-S37-M86 proposed amendment

Maximum " w/t " ratio = 25

Effective yield stress - F'_y

i). When

$$w/t \leq 200/\sqrt{F_y}; \quad F'_y = F_y \quad (2.8)$$

ii) When

$$200/\sqrt{F_y} < w/t \leq 380/\sqrt{F_y}; F'_y = F_y \left[1.677 - 0.677 \left\{ \frac{\frac{w}{t}}{\frac{200}{\sqrt{F_y}}} \right\} \right] \quad (2.9)$$

iii) When

$$380/\sqrt{F_y} < w/t \leq 25; F'_y = \frac{56415}{\left(\frac{w}{t}\right)^2} \quad (2.10)$$

where, F_y is the yield stress in MPa.

Factored axial compressive resistance - C_r

$$0 < \lambda \leq 0.15, \quad C_r = \phi A F'_y \quad (2.11)$$

$$0.15 < \lambda \leq 1.0, \quad C_r = \phi A F'_y (1.035 - 0.202\lambda - 0.222\lambda^2) \quad (2.12)$$

$$1.0 < \lambda \leq 2.0, \quad C_r = \phi A F'_y (-0.111 + 0.636\lambda^{-1} + 0.087\lambda^{-2}) \quad (2.13)$$

$$2.0 < \lambda \leq 3.6, \quad C_r = \phi A F'_y (0.009 + 0.877\lambda^{-2}) \quad (2.14)$$

$$3.6 < \lambda, \quad C_r = \phi A F'_y \lambda^{-2} = \phi A \left[1\,970 \frac{000}{(KL/r)^2} \right] \quad (2.15)$$

where,

$$\lambda = \frac{KL}{r} \sqrt{\frac{F'_y}{\pi^2 E}} \quad (2.16)$$

2.4.2 ASCE Manual No. 52 (1988)

The ultimate compressive stress F_u of axially loaded compression members shall be:

$$F_u = \left[1 - \frac{1}{2} \left(\frac{KL/r}{C_c} \right)^2 \right] F_y \quad \text{when} \quad KL/r \leq C_c \quad (2.17)$$

$$F_u = \frac{286000}{\left(\frac{KL}{r} \right)^2} \quad \text{when} \quad KL/r \geq C_c \quad (2.18)$$

$$C_c = \pi \left(\frac{2E}{F_y} \right)^{\frac{1}{2}} \quad (2.19)$$

2.4.2.1 Maximum w/t Ratio

The ratio w/t , where w = flat width and t = thickness of leg, shall not exceed 25. If w/t exceeds $(w/t)_{\text{lim}}$ given by

$$\left(\frac{w}{t} \right)_{\text{lim}} = \frac{80}{\sqrt{F_y}}; \quad (2.20)$$

then the ultimate stress F_u shall be computed with F_y replaced in the above equations with F_{cr} given by

$$F_{cr} = \left[1.677 - 0.677 \frac{w/t}{(w/t)_{\text{lim}}} \right] F_y \quad \text{when} \quad \left(\frac{w}{t} \right)_{\text{lim}} \leq \frac{w}{t} \leq \frac{144}{\sqrt{F_y}} \quad (2.21)$$

$$F_{cr} = \frac{9500}{(w/t)^2} \quad \text{when} \quad \frac{w}{t} > \frac{144}{\sqrt{F_y}} \quad (2.22)$$

where F_y is the yield strength in ksi.

2.4.3 AISC - Load and Resistance Factor Design Specification

The design strength of members whose elements have width-thickness ratios less than $76/\sqrt{F_y}$ (where F_y is in ksi) is $\phi_c P_n$.

$$\phi_c = 0.85 \quad (2.23)$$

$$P_n = A_g F_{cr} \quad (2.24)$$

When $b/t < 76.0/\sqrt{F_y}$, (where F_y is in ksi.),

$$Q = 1.0 \quad (2.25)$$

When $76.0/\sqrt{F_y} < b/t < 155/\sqrt{F_y}$;

$$Q = 1.340 - 0.00447(b/t)\sqrt{F_y} \quad (2.26)$$

When $b/t \geq 155/\sqrt{F_y}$;

$$Q = 15500 / [F_y (b/t)^2] \quad (2.27)$$

2.4.3.1 Flexural Buckling

For $\lambda_c \leq 1.5$

$$F_{cr} = (0.658^{\lambda_c^2}) F_y \quad (2.28)$$

For $\lambda_c > 1.5$

$$F_{cr} = \left[\frac{0.877}{\lambda_c^2} \right] F_y \quad (2.29)$$

where,

$$\lambda_c = \frac{K l}{r \pi} \sqrt{\frac{F_y}{E}} \quad (2.30)$$

A_g = gross area of member

F_y = specified yield stress, ksi

E = modulus of elasticity

K = effective length factor

l = unbraced length of member

r = governing radius of gyration about plane of buckling

To calculate the design strength of members whose elements have width-thickness ratios greater than $76/\sqrt{F_y}$ (where F_y is in ksi.), λ_c and F_y are modified as $\lambda_c \sqrt{Q}$ and $F_y Q$

2.4.3.2 Torsional-Flexural Buckling

The nominal critical stress F_{cr} is determined as follows:

a. For $\lambda_c \sqrt{Q} \leq 1.5$:

$$F_{cr} = Q(0.658^{Q\lambda_c^2})F_y \quad (2.31)$$

b. For $\lambda_c \sqrt{Q} > 1.5$:

$$F_{cr} = \left[\frac{0.877}{\lambda_c^2} \right] F_y \quad (2.32)$$

where

$$\lambda_c = \sqrt{F_y / F_e} \quad (2.33)$$

$$F_y = \text{specified minimum yield stress of steel, ksi} \quad (2.34)$$

$$F_e = \text{critical torsional-flexural elastic buckling stress, ksi} \quad (2.35)$$

2.4.4 BS 5950 : Part 1 : 1985

The compressive resistance C_r of an angle section is given as

$$C_r = A p_{cr} \quad (2.36)$$

when $w/t \leq 11.5 \sqrt{275/F_y}$,

p_{cr} is obtained from the Perry strut formula.

$$p_{cr} = \frac{p_E p_y}{\phi + \sqrt{\phi^2 - p_E p_y}} \quad (2.37)$$

where,

$$\phi = \frac{p_y + (\eta + 1) p_E}{2} \quad (2.38)$$

where, p_E is the Euler strength; p_y is the design strength; η is the Perry factor.

The Perry factor η for flexural buckling under load should be obtained from :

$$\eta = 0.001 a (\lambda - \lambda_o) > 0 \quad (2.39)$$

where, a is the Robertson constant taken as 5.5 for angle struts and limiting slenderness ratio,

$$\lambda_o = 0.2 \sqrt{\left(\frac{\pi^2 E}{p_y} \right)} \quad (2.40)$$

When w/t exceeds the limiting value, a reduction factor given by the lesser of

$$\frac{11}{\frac{a+b}{t \sqrt{\frac{275}{F_y}}} - 4} \quad (2.41)$$

and

$$\frac{\frac{19}{2(a+b)}}{t\sqrt{\frac{275}{F_y}}} - 4 \quad (2.42)$$

is applied to the yield stress (a and b are as per Fig. 1.3).

2.4.5 ECCS Recommendations (1985)

$$\text{Non-dimensional slenderness ratio } \Lambda = \lambda / (\pi \sqrt{E/F_{cr}}) \quad (2.43)$$

For equal leg rolled angles,

$$\text{For } \frac{b}{t} \leq \left(\frac{b}{t}\right)_{\lim} = 0.567 \sqrt{E/F_{cr}} = 260 / \sqrt{F_{cr}}, \quad F_{cr} = F_y; \quad (2.44)$$

$$\text{For } \left(\frac{b}{t}\right)_{\lim} < \left(\frac{b}{t}\right) < \frac{4}{3} \left(\frac{b}{t}\right)_{\lim}, \quad F_{cr} = F_y \left[2 - \left(\frac{b}{t}\right) / \left(\frac{b}{t}\right)_{\lim} \right]; \quad (2.45)$$

$$\text{For } \frac{b}{t} > \frac{4}{3} \left(\frac{b}{t}\right)_{\lim}, \quad F_{cr} = \pi^2 E / (5.1 b/t)^2; \quad (2.46)$$

Values of non-dimensional column curve are given in Table 2.1.

Chapter 3

THEORETICAL ANALYSIS

3.1 Classical Theory

Basic column buckling problem has been under investigation for the last two hundred years. Classical buckling is formulated in the form of differential equations. Solutions of these equations are presented in chapter 2.

3.2 Finite Element Analysis

The finite element method can be applied to problems which cannot be effectively handled by classical theory such as nonlinear buckling coupled with irregular geometry, residual stresses etc. In the present investigation, finite element analysis is employed to study the schifflerized steel angle under various failure modes. Software package ABAQUS [ABAQUS 1989] has been used for the computer runs.

3.2.1 Discretization

For the purpose of analysis, the schifflerized angle member has been discretized into several strips of elements along the length (Figs. 3.1 and 3.2). Eight-node shell elements with 6 degrees of freedom at each node are used. The element stiffness is computed using a reduced integration scheme with four Gauss points per element.

Direct concentric loading for hinged end conditions poses a problem because the centroid of the singly symmetric angle lies outside the finite element mesh. The shell elements cannot have in-plane loading except in the form of concentrated nodal loads. Boundary conditions in the form of displacement restraint and free rotation of all nodes at each end have proved to stiffen the member. In the actual hinged end conditions, the centroid is prevented from lateral movement but is allowed to freely rotate in the two lateral directions. Any rotation at the centroid results in the movement of points on the member surface at both the ends. Restraining the member ends from translation results in increased rotational stiffness and reduces the effective length. To avoid the problem, an end plate is attached to the entire section at each end. This plate is also discretized into several elements (Fig. 3.3). The plate is made sufficiently rigid to avoid possible bending and consequent interference with the main member elements. Boundary conditions are defined only at the centroidal points on the end plates. This allows a perfect hinge condition for the member under study. The assembly consisting of the discretized member and the two end plates is loaded in the axial direction at the precomputed centroidal points.

3.2.2 Nonlinear Analysis

The problem of buckling can be solved in two ways.

1. By forming a geometric stiffness matrix of the entire structure under a fraction of the loading pattern and extracting eigenvalues and mode shapes. This is useful only when the structure remains elastic until buckling.

2. By conducting a nonlinear analysis. In this case, buckling is indicated by excessive deformations and consequent reduction in load carrying capacity.

In the present study buckling loads are estimated using nonlinear analysis. This method allows for both material and geometric nonlinearities in the structure.

Several solution techniques are available to tackle such problems [Powell and Simons 1981; Bergan et al. 1978; Crisfield 1986; Matthies and Strang 1979]. Of these, Newtonian strategies are widely known. The nonlinear solution is obtained by iteratively solving a series of linear problems. At any displacement configuration, let $\{u\}$ be the vector of nodal displacements; $\{F_e\}$ the vector of external nodal loads; $\{F_i\}$ the vector of internal resisting forces; $[K]$ the tangent stiffness at the present displacement state. The unbalanced portion of the nodal forces is given by

$$\{F_u\} = \{F_e\} - \{F_i\} \quad (3.1)$$

$\{F_u\}$ represents the error in the present solution as represented by the displacement state $\{u\}$.

The iterative technique for Newtonian type solutions is as follows:

$$\{F_u^j\} = \{F_e\} - \{F_i^j\} \quad (3.2)$$

$$\Delta r^j = [K^j]^{-1} F_u^j \quad (3.3)$$

$$r^{j+1} = r^j + \Delta r^j \quad (3.4)$$

$$F_i^{j+1} = \text{function of } r^{j+1} \quad (3.5)$$

The structure loading is divided into several increments and at each increment, the nonlinear equations are solved using either Newton's method or variations of

it which are referred to as quasi-Newtonian techniques. These involve various types of automated control of load increment, handling of snap-through buckling, etc.

3.2.3 Determination of Failure Load by Finite Element Method

The schifflerized angle finite element model is used to perform a nonlinear static analysis under concentric loading. The load at which the member starts to have a decrease in axial load capacity or becomes geometrically unstable is considered as the buckling load. The finite element model cannot have such failure under a perfectly concentric load alone. Under a perfectly concentric load, the only failure possible is that when the section becomes entirely plastic and material instability sets in. In the real specimen the load is invariably eccentric and at the buckling load, this eccentricity initiates large deformations. In the finite element model this can be simulated by creating an artificial eccentricity for the applied load in the form of an initial out-of-straightness. This is generally done by assuming that the initial geometry is in the form of a half sine-wave with central deviation equal to $1/500$ to $1/2000$ of the member length. In the present study, this is achieved by placing small trigger loads at strategic points to create the desired buckling mode. For flexural buckling, a small load of about $1/1000$ of the expected failure load is applied at the mid-height along the major axis. For torsional-flexural buckling mode, a trigger load is applied at the heel of the angle at mid-height in the minor axis direction. This creates a load in the minor axis direction and a torque about the centroid which starts the torsional-flexural mode. The same effect can be achieved by applying end moments at the centroid or two loads at the toes of the legs at mid-height. However, care must be taken to avoid

mixing up of the two modes, as the moments in flexural mode tend to shift the load from centroid towards or away from the shear centre which in turn alters the torsional-flexural load capacity considerably.

3.2.4 Residual Stresses

Hot rolled angles develop residual stresses because of the differential cooling process. These residual stresses affect the ultimate load carrying capacity of the member by initiating yielding of some parts of the member before the other parts. Residual stress pattern for 90° angles has been studied by a number of researchers. It is currently an accepted practice to adopt the recommendations made by ECCS [ECCS 1985] as shown in Fig. 3.4. The stresses given in Fig. 3.4 are in the longitudinal direction. In the present investigation, a residual stress distribution similar to Fig. 3.4 is used for the schifflerized angle. In addition, the schifflerization process involves permanent bending of the legs of the angle. This is achieved only by yielding of the section around the line of bending. Release of the section after schifflerization induces residual stresses in the leg which vary through-the-thickness of the leg in the transverse direction (Fig. 3.5). These stresses do not directly affect the axial buckling load. However, the transverse residual stresses introduce longitudinal stresses because of the Poisson's effect. Hence, the residual stress distribution in the longitudinal direction for schifflerized angle is a superimposition of the variation due to hot-rolling as given by ECCS [ECCS 1985] and the variation due to schifflerization process. Numerical simulation of residual stresses with the shell element model is achieved by defining an initial stress pattern at each of the integration points through a user subroutine. For the purpose of 'through-the-thickness' variation of residual stress,

the shell element thickness is divided into twelve parts and the residual stress is defined at each of the resulting thirteen points. The total residual stress which is the sum of longitudinal 'hot-rolling' stress and the longitudinal 'schifflerization stress' at each of the thirteen points is taken as the starting stress which is added to the stress due to external loading in the first load increment. In effect, the residual stresses are treated as results of an earlier linear elastic load case.

Typical deformed shapes of schifflerized angles under nonlinear analysis are shown in Figs. 3.6 to 3.10.

Typical outputs from ABAQUS for failure load are given in the Appendices D, E and F.

Chapter 4

EXPERIMENTAL INVESTIGATION

4.1 General

Tests were conducted on five different sizes of schifflerized angles with 5x5x5/16, 4x4x1/4, 3.5x3.5x5/16, 3x3x3/8 and 3x3x1/4 in. nominal dimensions. These sections are generally used in panels with heights ranging between 1.2 and 2.0 m. To represent a typical field usage, column slenderness ratios are chosen to range between 50 and 100.

All members are tested under pinned end conditions so that the critical section for buckling will be at the mid-height. This reduces the effect of end plate assembly on the critical section to a minimum [SSRC 1988].

4.2 End Connections

Hinged end conditions are created using an assembly of plates and knife-edges. Each end is made up of an assembly consisting of three plates separated by two knife-edges (Fig. 4.1). The middle plate contains straight grooves (angle of cut 120°), one at the top and one at the bottom. These grooves are made perpendicular to each other in order to facilitate free rotation in two orthogonal directions. The top and bottom plates contain grooves (angle of cut 90°) on one side, facing the middle. The top and bottom plate grooves hold the knife-edges firmly while the knife-edges are free to rotate on the middle plate.

The knife-edge is made of a 30 mm square bar placed on edge. One edge fits completely into the top (or bottom) plate groove while the diagonally opposite edge fits loosely into the groove on the middle plate. One such assembly is attached to a bracket from a loading frame while the other assembly is placed on top of the loading cell. The angle specimen is placed in between the two end-plate assemblies. The effective length of the member is the distance between the free rotating edge of bottom knife-edge to the free rotating edge of the corresponding parallel knife-edge at the top. The top and bottom assembly axes are arranged perpendicular to each other in order to achieve the same effective length in both major and minor axes. To facilitate the alignment of the specimen and to prevent the ends of the specimen from slipping or kicking out during the loading, the plates directly bearing the member are provided with movable blocking plates (Fig. 4.2). Once the alignment of the column is fixed, these blocking plates can be firmly screwed to the bearing plates. This holds the member firmly in place and prevents accidental kicking out.

4.3 Fabrication of Test Specimens

Three angle members per size tested are cut from the same stock to minimize variations and imperfections. The length of each member was approximately 1.5 m. Both ends of each specimen are milled to be perfectly parallel to each other and perpendicular to the longitudinal axis. The ends are supported on top and bottom plate assemblies by simple bearing. The ends are prevented from lateral movement by movable blocks.

4.4 Alignment of Test Specimen

The most critical aspect of the column testing under concentric loading is its alignment. The member should be placed in the loading arrangement in such a way that the longitudinal axis and the line of action of the load coincide. Alignment eccentricity of as low as 5% of the cross-sectional dimension can cause considerable reduction in failure load. Alignment based on calculated values of centroid marked on the bearing surfaces can give errors because of the possible shift of knife-edges, load cell, jack etc., while setting up the specimen. Alignment based on theodolite readings was not found to be very satisfactory. To avoid such difficulty, the final alignment of specimen is achieved by the use of electrical resistance strain gauges. The specimen surface is carefully prepared using air operated grinders. Several 5 mm electrical strain gauges (steel type : SHOWA-N11-FA-5-120-11) are installed on the prepared surface of the specimen (Fig. 4.3). The wide scatter in the location of these strain gauges enables the detection of any strains due to bending of the member under eccentric loading. The strain gauges are connected to standard resistance bridges which give readings in microstrains. The member is loaded initially to about 20% of the expected failure load and all the strains are recorded. Differences in the strains indicate the possible bending due to eccentricity at top and or bottom. For a perfectly aligned specimen, strain in all gauges should be the same. If they are different from each other, the member is unloaded and is readjusted to reduce eccentricity. The process is continued to achieve the best possible alignment (for a typical test specimen, the total number of such adjustments can vary from 20 to 80 and can take 2 to 6 hours).

4.5 Testing

A 900 kN hydraulic jack was used to apply compressive loading. This is connected to a pump which gives adequate control of the loading process. A 900 kN universal flat load cell is placed on the jack and is connected to a pre-calibrated digital load indicator.

The load was applied in steady increments usually at about 5% to 10% of expected failure load. The complete setup is shown in Figs. 4.3 to 4.6 . These show the bottom support, the flat jack, pump, flat load cell, bottom and top end-plate assemblies, load and strain indicators. A typical test took an average of 6 hours to complete. Figs. 4.7a to 4.13 show typical test specimens in their buckled state.

In concentric column testing, the strain gauge readings and load-deflection data are used to monitor the alignment of the test specimens and to get an idea of the approach of failure load. In the present investigation, the deflections and rotation at mid-height were measured using mechanical dial gauges having a travel of 75 mm and a 0.01 mm least reading.

Typical load-deflection data and strain gauge readings are shown in Appendix A.

4.6 Tension Test on Standard Coupons

Tension tests were conducted on standard size coupons from the same stock as that of test specimens. The strain is measured on a 50 mm gauge length by a metal testing averaging type breakaway extensometer. The results are plotted on a flat bed X-Y electronic recorder. Fig. 4.14 shows a typical tensile coupon being

tested in a 600 kN Tinius Olsen Universal Testing Machine. Two coupons are tested for each section size (Figs. 4.15a to 4.15c). Average values of yield stresses are used in computations.

4.7 Stub Column Testing

For the purpose of determining the magnitude of residual stresses, the member is normally sliced into thin strips. This relieves the initial strain and thus changes the length of the strip. The difference in these lengths gives a measure of residual stresses. The effect of through-the-thickness variation of the residual stresses can be found by drilling holes on the surface of the test specimen to the desired depth and observing the change in strain in an electrical resistance gauge. However, in the present study the overall magnitude of the residual stresses in the section is sought to be measured using stub column test.

The stub column test gives a measure of the total effect of residual stresses on the column strength. For this purpose, a piece of the test section 330 mm long was cold sawed from the same stock as those of the test specimens. The length was chosen as per SSRC guidelines. The ends of the stub column thus obtained were milled plane and perpendicular to the longitudinal axis. The properties were measured and recorded. The stub column was then tested in a universal testing machine to obtain the stress-strain relationship (Fig. 4.16).

Chapter 5

DISCUSSION OF RESULTS

5.1 General

This chapter describes the results of experimental investigation and theoretical analysis. The geometric and mechanical properties of the test specimens are first determined. The data thus obtained is used for finite element analysis and to calculate loads as per various standard specifications. Both quantitative and qualitative observations made during the course of the entire investigation are discussed. The objective of this discussion is to interpret and understand the results and to focus on their implications.

5.2 Properties

5.2.1 Geometric Properties

Geometric properties of angles have been calculated based on the accepted practice in North America. The cross-section is idealized into segments of four rectangles by ignoring toe and fillet radii (Fig. 1.3) and the following formulae are derived for geometric properties.

$$A = \text{area of cross-section} = 2t(a+b-t/2) \quad (5.1)$$

$$d = \text{leg width} = a+b \quad (5.2)$$

$$u_c = \frac{2(a-t/2)^2 + 4b(a-t/2) + \sqrt{6}b^2}{4\sqrt{2}(a+b-t/2)} \quad (5.3)$$

$$I_u = 2 (I_{u1} + I_{u2}) \quad (5.4)$$

where,

$$I_{u1} = \frac{3bt^3}{16} + \frac{b^3t}{48} + bt \left(\frac{b}{4} + \frac{(a-t/2)}{\sqrt{2}} \right)^2 \quad (5.5)$$

and

$$I_{u2} = \frac{(a-t/2)t^3}{24} + \frac{t(a-t/2)^3}{6} \quad (5.6)$$

$$I_v = 2 (I_{v1} + I_{v2}) - Au_c^2 \quad (5.7)$$

where,

$$I_{v1} = \frac{bt^3}{48} + \frac{3b^3t}{48} + bt \left(\frac{(a-t/2)}{\sqrt{2}} + \sqrt{3}\frac{b}{4} \right)^2 \quad (5.8)$$

and

$$I_{v2} = \frac{(a-t/2)t^3}{24} + \frac{t(a-t/2)^3}{6} \quad (5.9)$$

$$I_{pc} = I_u + I_v \quad (5.10)$$

$$I_{ps} = I_{pc} + Au_c^2 \quad (5.11)$$

$$r_u = \sqrt{\frac{I_u}{A}} \quad (5.12)$$

$$r_v = \sqrt{\frac{I_v}{A}} \quad (5.13)$$

$$r_{ps} = \sqrt{\frac{I_{ps}}{A}} \quad (5.14)$$

$$J = \frac{2}{3} (a+b-t/2) t^3 \quad (5.15)$$

$$R = \text{shape factor} = 1 - \frac{u_c^2}{r_{ps}^2} \quad (5.16)$$

$$r_e = \frac{1}{2R} \left(r_u^2 + r_\phi^2 - \sqrt{(r_u^2 + r_\phi^2)^2 - 4Rr_u^2 r_\phi^2} \right) \quad (5.17)$$

where all the symbols are explained in the notation.

All cross-sectional properties are computed using the computer program given in Appendix B. (The geometric properties are obtained by converting the imperial dimensions into SI system). The actual cross-sectional dimensions d and t are measured at five locations along the length on each leg and their average is adopted for further computations. The unschifflerized length 'a' of each section is taken as per the current practice in industry. The actual and nominal properties used in computing member strengths are listed in Tables 5.1a to 5.1f. An examination of these properties reveals that the member areas for specimens with nominal sizes 5x5x5/16, 4x4x1/4 and 3x3x1/4 in. are lower by up to 2.5% when compared to the nominal areas. For members of sizes 3.5x3.5x5/16 and 3x3x3/8 in., the areas are higher by up to 2% when compared to the nominal areas. The moments of inertia for sizes 5x5x5/16 and 4x4x1/4 in. are lower by up to 5% when compared to the moments of inertia based on nominal dimensions. The corresponding values for the remaining specimens are higher by up to 5% when compared to their nominal values.

5.2.2 Mechanical Properties

Results of tests on tensile coupons (as per ASTM standards) were used to determine the mechanical properties of the material being tested. One coupon per leg per section size was selected. The load-strain curves for each of these coupons are presented in Figs. 4.15a to 4.15c. The actual yield stress calculated as the average of the yield stress from both the legs of the section is used in all computations. The actual yield stresses are found to be 11 to 23% higher than the corresponding nominal values. The value of Young's modulus is taken as 200 000 *MPa* as per established practice. Table 5.2 lists the mechanical properties of the tensile coupons.

5.3 Theoretical Computations

5.3.1 Classical Approach

Theoretical investigation involves classical column buckling theory. If the member has a nonlinear stress-strain relationship, the failure loads can be estimated using the tangent modulus E_T instead of E for flexural buckling. An approximate shear modulus which is generally taken as G_T [where, $G_T = E_T / 2(1 + \nu)$] can be used for torsional-flexural buckling. However, if the member enters the plastic stage, the classical theory fails to give accurate results. In addition, the classical theory cannot effectively handle the residual stress distributions. All specimens used in the investigation fall in the intermediate range of slenderness. All test columns entered plastic stage. The classical elastic theoretical loads are computed using the computer program given in Appendix C. Since all the specimens failed by inelastic buckling, the results

obtained from the classical elastic theory are not presented for discussion.

5.3.2 Finite Element Analysis

The finite element analysis as described in Chapter 3 has been carried out for each of the test specimens using the actual dimensions. Elastic range is defined using nominal value for Young's modulus ($E=200\,000$ MPa). An elastic-perfectly plastic model is used for material nonlinear analysis.

In order to verify the suitability of the present model of finite element analysis for the problem, a series of numerical tests were carried out using commercially available software "ABAQUS" (as mentioned in Ch.3).

5.3.2.1 Convergence Test for Flexural Buckling

To test the convergence properties of the finite element mesh, a sample problem is analyzed for purely elastic case.

A $150 \times 150 \times 10$ mm 90° angle specimen of length 2500 mm has been selected for flexural buckling mode. The member was discretized using eight-node shell elements and analyzed for geometric nonlinear failure load under perfectly elastic conditions. The initial crookedness is introduced by a small concentric load which is about $1/500$ of the expected failure load, applied in the u-u direction at mid-height (the same method is followed in the actual analysis of the test specimen). The mesh has converged close to the theoretical buckling load as predicted by classical theory (Fig. 5.1).

5.3.2.2 Convergence Test for Torsional-Flexural Buckling

A 150x150x10 mm 90° angle specimen of length 1525 mm has been selected for torsional-flexural buckling mode. The angle is discretized in the same manner as in the case of flexural buckling mode. The problem is analyzed under initial crookedness to create torsional-flexural buckling. Over twenty different ways of creating the torsional buckling mode have been employed and the failure loads were estimated under perfectly elastic conditions. All the different ways of creating the torsional failure have given the results within a close range. Of these models, the crookedness introduced by a mid-height concentrated load at the toe of each leg forming a twisting couple and a resultant load in the minor axis direction has been found to yield results closest to the theoretical load. This mode of initial out-of-straightness has been adopted for further mesh refinement. The mesh has again converged quickly to the estimated theoretical load (Fig. 5.2).

The same kind of analysis has been carried out for elastic-perfectly plastic model for both flexural and torsional-flexural modes of failure. The rate of convergence of the mesh has been observed and the optimal mesh size has been selected as one with 5 segments along the length with 8 elements per segment.

5.3.2.3 Effect of Thickness of End Plates

To test the effect of the end plate rigidity on failure load, a perfectly elastic problem has been analyzed with varying thicknesses of end plates. It is found that an end plate thickness that is less than five times the leg thickness of the angle member has an effect on the failure load. For such thicknesses the end plate tries to bend along with the member legs and the resulting failure load does not represent the true buckling load.

5.3.2.4 Effect of the End Plate Size

To test the effect of the end plate size on the failure load, an elastic model has been analyzed with various shapes of the end plate having thickness equal to 16 times the leg thickness. It is found that any reasonable shape of the plate that connects the centroid of the section with all the nodes of the leg elements gives satisfactory results.

5.3.2.5 Effect of End Plate Assemblies

To test the effect of the end connections used in actual testing setup, the end plate-knife-edge assembly (Fig. 4.1) has been discretized using shell elements. For such assembly of plates, the finite element model assumes the nodes to be in the mid-surface of each plate. In the physical setup, these surfaces are not in actual contact with each other but are separated by the thicknesses of the plates. The problem of thickness offset of the elements because of the “plate to knife-edge to plate” connection has been studied in two ways:

1. By giving actual thickness to each plate and average thickness to the knife-edge along their centre lines and connecting them with multi-point constraints to transfer displacements and rotations.
2. By employing very rigid shell elements with large thickness to close the gap between the centerlines of plates and the edges of knife-edges.

In both the cases, the finite element modelling of the end plate assembly did not show appreciable difference in failure load from the load obtained using a single plate at each end of the full effective length of the member.

5.3.2.6 Effect of Variation of Yield Stress

Effect of the variation of the material yield stress on the failure load has been studied using a 75x75x10 mm 60° angle of length 1650 mm. As expected, the results show a nonlinear relationship between yield stress and the failure load (Fig. 5.3).

5.3.2.7 Effect of Variation of Young's Modulus

Effect of variation of Young's modulus on the failure load of an elastic-plastic column, studied using the same model as above has revealed that the finite element failure load for a constant yield stress does not vary linearly with Young's modulus. The failure load (Fig. 5.4) varies in a slightly nonlinear manner with increase in the value of E. But for practical purposes, the variation from linearity is negligibly small.

5.3.2.8 Effect of Location of Load Point

Effect of the location of the point of application of the axial load has been extensively studied using the finite element model. The results showed that an eccentricity of even five percent of the leg width can considerably reduce the flexural buckling capacity of the column. The results also confirmed the prediction of classical theory, that the member will have higher torsional-flexural buckling capacity if the point of application of axial load moves towards the centre of rotation [Timoshenko and Gere 1970].

5.3.2.9 Effect of Slenderness Ratio

Effect of the slenderness ratio on the failure load has been studied using a 75x75x10 mm 60° angle (nominal yield 300 MPa). The resulting relationship between load and slenderness ratio has followed the established predictions (Fig. 5.5). In the elastic range, the curve follows Euler equation and in the inelastic range, the curve shows a trend similar to that of the ECCS curves.

5.3.2.10 Effect of Residual Stresses

Effect of the residual stresses on the angle member has been studied by adopting a slightly modified version of the ECCS recommendations. All the maximum ordinates of the standard ECCS residual stress curve are taken to be equal in magnitude disregarding the small variation in the original curve. A 75x75x10 mm column of length 1020 mm has been studied with varying magnitudes of the residual stress ordinates. The influence of the maximum residual stress ordinate as percentage of yield stress on the failure load of a typical member is presented in Fig. 5.6. The rate of reduction of failure load decreases with increase in the percentage of residual stress.

The effect of through-the-thickness variation of the residual stresses on failure load has been computed and has been found to be less than 2% to 4% of the load without such variation.

The effect of the transverse residual stresses due to schifflerization process has been studied by defining initial stresses in the transverse direction at thirteen points along the cross-section thickness near the line of bend of each leg. It is found that these stresses do not effect the axial load carrying capacity of the member.

5.4 Experimental Investigation

5.4.1 Member Capacities

This section focuses on the ultimate load capacity and the failure modes of test specimens.

Of the five different sizes of members tested, sizes 5x5x5/16 in. and 4x4x1/4 in. were analyzed beforehand and were chosen with the appropriate length so as to cause failure in torsional-flexural mode. All six specimens tested for these sizes failed in the torsional-flexural mode as expected. It is interesting to see in the published literature, a long drawn-out debate about the legitimacy of calling torsional-flexural buckling as local plate failure. CAN3-S 16.1-M84 [Canadian Standards Association 1984] specifies a limiting (w/t) ratio of $200/\sqrt{F_y}$. This limit is generally taken to represent the susceptibility of the leg plate to local failure. Angles in both the sizes 5x5x5/16 in. and 4x4x1/4 in. have (w/t) ratio in excess of this limit. In the present investigation, the failure process has been closely monitored in order to determine the nature of buckling. Initial load increments were kept at about 1/20 of the expected failure load. As the load approached the failure limit, the load increments were reduced to about 1/50 of the buckling load. In all the six test specimens in this category, the failure occurred suddenly and without any delay between local plate failure and overall torsional-flexural buckling. But it may be of interest to note that from the angle of observation during the present investigation, the failure seemed to have occurred first in local plate buckling mode, immediately followed by failure in overall torsional-flexural buckling mode. The failure is always accompanied by a loud noise. None of the failures were purely in plate buckling mode. No member

failed by local failure of plates in which legs buckled in opposite directions. It may also be of interest to note that there was an appreciable amount of flexural bending about the minor axis in all the torsional-flexural buckling modes. However, the minor axis flexural buckling did not seem to be affecting the magnitude of failure load.

All the members in this category have tried to twist the end plate assembly at the time of buckling. In the present setup, the top plate assembly has been firmly fixed to the top bracket which is attached to the loading frame. The bottom plate assembly however, has been placed on top of the flat load cell, which in turn rests on top of the flat jack. There is no special arrangement at the bottom to prevent twisting of the member except the high static frictional force developed under the buckling load. Members of size 4x4x1/4 in. have failed while attempting to twist the bottom plate assembly on top of the flat jack. The final failure was accompanied by twisting of the bottom end of the member. The first two specimens of this category have failed in the bottom 1/5 portion of the member height (Figs. 4.7a to 4.7c). When specimen S4-1/4-3 has been tested under a temporary arrangement to resist bottom plate rotation, the member could not manage to twist the support assembly, but failed in the top 1/5 portion of the member height (Fig. 4.8). The failure load of this specimen was recorded to be approximately 10% higher than the other two specimens of the same size and length. The result seemed to contradict the finding of Yakoo et al. that end conditions do not effect the failure load in torsional-flexural buckling mode. However it should be noted that the present observation is made on the basis of only a few test specimens and no attempt has been made to measure the amount of

partial restraint offered by the static friction between the end plate assembly and the load cell. The real increase in failure load might have been due to some partial restraint to the end rotation of the member about major axis provided by the temporary arrangement.

Members of size $5 \times 5 \times 5/16$ in. failed in torsional-flexural mode at mid-height. In all cases, some twisting of the bottom assembly was observed (Figs. 4.9a and 4.9b).

Specimens of nominal size $3 \times 3 \times 1/4$ in. have their (w/t) ratio just bordering on the specified limit. All three members of this size failed by flexural buckling. But it is of interest to note that all three specimens of this size failed by buckling about both minor and major axes (Figs. 4.10a and 4.10b). No appreciable twisting has been observed. The reason for this could be the fact that flexural and equivalent torsional-flexural radii of gyration for these members do not differ greatly. The elastic-plastic flexural buckling capacities of these members about minor and major axes computed using finite element analysis are very close to each other. Another reason could be that after buckling, the member alignment changes and additional axial compression applied can easily result in bending about the major axis. To avoid any possible twisting and consequent failure in torsion, the bottom assembly for S3-1/4-2 and S3-1/4-3 was provided with additional restraint against twisting (as in the case of S4-1/4-3). The arrangement seems to have slightly increased the failure load. When specimen S3-1/4-1 was tested without any additional arrangement for bottom restraint, the failure load came out to be less than the corresponding loads of the other two specimens of the same category.

Size 3.5x3.5x5/16 in. specimens have (w/t) ratio further below the specified limit when compared to size 3x3x1/4 in. specimens. All three specimens of this size have failed by flexural buckling about minor axis (Figs. 4.11 and 4.12). No appreciable twisting or deflection about the major axis has been recorded. The member load increments were reduced to about 1/50 of the expected load in the final quarter of loading. It was observed that the failure is slow and steady. Once the member reached its ultimate capacity, at constant load the deflections of the member at mid-height have increased slowly and the members took almost 10 seconds to fail completely by flexural buckling.

Size 3x3x3/8 in. specimens have (w/t) ratio below the specified limit. All specimens of this size have failed by flexural buckling about minor axis and no appreciable twisting or deflection about major axis have been recorded (Fig. 4.13). The final mid-height deflection was less than half of what could be expected from the corresponding deflections of other sizes. After buckling, the test specimens of this size sustained loads that are considerably higher than the corresponding loads for other sizes. This may be due to the fact that members of this size have very high yield strength (475 MPa) and lower (w/t) ratios.

Table 5.3 lists the failure loads for all the specimens along with their slenderness ratios.

5.4.2 Loading and End-Plate Assembly

Loading of the members has been carried out via a flat jack which was operated by a hand pump. Although the SSRC guidelines for column testing recommend a constant rate of loading by a mechanical pump, a hand operated pump has been found to be satisfactory for the purpose of the present investigation. The hand pump not only gave good control over the load increments but also allowed easy recording of observations. The loads were monitored by a digital indicator and the reading was accurate to within 0.5% of failure load. The load cell was calibrated twice during the testing process and no change in the calibration curves was observed.

The end plate assembly described in Chapter 4 was found to be adequate for flexural buckling. The knife-edges did not pose any restraint to rotation of the plates about the minor or major axis. But, as already mentioned, the bottom plate assembly could not provide complete fixity against twisting of the member (more sophisticated experimental setups can be designed with several kinds of end fixtures. For example, the setup used by Wilhoite et al. [Wilhoite et al. 1984] uses Cardan's joints with an automated adjusting mechanism).

The loading frame has been found to be adequate for the range of loads experienced in the present investigation.

The movable blocks (Fig. 4.2) used to provide protection against accidental 'kicking-out' of the member ends have proved to be necessary in torsional-flexural buckling. All the members that failed in that mode have tried to twist the bottom plate assembly by transferring lateral forces through the screws used to hold the blocks firmly to the top of the top plate of bottom assembly. Specimen S4-1/4-3

has exerted sufficient lateral thrust so as to cause partial shearing of one such screw.

5.4.3 Alignment and Measurements

The member alignment has been achieved by attaching several electrical strain gauges to the surface of the member at different locations. The criterion for concentric loading has been taken as that alignment which produces strain gauge readings with least deviation. SSRC recommendations indicate that a total of 18 strain gauges can be placed on the surface of the angle (five each at top, bottom and mid-height). Attaching these strain gauges is a costly and tedious process. In order to see the effect of the number of strain gauges on the alignment of the angle, different combinations of strain gauge locations have been experimented with. Eight specimens have been experimented with with zero, 3, 5, 7, 9, and 11 strain gauges. The first two test specimens have been discarded because of poor alignment. It is observed that the minimum number of strain gauges required for alignment is five. The five strain gauges are placed at (Fig. 4.4),

1. heel of the top end
2. heel at mid-height
3. toe of one of the legs at mid-height
4. toe of the other leg at mid-height
5. toe of one of the legs at bottom end.

These five strain gauges monitor eccentricities at the middle and indicate the differential eccentricities at both the ends. However alignment with the use of 9 strain gauges (3 at each section) is found to be easier and faster although the final result is not appreciably different from the result obtained from attaching five gauges.

The strain gauge readings were recorded at each load increment till the final phase of loading before buckling. The strains after buckling of the specimens for the mid-height gauges were observed to have readings several times their pre-buckling readings. The readings at the ends of the member also showed a good jump, although the end sections are not expected to have yielded. The load carried by the member after buckling was almost constant under increasing axial deflection. This may be due to the fact that with increase in axial deflection after buckling, the member ends rotate and the corresponding rotation of the end plates creates a 'follower' type axial load that rotates with the member ends.

Deflections at mid-height have been recorded with dial gauges. Two dial gauges have been used to measure mid-height deflection along the major axis. Two more dial gauges recorded deflection of the two legs at the toe. The average of the first two gauges was used as deflection along u-u axis. Average of the second set is used as v-v deflection. Difference of the second set of readings served to indicate the twist of the member at mid-height. None of the members has shown appreciable deflection or rotation before buckling.

Upon unloading, at least half of the deflection along the major axis has recovered for the members that failed in flexural buckling. No appreciable recovery was observed for torsional-flexural buckling.

Stub-column tests as described in Ch.4 were carried out for test specimens. However, due to the limitation of the capacity of Universal Testing Machine, only one section size (nominal 3x3x1/4 in.) could be fully tested to failure (Fig. 4.16). The results indicate that the magnitude of maximum residual stress on the section is almost 50% of the yield stress. However, no conclusions can be drawn from this single test.

5.4.4 Comparison of Experimental and Finite Element Loads

Table 5.4 lists the member failure loads obtained from experimental investigation and finite element analysis. Except for specimens S4-1/4-3, S3-1/4-2 and S3-1/4-3, all the specimens have FEM results within 5 to 10% of the experimental loads. For those three specimens, it may be noted that the bottom plate assembly has been slightly modified to prevent twisting of the assembly. This arrangement, as already pointed out, has resulted in increased experimental loads. The finite element analysis predicts loads within 5% of the theoretical failure loads for elastic buckling. Assuming that the margin of error due to finite element analysis in inelastic buckling is the same as in the case of elastic buckling, the computed loads are very close to the experimental loads. In almost all cases, the predicted loads are slightly less than or just above the experimental loads. From the results obtained, it appears that the finite element analysis with all the underlying assumptions, did give reasonably good results when compared with the experimentally obtained failure loads.

5.5 Comparison of Experimental Loads with Specifications

5.5.1 General

This section focuses on the loads calculated as per various standard specifications and recommendations and their comparison with the experimentally obtained values. As mentioned in Chapter 1, the column capacity is influenced by the w/t ratio. For sections with w/t ratio more than a specified maximum, the applicable critical stress is derated by a reduction factor. For 60° schifflerized angles, the value of w can be variously taken as (b) , $(a+b-t-c)$, $(a+b-t)$ or $(a+b)$

[refer Fig. 1.3]. All these different values of w are used in the present discussion to predict member capacity as per different standard specifications. Some of the specifications refer to a resistance factor ϕ . The computed resistances are to be derated using this factor. But in the case of present discussion, the value should be taken as 1.0 because of the usage of actual test specimens. Therefore, all the column capacities are computed using the actual properties, yield stresses and a resistance factor of 1.0. However, in the design office practice, it is very rare that individual members are tested to find their resistance. In any typical design situation, the nominal values are used to find member capacities. In view of this, all the computations are repeated using nominal properties (dimensions and yield stress) and applicable resistance factors. All computations are performed using the computer program given in Appendix C.

Specimens of nominal size $5 \times 5 \times 5/16$ in. and $4 \times 4 \times 1/4$ in. have their w/t ratios above the specified limits for all the different possible values of w . These specimens have different load capacities for each value of w . Specimens of nominal size $3.5 \times 3.5 \times 5/16$ in. and $3 \times 3 \times 1/4$ in. have their w/t ratios bordering on the specified limits. For these specimens, the column capacity will be affected by w/t ratios for some values of flat with w .

Specimens of nominal size $3 \times 3 \times 3/8$ in. have their w/t ratios below the specified limit. The column capacity for these specimens will not be affected by w/t ratios.

Tables 5.5a to 5.9b list the calculated values and their ratios with experimental values. In all computations, the experimental loads have been taken as the base for comparison.

5.5.2 CAN/CSA-S37-M86

The Canadian Standard S37 refers to CAN3-S16.1 [Steel Structures for Buildings (Limit States Design)] for factored axial compression resistance formulae. These are adopted from the column design curve no.2 of the Structural Stability Research Council Proposals. The formulae are mainly derived for W shapes rolled in Canada and are applicable for other doubly symmetric hot-rolled sections. The members in the intermediate range of slenderness are treated as beam-columns with an initial out of straightness and residual stresses. These formulae are not based on test results obtained for singly symmetric sections such as angles. For such members, the standard advises the designer to check whether torsional-flexural buckling is critical. The standard, however does not give any guidelines for the procedures to be adopted for such checking. S16.1 limits the applicable w/t ratio to $200/\sqrt{F_y}$. The proposed amendment to S37 seeks to include the sections with w/t ratio greater than this limit by introducing a reduction factor.

The column capacities are calculated using the formulae given in Clause 13.3.1 of S16.1 and the proposed amendment to S37 with a ϕ value of 1.0. The results are shown in Table 5.5a. The values calculated using flat width equal to the width of bent portion 'b' of the schifflerized angle are closest to the test results. However, the values are higher than the test results for specimens S5-5/16-1 to 3. The same trend is seen in the values computed using the nominal dimensions (Table 5.5b). These values are slightly less than the values calculated for actual dimensions. In this table, all predicted values (except S5-5/16-1) are smaller than the experimental values.

The corresponding values scaled down with a resistance factor of $\phi = 0.90$ are given in Tables 5.5c and 5.5d. All these values for both actual and nominal dimensions are less than the test results. It may be noted that for schifflerized angles which failed by flexural buckling, the load capacity predicted by the specification is conservative by 15% to 20%. Even though the formulae given in the specification are not intended for torsional-flexural buckling, these formulae predict column strengths which are close to the test results. From these results it appears that for schifflerized angles, the Canadian standard S37 with the proposed amendment to account for the sections with w/t ratios larger than the limiting value gives acceptably good results. The applicable leg width can be taken as the width of the bent portion of the schifflerized leg. It should be noted that, CAN3-S16.1-M84 underestimated the flexural buckling strength of schifflerized angles.

5.5.3 ASCE Manual No. 52 (1988)

The widely used "Guide for Design of Steel Transmission Towers" adopts the Structural Stability Research Council formula for ultimate strength of the centrally loaded columns in the inelastic range. For the elastic range, it depends on the Euler formula. The manual justifies the use of these formulae using experimental data. Steel Transmission towers are routinely subjected to full scale testing. The data gathered by ASCE from these tests concerns with members with L/r ratios up to 50. Eventhough the SSRC curves are developed primarily for members with somewhat higher L/r ratios, the manual accepts their use for towers because of their agreement with data from tower testing. The manual accounts for local buckling by derating the critical strength based on the value of w/t ratio.

The column strengths predicted by ASCE manual using actual dimensions are given in Table 5.6a. Corresponding values for nominal dimensions are listed in Table 5.6b. Although the manual specifies that the applicable flat width for w/t ratio is the width from the toe of the angle to the edge of fillet for a 90° angle, the capacities for schifflerized angles are calculated using all four alternative possible flat widths. The capacity calculated using a flat width equal to the bent portion of the schifflerized leg is almost always greater than the test result. The corresponding value calculated using nominal leg width is lower. The loads calculated using nominal properties are lower than the corresponding values for actual properties. For flexural buckling, the predicted values are higher by up to 9% when compared to the test results. This happens only in the case of the specimens with nominal size of $3 \times 3 \times 3/8$ in.. For this size, the slenderness ratios exceed slightly the limit set for the slender columns. For such cases, the member strength is calculated using elastic Euler buckling formula, whereas the actual member failed by inelastic buckling. This discrepancy can account for the slightly higher loads predicted by the ASCE formula.

From the above results, it can be seen that the ASCE manual predicts column capacities that are in good agreement with the test results for flexural buckling. For torsional-flexural failure of schifflerized angles, the manual predicts higher capacities. This can be greatly reduced or avoided by taking the applicable flat width as the nominal leg width instead of the width as defined in ASCE Manual No.52 for computing w/t ratios.

5.5.4 AISC-LRFD-1986

The AISC load and resistance factor design for concentrically loaded columns is based on a modified approach compared to the allowable stress design (ASD). The ASD is based on SSRC column curve no.2. This column curve is fitted with an exponential equation in the inelastic flexural buckling range. This equation predicts slightly lower values than the corresponding ASD formula. The elastic flexural buckling is represented by a modified Euler equation. Unlike CSA-S37 or ASCE manual, the AISC specifically accounts for torsional-flexural buckling. It uses the classical approach for determining the elastic torsional-flexural buckling capacity. The upper limit for elastic buckling is set at 50% of the yield stress. When the stress exceeds this value, the torsional buckling formulae are modified by the use of an equivalent slenderness factor. In both flexural and torsional-flexural buckling modes, the local plate failure is accounted for, by a modification factor which is a function of the w/t ratio. The limiting ratio however is slightly less than the corresponding limit set by ASCE or CSA.

Column capacities computed using various possible values of flat width for actual and nominal properties are listed in Tables 5.7a and 5.7b. The value of ϕ is taken as 1.0 for these tables. The corresponding loads for ϕ equal to 0.85 are shown in Tables 5.7c and 5.7d. All the values predicted in all these tables are less than the corresponding test results. The computed results have less scatter when compared to the values of either CSA or ASCE. The level of accuracy is consistent between members that failed in torsional-flexural and flexural failure modes. The nominal properties predicted loads that are slightly less than those for actual properties.

An examination of these values shows that the loads computed using a flat width equal to the bent portion of the schifflerized angle leg are closest yet less than the experimental failure loads. Therefore the width b (Fig. 1.3) can be used for all computations with AISC formulae.

5.5.5 BS 5950 : Part 1 : 1985

In the British practice, the critical stresses for different slenderness ratios and yield stresses are computed using the long-standing Perry-Robertson formulae. The yield stress is modified when the w/t ratio exceeds a limiting value. Loads computed using the provisions of the British practice are given in Table 5.8a and 5.8b for actual and nominal properties respectively. All the loads predicted are less than the corresponding test loads. The loads for nominal properties are slightly less than the corresponding loads for actual properties. The predicted loads have more scatter when compared with the predictions of AISC formulae. The values predicted for torsional-flexural buckling are closer to the failure loads than the values for flexural buckling. An examination of the values shows that the loads computed using a flat width equal to the bent portion of the schifflerized leg are closest to the experimental loads. Hence the width b (Fig. 1.3) can be taken as the applicable flat width for w/t ratio.

5.5.6 ECCS Recommendations

The European practice follows design strength procedures established from the data collected from several tower testing programs throughout Europe. The formulae are specifically designed for angles in transmission towers and are different from the corresponding formulae used in general steel construction. The

design buckling stresses are higher than the normal steel design practice because, these structures are tested to failure and in this sense are the best understood steel structures for the designers. The ECCS non-dimensional buckling curve is computed with an initial sinusoidal imperfection of 1/1000 of the length. It does not directly include the effect of torsional-flexural buckling. The plate buckling is considered by derating the applicable critical stress when w/t ratio exceeds a limiting value. The nominal leg width is used for computing w/t ratio. The limiting ratio however, is set at $260/\sqrt{F_y}$ instead of a value close to $200/\sqrt{F_y}$ as is the case with North American practice.

The column capacities calculated using various possible flat widths for both nominal and actual properties are listed in Tables 5.9a and 5.9b. It can be readily seen that the ECCS recommendations give excellent predictions for flexural buckling. The values are closest yet less than the experimental values when compared to the other standard specifications. The loads for torsional-flexural buckling failure however, are higher by up to 20% when compared to the experimental loads. The higher predictions of ECCS formulae for torsional mode can perhaps be explained by the higher limiting w/t ratio when compared to the North American practice. From these results, it can be seen that the applicable flat width is the nominal leg width of the schifflerized angle (" $a+b$ " of Fig. 1.3).

Chapter 6

CONCLUSIONS AND RECOMMENDATIONS

In the present investigation, the behaviour of schifflerized hot-rolled angles under concentric loading is studied. Special emphasis is placed on determining the applicable flat width to be used for computing the w/t ratio which is used to estimate the strength of axially loaded compression members.

6.1 Conclusions

Based on the results and observations of the present investigation, the following conclusions are arrived at:

1. The compression tests carried out on the schifflerized angles under concentric loads have yielded data for members failing in flexural and torsional-flexural buckling modes. The data obtained is found to be suitable for calibrating design procedures.
2. In general, column strengths computed using various standard specifications differ appreciably from each other.
 - a. The proposed amendment for CAN/CSA-S37-M86 predicts schifflerized angle strengths close to actual test results for torsional-flexural buckling. For flexural buckling, the provisions of CAN3-S16.1-M84 which are referenced by CAN/CSA-S37-M86 underestimate the schifflerized angle capacities.

- b. ASCE Manual No. 52 predicts flexural buckling loads that are very close to test results. But for torsional-flexural buckling, the manual overestimates the failure loads of schifflerized angles.
 - c. AISC-LRFD-1986 predicts loads that are in good agreement with test results for both flexural and torsional-flexural buckling modes. There is less scatter between predicted and experimental failure loads compared to other standards.
 - d. BS 5950 : Part 1 : 1985 predicts flexural and torsional-flexural buckling loads which are in reasonable agreement with the test data. In no case, does the standard overestimate the member capacity. The load estimates have greater scatter when compared to AISC predictions.
 - e. ECCS Recommendations predict column strengths in flexural buckling which are in excellent agreement with test results. However, for torsional-flexural buckling the recommendations overestimate the column strength.
3. The recommended flat width to be used in the computation of w/t ratio for various standard specifications is as follows :
- a. For CAN/CSA-S37-M86, w = width of the bent portion of the schifflerized angle (dimension b of Fig. 1.3).
 - b. For ASCE Manual No. 52 (1988), w = nominal leg width.
 - c. For AISC-LRFD-1986, w = width of the bent portion of the schifflerized angle (dimension b of Fig. 1.3).

- d. For BS 5950 : Part 1 : 1985, w = width of the bent portion of the schifflerized angle (dimension b of Fig. 1.3).
 - e. For ECCS Recommendations (1985), w = nominal leg width.
4. The finite element model designed for analyzing the schifflerized angles gives reasonably good estimation of the failure loads. The procedure can be used to predict failure loads of schifflerized angles when actual testing cannot be carried out.
 5. Using finite element analysis, it is estimated that the residual stresses reduce the strength of the the schifflerized angle by approximately 20%. Through the thickness variation of the residual stresses due to schifflerization process reduces the buckling load by approximately 2% to 4%.

6.2 Recommendations for Further Research

Based on the experience gained in the present investigation, it is recommended that the following issues may be considered for future research:

1. Keeping in view of the limited nature of the present experimental investigation, more tests can be conducted for different sizes of schifflerized angles.
2. 60° angles manufactured directly by hot-rolling can be studied to find the similarities and differences with schifflerized angles.
3. The residual stress patterns as used in the present study are based on the recommendations of ECCS. Although the results obtained using these recommendations seem to be in good agreement with the test results, it is

desirable to determine experimentally the residual stress distribution across the section and through the thickness of the legs.

4. The test setup used is found to be good for flexural buckling. However, a better design for end fixtures is desirable for members failing in torsional-flexural buckling mode.

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TABLES

Table 2.1 Non-dimensional Buckling Curve based on ECCS Recommendations

VALUES OF NON-DIMENSIONAL COLUMN CURVE
EQUATION $\bar{\lambda} = \lambda$

λ	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
1.0	1.0000	.9987	.9974	.9961	.9947	.9934	.9920	.9907	.9893	.9879
1.1	.9865	.9850	.9836	.9821	.9806	.9791	.9776	.9761	.9745	.9729
1.2	.9713	.9696	.9679	.9662	.9644	.9626	.9608	.9589	.9570	.9551
1.3	.9531	.9510	.9489	.9468	.9446	.9423	.9400	.9376	.9352	.9327
1.4	.9301	.9274	.9247	.9219	.9190	.9160	.9129	.9097	.9064	.9030
1.5	.8995	.8959	.8921	.8883	.8843	.8802	.8759	.8715	.8670	.8623
1.6	.8575	.8525	.8474	.8421	.8366	.8310	.8253	.8193	.8133	.8070
1.7	.8007	.7941	.7875	.7807	.7737	.7667	.7595	.7522	.7449	.7374
1.8	.7298	.7222	.7146	.7068	.6991	.6913	.6834	.6756	.6678	.6600
1.9	.6521	.6444	.6366	.6289	.6212	.6136	.6060	.5985	.5910	.5837
2.0	.5764	.5691	.5620	.5549	.5479	.5410	.5342	.5274	.5203	.5142
2.1	.5078	.5014	.4951	.4889	.4828	.4768	.4709	.4651	.4593	.4536
2.2	.4481	.4426	.4372	.4319	.4266	.4215	.4164	.4114	.4065	.4017
2.3	.3969	.3922	.3876	.3831	.3786	.3742	.3699	.3657	.3615	.3573
2.4	.3533	.3493	.3454	.3415	.3377	.3339	.3302	.3266	.3230	.3195
2.5	.3160	.3126	.3093	.3060	.3027	.2995	.2963	.2932	.2901	.2871
2.6	.2841	.2812	.2783	.2755	.2727	.2699	.2672	.2645	.2619	.2593
2.7	.2567	.2542	.2517	.2492	.2468	.2444	.2420	.2397	.2374	.2351
2.8	.2329	.2307	.2286	.2264	.2243	.2222	.2202	.2182	.2162	.2142
2.9	.2122	.2103	.2084	.2066	.2047	.2029	.2011	.1993	.1976	.1959
3.0	.1942	.1925	.1908	.1892	.1876	.1860	.1844	.1828	.1813	.1798
3.1	.1783	.1768	.1753	.1739	.1724	.1710	.1696	.1683	.1669	.1656
3.2	.1642	.1629	.1616	.1603	.1591	.1578	.1566	.1554	.1541	.1530
3.3	.1518	.1506	.1494	.1483	.1472	.1461	.1450	.1439	.1428	.1417
3.4	.1407	.1396	.1386	.1376	.1366	.1356	.1346	.1336	.1326	.1317
3.5	.1307	.1298	.1289	.1280	.1270	.1261	.1253	.1244	.1235	.1227
3.6	.1218	.1210	.1201	.1193	.1185	.1177	.1169	.1161	.1153	.1145
3.7	.1138	.1130	.1122	.1115	.1108	.1100	.1093	.1086	.1079	.1072
3.8	.1065	.1058	.1051	.1044	.1038	.1031	.1024	.1018	.1011	.1005

TABLE 5.1a
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 5x5x5/16 in.)

PROPERTY	NOMINAL	S5-5/16-1	S5-5/16-2	S5-5/16-3
Leg width (mm)	127.0	125.4	126.2	125.4
a (mm)	25.0	25.0	25.0	25.0
b (mm)	102.0	100.4	101.2	100.4
t (mm)	7.9	7.9	7.9	7.9
c (mm)	13.0	13.0	13.0	13.0
Area (mm ²)	1953.1	1907.5	1926.4	1907.4
u ₁ (mm)	50.2	49.6	49.9	49.5
I _{max} 10 ⁴ (mm ⁴)	3.022	2.886	2.948	2.886
I _{min} 10 ⁴ (mm ⁴)	1.799	1.712	1.752	1.712
I _p 10 ⁴ (mm ⁴)	9.746	9.282	9.494	9.280
J 10 ⁴ (mm ⁴)	4.102	3.918	3.985	3.918
C _g 10 ³ (mm ³)	0.517	0.482	0.496	0.482
R ₁ (mm)	39.3	38.9	39.1	38.9
R ₂ (mm)	30.4	30.0	30.2	30.0
R ₃ (mm)	21.3	21.3	21.3	21.3
R ₄ (mm)	19.7	19.7	19.7	19.7
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.1b
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 4x4x1/4 in.)

PROPERTY	NOMINAL	S4-1/4-1	S4-1/4-2	S4-1/4-3
Leg width (mm)	101.6	100.8	100.8	101.0
a (mm)	24.0	24.0	24.0	24.0
b (mm)	77.6	76.8	76.8	77.0
t (mm)	6.4	6.2	6.2	6.2
c (mm)	10.0	10.0	10.0	10.0
Area (mm ²)	1250.0	1217.3	1217.7	1222.1
u _z (mm)	39.7	39.3	39.3	39.4
I _{max} (10 ⁶ mm ⁴)	1.293	1.244	1.244	1.253
I _{min} (10 ⁶ mm ⁴)	0.727	0.697	0.697	0.702
I _{ps} (10 ⁶ mm ⁴)	3.986	3.824	3.825	3.854
J (10 ⁴ mm ⁴)	1.680	1.575	1.576	1.588
C _w (10 ⁷ mm ⁶)	0.136	0.125	0.125	0.127
R _u (mm)	32.2	32.0	32.0	32.0
R _v (mm)	24.1	23.9	23.9	24.0
R _q (mm)	21.3	21.0	21.0	21.0
R _o (mm)	19.9	19.7	19.8	19.8
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.1c
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 3.5x3.5x5/16 in.)

PROPERTY	NOMINAL	S3.5-5/16-1	S3.5-5/16-2	S3.5-5/16-3
Leg width (mm)	88.9	90.1	90.1	90.1
a (mm)	25.0	25.0	25.0	25.0
b (mm)	63.9	65.1	65.1	65.1
t (mm)	7.9	8.0	8.0	8.0
c (mm)	10.0	10.0	10.0	10.0
Area (mm ²)	1348.3	1369.6	1371.4	1373.8
u _c (mm)	33.8	34.4	34.4	34.4
I _{max} (10 ⁶ mm ⁴)	1.081	1.125	1.126	1.128
I _{min} (10 ⁶ mm ⁴)	0.577	0.603	0.604	0.605
I _{ps} (10 ⁶ mm ⁴)	3.202	3.344	3.348	3.354
J (10 ⁴ mm ⁴)	2.832	2.887	2.899	2.915
C _u (10 ⁶ mm ⁶)	0.170	0.178	0.179	0.180
R _u (mm)	28.3	28.7	28.7	28.7
R _v (mm)	20.7	21.0	21.0	21.0
R _q (mm)	30.8	30.4	30.5	30.5
R _e (mm)	22.6	22.5	22.7	22.7
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.1d
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 3x3x3/8 In. SET-A)

PROPERTY	NOMINAL	S3-3/8-1	S3-3/8-2	S3-3/8-3
Leg width (mm)	76.2	76.2	77.4	77.4
a (mm)	26.0	26.0	26.0	26.0
b (mm)	50.2	50.2	51.4	51.4
t (mm)	9.5	9.6	9.6	9.6
c (mm)	8.0	8.0	8.0	8.0
Area (mm ²)	1360.9	1368.2	1391.3	1391.1
u _c (mm)	29.1	29.1	29.6	29.6
I _{max} (10 ⁶ mm ⁴)	0.914	0.818	0.855	0.855
I _{min} (10 ⁶ mm ⁴)	0.405	0.407	0.428	0.428
I _{ps} (10 ⁶ mm ⁴)	2.291	2.301	2.418	2.419
J (10 ⁴ mm ⁴)	4.116	4.186	4.258	4.256
C _v (10 ⁹ mm ⁶)	0.175	0.178	0.187	0.187
R _u (mm)	24.5	24.5	24.8	24.8
R _v (mm)	17.2	17.2	17.5	17.5
R _q (mm)	43.9	44.1	43.4	43.4
R _e (mm)	22.6	22.6	22.8	22.8
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.1e
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 3x3x3/8 in.SET-B)

PROPERTY	NOMINAL	S3-3/8-4	S3-3/8-5	S3-3/8-6
Leg width (mm)	76.2	76.9	77.1	77.4
a (mm)	26.0	26.0	26.0	26.0
b (mm)	50.2	50.9	51.1	51.4
t (mm)	9.5	9.6	9.6	9.6
c (mm)	8.0	8.0	8.0	8.0
Area (mm ²)	1360.9	1381.6	1385.6	1391.1
u _c (mm)	28.1	28.3	28.4	28.6
I _{max} (10 ⁶ mm ⁴)	0.814	0.840	0.846	0.855
I _{min} (10 ⁶ mm ⁴)	0.405	0.419	0.423	0.428
I _{ps} (10 ⁶ mm ⁴)	2.291	2.369	2.389	2.418
J (10 ⁴ mm ⁴)	4.116	4.227	4.240	4.256
C _w (10 ⁶ mm ⁵)	0.175	0.183	0.185	0.187
R _u (mm)	24.5	24.7	24.7	24.8
R _v (mm)	17.2	17.4	17.5	17.5
R _q (mm)	43.9	43.7	43.6	43.4
R _o (mm)	22.6	22.8	22.8	22.8
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.1f
 PROPERTIES OF TEST SPECIMENS (NOMINAL SIZE : 3x3x1/4 in.)

PROPERTY	NOMINAL	S3-1/4-1	S3-1/4-2	S3-1/4-3
Leg width (mm)	76.2	77.0	77.0	76.7
a (mm)	24.0	24.0	24.0	24.0
b (mm)	52.2	53.0	53.0	52.7
t (mm)	6.4	6.2	6.2	6.2
r (mm)	8.0	8.0	8.0	8.0
Area (mm ²)	927.4	920.6	918.1	915.7
u _o (mm)	28.8	29.1	29.1	29.0
I _{max} 10 ⁶ (mm ⁴)	0.570	0.578	0.577	0.571
I _{min} 10 ⁶ (mm ⁴)	0.288	0.293	0.293	0.289
I _{yo} 10 ⁶ (mm ⁴)	1.627	1.653	1.649	1.631
J 10 ⁴ (mm ⁴)	1.247	1.191	1.181	1.182
C _y 10 ⁸ (mm ⁶)	0.055	0.054	0.054	0.053
R _x (mm)	24.8	25.1	25.1	25.0
R _y (mm)	17.6	17.9	17.9	17.8
R _z (mm)	28.6	27.8	27.7	27.9
R _o (mm)	20.4	20.2	20.2	20.2
Length (mm)	1654.2	1654.2	1654.2	1654.2

** For explanations refer Fig. 1.3 and Notation

TABLE 5.2
MECHANICAL PROPERTIES OF TENSILE COUPONS

Nominal Size (in.)		Yield Stress (MPa) (2% offset)	Ultimate Stress (MPa)

5x5x5/16	#1	333	490
5x5x5/16	#2	333	487
4x4x1/4	#1	356	527
4x4x1/4	#2	356	531
3.5x3.5x5/16	#1	369	530
3.5x3.5x5/16	#2	369	528
3x3x3/8	#1	480	620
3x3x3/8	#2	470	616
3x3x1/4	#1	363	542
3x3x1/4	#2	363	547

TABLE 5.3
FAILURE LOADS OF TEST SPECIMENS

SPECIMEN	SLENDERNESSE RATIO	COLUMN SLENDERNESSE PARAMETER	FAILURE LOAD (kN)	FAILURE STRESS (MPa)

S5-5/16-1	55	0.716	422	221
S5-5/16-2	55	0.711	446	232
S5-5/16-3	55	0.716	440	231
S4-1/4-1	69	0.929	278	228
S4-1/4-2	69	0.929	286	235
S4-1/4-3	69	0.927	311	254
S3.5-5/16-1	79	1.078	350	256
S3.5-5/16-2	79	1.078	366	267
S3.5-5/16-3	79	1.078	350	255
S3-3/8-1	96	1.488	287	210
S3-3/8-2	94	1.463	287	206
S3-3/8-3	94	1.463	288	207
S3-3/8-4	95	1.473	278	201
S3-3/8-5	95	1.469	287	207
S3-3/8-6	94	1.463	289	208
S3-1/4-1	93	1.257	187	203
S3-1/4-2	93	1.256	217	236
S3-1/4-3	93	1.262	208	227

TABLE 5.4
RESULTS OF FINITE ELEMENT ANALYSIS FOR TEST SPECIMENS

SPECIMEN	KL/r	COLUMN NON-DIMENSIONAL SLENDERNESS PARAMETER	EXPERIMENTAL LOAD (kN)	FINITE ELEMENT LOAD (kN)	RATIO OF F.E.M. AND EXPERIMENTAL LOADS
S5-5/16-1	55	0.716	422	451	1.06
S5-5/16-2	55	0.711	446	455	1.02
S5-5/16-3	55	0.716	440	451	1.03
S4-1/4-1	69	0.929	278	262	0.94
S4-1/4-2	69	0.929	286	262	0.93
S4-1/4-3	69	0.927	311	263	0.85
S3.5-5/16-1	79	1.078	350	336	0.96
S3.5-5/16-2	79	1.078	366	336	0.92
S3.5-5/16-3	79	1.078	350	337	0.96
S3-3/8-1	96	1.488	287	257	0.90
S3-3/8-2	94	1.463	287	261	0.91
S3-3/8-3	94	1.463	288	261	0.91
S3-3/8-4	95	1.473	278	260	0.94
S3-3/8-5	95	1.469	287	260	0.91
S3-3/8-6	94	1.463	289	261	0.90
S3-1/4-1	93	1.257	187	175	0.94
S3-1/4-2	93	1.256	217	175	0.81
S3-1/4-3	93	1.262	208	174	0.94

TABLE 5.5a
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO CAN/CSA-S37-M86
Strength based on actual dimensions, $\phi = 1.0$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO

S5-5/16-1	422.	449.	1.06	435.	1.03	393.	0.93	366.	0.87
S5-5/16-2	446.	453.	1.02	440.	0.99	397.	0.89	369.	0.83
S5-5/16-3	440.	449.	1.02	435.	0.99	393.	0.89	366.	0.83
S4-1/4-1	278.	265.	0.95	250.	0.90	227.	0.82	212.	0.76
S4-1/4-2	286.	265.	0.93	250.	0.87	228.	0.80	212.	0.74
S4-1/4-3	311.	267.	0.86	251.	0.81	229.	0.74	213.	0.69
S3.5-5/16-1	350.	280.	0.80	280.	0.80	280.	0.80	274.	0.78
S3.5-5/16-2	366.	280.	0.77	280.	0.77	280.	0.77	275.	0.75
S3.5-5/16-3	350.	281.	0.80	281.	0.80	281.	0.80	275.	0.79
S3-3/8-1	287.	231.	0.81	231.	0.81	231.	0.81	231.	0.81
S3-3/8-2	287.	241.	0.84	241.	0.84	241.	0.84	241.	0.84
S3-3/8-3	286.	241.	0.84	241.	0.84	241.	0.94	241.	0.84
S3-3/8-4	278.	237.	0.85	237.	0.85	237.	0.85	237.	0.85
S3-3/8-5	287.	238.	0.83	238.	0.83	238.	0.93	238.	0.83
S3-3/8-6	289.	241.	0.83	241.	0.83	241.	0.93	241.	0.83
S3-1/4-1	187.	150.	0.80	150.	0.80	148.	0.79	144.	0.77
S3-1/4-2	217.	150.	0.69	150.	0.69	147.	0.68	144.	0.66
S3-1/4-3	208.	149.	0.72	149.	0.72	146.	0.70	143.	0.69

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation; RATIO='Load P as per spec.'/'P Test'

TABLE 5.5b
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO CAN/CSA-S37-M96
Strength based on nominal dimensions, $\phi = 1.0$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	439.	1.04	429.	1.01	390.	0.92	366.	0.87
S5-5/16-2	446.	439.	0.99	428.	0.96	390.	0.87	366.	0.82
S5-5/16-3	440.	439.	1.00	428.	0.97	390.	0.89	366.	0.83
S4-1/4-1	278.	258.	0.93	244.	0.88	226.	0.81	214.	0.77
S4-1/4-2	286.	258.	0.90	244.	0.85	226.	0.79	214.	0.75
S4-1/4-3	311.	258.	0.83	244.	0.79	226.	0.73	214.	0.69
S3.5-5/16-1	350.	251.	0.72	251.	0.72	251.	0.72	251.	0.72
S3.5-5/16-2	366.	251.	0.69	251.	0.69	251.	0.69	251.	0.69
S3.5-5/16-3	350.	251.	0.72	251.	0.72	251.	0.72	251.	0.72
S3-3/8-1	287.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-3/8-2	287.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-3/8-3	288.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-3/8-4	278.	219.	0.79	219.	0.79	219.	0.79	219.	0.79
S3-3/8-5	287.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-3/8-6	289.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-1/4-1	187.	140.	0.75	140.	0.75	140.	0.75	139.	0.74
S3-1/4-2	217.	140.	0.65	140.	0.65	140.	0.65	139.	0.64
S3-1/4-3	208.	140.	0.67	140.	0.67	140.	0.67	139.	0.67

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.5c
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO CAN/CSA-S37-M86
Strength based on actual dimensions, $\Phi = 0.9$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	404.	0.96	392.	0.93	354.	0.84	330.	0.79
S5-5/16-2	446.	408.	0.91	396.	0.89	357.	0.80	332.	0.75
S5-5/16-3	440.	404.	0.92	392.	0.89	354.	0.80	330.	0.75
S4-1/4-1	278.	239.	0.86	225.	0.81	205.	0.74	191.	0.69
S4-1/4-2	286.	239.	0.83	225.	0.79	205.	0.72	191.	0.67
S4-1/4-3	311.	240.	0.77	226.	0.73	206.	0.66	192.	0.62
S3.5-5/16-1	350.	252.	0.72	252.	0.72	252.	0.72	247.	0.71
S3.5-5/16-2	366.	252.	0.69	252.	0.69	252.	0.69	247.	0.68
S3.5-5/16-3	350.	253.	0.72	253.	0.72	253.	0.72	248.	0.71
S3-3/8-1	287.	208.	0.72	208.	0.72	208.	0.72	208.	0.72
S3-3/8-2	287.	217.	0.76	217.	0.76	217.	0.76	217.	0.76
S3-3/8-3	288.	217.	0.75	217.	0.75	217.	0.75	217.	0.75
S3-3/8-4	278.	213.	0.77	213.	0.77	213.	0.77	213.	0.77
S3-3/8-5	287.	215.	0.75	215.	0.75	215.	0.75	215.	0.75
S3-3/8-6	289.	217.	0.75	217.	0.75	217.	0.75	217.	0.75
S3-1/4-1	187.	135.	0.72	135.	0.72	133.	0.71	130.	0.70
S3-1/4-2	217.	135.	0.62	135.	0.62	133.	0.61	130.	0.60
S3-1/4-3	208.	134.	0.64	134.	0.64	132.	0.63	129.	0.62

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation; RATIO = 'Load P as per spec.' / 'P Test'

TABLE 5.5d
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO CAN/CSA-S37-M86
Strength based on nominal dimensions, $\phi=0.9$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	395.	0.94	385.	0.91	351.	0.83	329.	0.78
S5-5/16-2	446.	395.	0.89	385.	0.86	351.	0.79	329.	0.74
S5-5/16-3	440.	395.	0.90	385.	0.88	351.	0.80	329.	0.75
S4-1/4-1	278.	232.	0.83	220.	0.79	203.	0.73	192.	0.69
S4-1/4-2	286.	232.	0.81	220.	0.77	203.	0.71	192.	0.67
S4-1/4-3	311.	232.	0.75	220.	0.71	203.	0.65	192.	0.62
S3.5-5/16-1	350.	226.	0.64	226.	0.64	226.	0.64	226.	0.64
S3.5-5/16-2	366.	226.	0.62	226.	0.62	226.	0.62	226.	0.62
S3.5-5/16-3	350.	226.	0.64	226.	0.64	226.	0.64	226.	0.64
S3-3/8-1	287.	197.	0.69	197.	0.69	197.	0.69	197.	0.69
S3-3/8-2	287.	197.	0.69	197.	0.69	197.	0.69	197.	0.69
S3-3/8-3	288.	197.	0.68	197.	0.68	197.	0.68	197.	0.68
S3-3/8-4	278.	197.	0.71	197.	0.71	197.	0.71	197.	0.71
S3-3/8-5	287.	197.	0.69	197.	0.69	197.	0.69	197.	0.69
S3-3/8-6	289.	197.	0.68	197.	0.68	197.	0.68	197.	0.68
S3-1/4-1	187.	126.	0.67	126.	0.67	126.	0.67	125.	0.67
S3-1/4-2	217.	126.	0.58	126.	0.58	126.	0.58	125.	0.58
S3-1/4-3	208.	126.	0.61	126.	0.61	126.	0.61	125.	0.60

** note : case (I):w=b; (II):w=a+b-t-c; (III):w=a+b-t; (IV):w=a+b
** See Fig.1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.6a
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO ASCE MANUAL 52-1988
Strength based on actual dimensions, $\phi = 1.00$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	511.	1.21	494.	1.17	440.	1.04	408.	0.97
S5-5/16-2	446.	515.	1.16	498.	1.12	444.	1.00	411.	0.92
S5-5/16-3	440.	511.	1.16	494.	1.12	440.	1.00	408.	0.93
S4-1/4-1	278.	315.	1.13	289.	1.04	256.	0.92	236.	0.85
S4-1/4-2	286.	315.	1.10	290.	1.01	256.	0.90	236.	0.82
S4-1/4-3	311.	317.	1.02	291.	0.94	258.	0.83	237.	0.76
S3.5-5/16-1	350.	359.	1.02	359.	1.02	359.	1.02	350.	1.00
S3.5-5/16-2	366.	359.	0.98	359.	0.98	359.	0.98	351.	0.96
S3.5-5/16-3	350.	360.	1.03	360.	1.03	360.	1.03	352.	1.01
S3-3/8-1	287.	293.	1.02	293.	1.02	293.	1.02	293.	1.02
S3-3/8-2	287.	309.	1.08	309.	1.08	309.	1.08	309.	1.08
S3-3/8-3	288.	309.	1.07	309.	1.07	309.	1.07	309.	1.07
S3-3/8-4	278.	302.	1.09	302.	1.09	302.	1.09	302.	1.09
S3-3/8-5	287.	305.	1.06	305.	1.06	305.	1.06	305.	1.06
S3-3/8-6	289.	309.	1.07	309.	1.07	309.	1.07	309.	1.07
S3-1/4-1	187.	202.	1.08	202.	1.08	198.	1.06	186.	0.99
S3-1/4-2	217.	202.	0.93	202.	0.93	197.	0.91	185.	0.85
S3-1/4-3	208.	200.	0.96	200.	0.96	196.	0.94	184.	0.88

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation: $RATIO = \text{'Load P as per spec.'} / \text{'P Test'}$

TABLE 5.6b
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO ASCE MANUAL 52-1988
Strength based on nominal dimensions, $\Phi=1.00$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	499.	1.18	484.	1.15	436.	1.03	407.	0.97
S5-5/16-2	446.	499.	1.12	484.	1.09	436.	0.98	407.	0.91
S5-5/16-3	440.	499.	1.13	484.	1.10	436.	0.99	407.	0.93
S4-1/4-1	278.	306.	1.10	286.	1.03	259.	0.93	241.	0.87
S4-1/4-2	286.	306.	1.07	286.	1.00	259.	0.90	241.	0.84
S4-1/4-3	311.	306.	0.99	286.	0.92	259.	0.83	241.	0.78
S3.5-5/16-1	350.	306.	0.87	306.	0.87	306.	0.87	306.	0.87
S3.5-5/16-2	366.	306.	0.84	306.	0.84	306.	0.84	306.	0.84
S3.5-5/16-3	350.	306.	0.87	306.	0.87	306.	0.87	306.	0.87
S3-3/8-1	287.	291.	1.01	291.	1.01	291.	1.01	291.	1.01
S3-3/8-2	287.	291.	1.01	291.	1.01	291.	1.01	291.	1.01
S3-3/8-3	288.	291.	1.01	291.	1.01	291.	1.01	291.	1.01
S3-3/8-4	278.	291.	1.05	291.	1.05	291.	1.05	291.	1.05
S3-3/8-5	287.	291.	1.01	291.	1.01	291.	1.01	291.	1.01
S3-3/8-6	289.	291.	1.01	291.	1.01	291.	1.01	291.	1.01
S3-1/4-1	187.	185.	0.99	185.	0.99	185.	0.99	185.	0.99
S3-1/4-2	217.	185.	0.85	185.	0.85	185.	0.85	185.	0.85
S3-1/4-3	208.	185.	0.89	185.	0.89	185.	0.89	185.	0.89

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$

** See Fig. 1.3 for notation; RATIO='Load P as per spec.'/'P Test'

TABLE 5.7a
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO AISC-LRFD-1986
Strength based on actual dimensions, $\phi=1.00$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO

S5-5/16-1	422.	374.	0.89	370.	0.88	359.	0.85	352.	0.83
S5-5/16-2	446.	377.	0.84	373.	0.84	362.	0.81	354.	0.79
S5-5/16-3	440.	374.	0.85	370.	0.84	359.	0.82	352.	0.80
S4-1/4-1	278.	235.	0.85	230.	0.83	224.	0.81	220.	0.79
S4-1/4-2	286.	235.	0.82	230.	0.81	224.	0.78	220.	0.77
S4-1/4-3	311.	236.	0.76	231.	0.74	225.	0.72	221.	0.71
S3.5-5/16-1	350.	311.	0.89	311.	0.89	311.	0.89	306.	0.87
S3.5-5/16-2	366.	311.	0.85	311.	0.85	311.	0.85	306.	0.84
S3.5-5/16-3	350.	312.	0.89	312.	0.89	312.	0.89	307.	0.88
S3-3/8-1	287.	257.	0.90	257.	0.90	257.	0.90	257.	0.90
S3-3/8-2	287.	270.	0.94	270.	0.94	270.	0.94	270.	0.94
S3-3/8-3	288.	270.	0.94	270.	0.94	270.	0.94	270.	0.94
S3-3/8-4	278.	265.	0.95	265.	0.95	265.	0.95	265.	0.95
S3-3/8-5	287.	267.	0.93	267.	0.93	267.	0.93	267.	0.93
S3-3/8-6	289.	270.	0.93	270.	0.93	270.	0.93	270.	0.93
S3-1/4-1	187.	173.	0.92	173.	0.92	171.	0.91	169.	0.90
S3-1/4-2	217.	172.	0.79	172.	0.79	170.	0.78	168.	0.78
S3-1/4-3	208.	171.	0.82	171.	0.82	169.	0.81	167.	0.80

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation; RATIO= 'Load P as per spec.' / 'P Test'

TABLE 5.7b
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO AISC-LRFD-1986
Strength based on nominal dimensions, $\phi = 1.00$

SPECIMEN	P	CASE	CASE	CASE	CASE	CASE	CASE	CASE	CASE
	TEST	I	I	II	II	III	III	IV	IV
	(kN)	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO
	(kN)	(kN)		(kN)		(kN)		(kN)	
S5-5/16-1	422.	366.	0.87	363.	0.86	352.	0.83	345.	0.82
S5-5/16-2	446.	366.	0.82	363.	0.81	352.	0.79	345.	0.77
S5-5/16-3	440.	366.	0.83	363.	0.82	352.	0.80	345.	0.78
S4-1/4-1	278.	228.	0.82	224.	0.81	218.	0.78	214.	0.77
S4-1/4-2	286.	228.	0.80	224.	0.78	218.	0.76	214.	0.75
S4-1/4-3	311.	228.	0.73	224.	0.72	218.	0.70	214.	0.69
S3.5-5/16-1	350.	269.	0.77	269.	0.77	269.	0.77	269.	0.77
S3.5-5/16-2	366.	269.	0.74	269.	0.74	269.	0.74	269.	0.74
S3.5-5/16-3	350.	269.	0.77	269.	0.77	269.	0.77	269.	0.77
S3-3/8-1	287.	249.	0.87	249.	0.87	249.	0.87	249.	0.87
S3-3/8-2	287.	249.	0.87	249.	0.87	249.	0.87	249.	0.87
S3-3/8-3	288.	249.	0.87	249.	0.87	249.	0.87	249.	0.87
S3-3/8-4	278.	249.	0.90	249.	0.90	249.	0.90	249.	0.90
S3-3/8-5	287.	249.	0.87	249.	0.87	249.	0.87	249.	0.87
S3-3/8-6	289.	249.	0.86	249.	0.86	249.	0.86	249.	0.86
S3-1/4-1	187.	159.	0.85	159.	0.85	159.	0.85	158.	0.84
S3-1/4-2	217.	159.	0.73	159.	0.73	159.	0.73	158.	0.73
S3-1/4-3	208.	159.	0.76	159.	0.76	159.	0.76	158.	0.76

** note : case (I):w=b; (II):w=a+b-t-c; (III):w=a+b-t; (IV):w=a+b
** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.7c
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO AISC-LRFD-1986
Strength based on actual dimensions, $\phi = 0.95$

SPECIMEN	P	CASE	CASE	CASE	CASE	CASE	CASE	CASE	CASE
	TEST	I	I	II	II	III	III	IV	IV
	(kN)	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO
	(kN)	(kN)		(kN)		(kN)		(kN)	
S5-5/16-1	422.	318.	0.75	315.	0.75	305.	0.72	299.	0.71
S5-5/16-2	446.	320.	0.72	317.	0.71	307.	0.69	301.	0.68
S5-5/16-3	440.	318.	0.72	315.	0.72	305.	0.69	299.	0.68
S4-1/4-1	278.	200.	0.72	196.	0.70	190.	0.68	187.	0.67
S4-1/4-2	286.	200.	0.70	196.	0.68	190.	0.67	187.	0.65
S4-1/4-3	311.	201.	0.64	197.	0.63	191.	0.61	187.	0.60
S3.5-5/16-1	350.	264.	0.75	264.	0.75	264.	0.75	260.	0.74
S3.5-5/16-2	366.	265.	0.72	265.	0.72	265.	0.72	260.	0.71
S3.5-5/16-3	350.	265.	0.76	265.	0.76	265.	0.76	261.	0.75
S3-3/8-1	287.	219.	0.76	219.	0.76	219.	0.76	219.	0.76
S3-3/8-2	287.	229.	0.80	229.	0.80	229.	0.80	229.	0.80
S3-3/8-3	288.	229.	0.80	229.	0.80	229.	0.80	229.	0.80
S3-3/8-4	278.	225.	0.81	225.	0.81	225.	0.81	225.	0.81
S3-3/8-5	287.	227.	0.79	227.	0.79	227.	0.79	227.	0.79
S3-3/8-6	289.	229.	0.79	229.	0.79	229.	0.79	229.	0.79
S3-1/4-1	187.	147.	0.78	147.	0.78	145.	0.78	143.	0.77
S3-1/4-2	217.	146.	0.67	146.	0.67	145.	0.67	143.	0.66
S3-1/4-3	208.	145.	0.70	145.	0.70	144.	0.69	142.	0.68

** note : case (I):w=b; (II):w=a+b-t-c; (III):w=a+b-t; (IV):w=a+b

** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.7d
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO AISC-LRFD-1986
Strength based on nominal dimensions, $\phi = 0.95$

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	311.	0.74	308.	0.73	299.	0.71	293.	0.69
S5-5/16-2	446.	311.	0.70	308.	0.69	299.	0.67	293.	0.66
S5-5/16-3	440.	311.	0.71	308.	0.70	299.	0.68	293.	0.67
S4-1/4-1	278.	194.	0.70	190.	0.68	185.	0.67	182.	0.65
S4-1/4-2	286.	194.	0.68	190.	0.67	185.	0.65	182.	0.64
S4-1/4-3	311.	194.	0.62	190.	0.61	185.	0.60	182.	0.58
S3.5-5/16-1	350.	229.	0.65	229.	0.65	229.	0.65	229.	0.65
S3.5-5/16-2	366.	229.	0.63	229.	0.63	229.	0.63	229.	0.63
S3.5-5/16-3	350.	229.	0.65	229.	0.65	229.	0.65	229.	0.65
S3-3/8-1	287.	212.	0.74	212.	0.74	212.	0.74	212.	0.74
S3-3/8-2	287.	212.	0.74	212.	0.74	212.	0.74	212.	0.74
S3-3/8-3	288.	212.	0.74	212.	0.74	212.	0.74	212.	0.74
S3-3/8-4	278.	212.	0.76	212.	0.76	212.	0.76	212.	0.76
S3-3/8-5	287.	212.	0.74	212.	0.74	212.	0.74	212.	0.74
S3-3/8-6	289.	212.	0.73	212.	0.73	212.	0.73	212.	0.73
S3-1/4-1	187.	135.	0.72	135.	0.72	135.	0.72	134.	0.72
S3-1/4-2	217.	135.	0.62	135.	0.62	135.	0.62	134.	0.62
S3-1/4-3	208.	135.	0.65	135.	0.65	135.	0.65	134.	0.65

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation; RATIO='Load P as per spec.'/'P Test'

TABLE 5.8a
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO BS 5950:PART 1:1995
Strength based on actual dimensions

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	385.	0.91	374.	0.89	361.	0.85	361.	0.85
S5-5/16-2	446.	389.	0.87	378.	0.85	364.	0.82	364.	0.82
S5-5/16-3	440.	385.	0.88	374.	0.85	360.	0.82	360.	0.82
S4-1/4-1	278.	237.	0.85	208.	0.75	202.	0.73	202.	0.73
S4-1/4-2	286.	237.	0.83	208.	0.73	202.	0.71	202.	0.71
S4-1/4-3	311.	238.	0.77	209.	0.67	203.	0.65	203.	0.65
S3.5-5/16-1	350.	274.	0.78	274.	0.78	257.	0.74	242.	0.69
S3.5-5/16-2	366.	274.	0.75	274.	0.75	258.	0.70	243.	0.66
S3.5-5/16-3	350.	275.	0.79	275.	0.79	258.	0.74	243.	0.69
S3-3/8-1	287.	223.	0.78	223.	0.78	223.	0.78	223.	0.78
S3-3/8-2	287.	227.	0.79	227.	0.79	227.	0.79	227.	0.79
S3-3/8-3	288.	227.	0.79	227.	0.79	227.	0.79	227.	0.79
S3-3/8-4	278.	225.	0.81	225.	0.81	225.	0.81	225.	0.81
S3-3/8-5	287.	226.	0.79	226.	0.79	226.	0.79	226.	0.79
S3-3/8-6	289.	227.	0.78	227.	0.78	227.	0.78	227.	0.78
S3-1/4-1	187.	147.	0.79	147.	0.79	134.	0.72	132.	0.70
S3-1/4-2	217.	147.	0.68	147.	0.68	134.	0.62	131.	0.61
S3-1/4-3	208.	147.	0.70	147.	0.70	134.	0.64	131.	0.63

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$
 ** See Fig. 1.3 for notation; RATIO='Load P as per spec.'/'P Test'

TABLE 5.8b
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO BS 5950:PART 1:1985
Strength based on nominal dimensions

SPECIMEN	P TEST (kN)	CASE I LOAD (kN)	CASE I RATIO	CASE II LOAD (kN)	CASE II RATIO	CASE III LOAD (kN)	CASE III RATIO	CASE IV LOAD (kN)	CASE IV RATIO
S5-5/16-1	422.	383.	0.91	369.	0.87	369.	0.87	369.	0.87
S5-5/16-2	446.	383.	0.86	369.	0.83	369.	0.83	369.	0.83
S5-5/16-3	440.	383.	0.87	369.	0.84	369.	0.84	369.	0.84
S4-1/4-1	278.	220.	0.79	207.	0.75	207.	0.75	207.	0.75
S4-1/4-2	286.	220.	0.77	207.	0.73	207.	0.73	207.	0.73
S4-1/4-3	311.	220.	0.71	207.	0.67	207.	0.67	207.	0.67
S3.5-5/16-1	350.	232.	0.66	232.	0.66	232.	0.66	232.	0.66
S3.5-5/16-2	366.	232.	0.63	232.	0.63	232.	0.63	232.	0.63
S3.5-5/16-3	350.	232.	0.66	232.	0.66	232.	0.66	232.	0.66
S3-3/8-1	287.	215.	0.75	215.	0.75	215.	0.75	215.	0.75
S3-3/8-2	287.	215.	0.75	215.	0.75	215.	0.75	215.	0.75
S3-3/8-3	288.	215.	0.75	215.	0.75	215.	0.75	215.	0.75
S3-3/8-4	278.	215.	0.77	215.	0.77	215.	0.77	215.	0.77
S3-3/8-5	287.	215.	0.75	215.	0.75	215.	0.75	215.	0.75
S3-3/8-6	289.	215.	0.74	215.	0.74	215.	0.74	215.	0.74
S3-1/4-1	187.	133.	0.71	133.	0.71	133.	0.71	125.	0.67
S3-1/4-2	217.	133.	0.61	133.	0.61	133.	0.61	125.	0.58
S3-1/4-3	208.	133.	0.64	133.	0.64	133.	0.64	125.	0.60

** note : case (I): $w=b$; (II): $w=a+b-t-c$; (III): $w=a+b-t$; (IV): $w=a+b$

** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.9a
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO ECCS - 1985
Strength based on actual dimensions

SPECIMEN	P TEST	CASE I	CASE I	CASE II	CASE II	CASE III	CASE III	CASE IV	CASE IV
	(kN)	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO
		(kN)		(kN)		(kN)		(kN)	
S5-5/16-1	422.	574.	1.36	574.	1.36	546.	1.29	505.	1.20
S5-5/16-2	446.	582.	1.30	582.	1.30	551.	1.24	510.	1.14
S5-5/16-3	440.	574.	1.30	574.	1.30	546.	1.24	505.	1.15
S4-1/4-1	278.	360.	1.30	360.	1.30	323.	1.16	297.	1.07
S4-1/4-2	286.	360.	1.26	360.	1.26	324.	1.13	298.	1.04
S4-1/4-3	311.	362.	1.16	362.	1.16	325.	1.04	299.	0.96
S3.5-5/16-1	350.	337.	0.96	337.	0.96	337.	0.96	337.	0.96
S3.5-5/16-2	366.	338.	0.92	338.	0.92	338.	0.92	338.	0.92
S3.5-5/16-3	350.	339.	0.97	339.	0.97	339.	0.97	339.	0.97
S3-3/8-1	287.	261.	0.91	261.	0.91	261.	0.91	261.	0.91
S3-3/8-2	287.	272.	0.95	272.	0.95	272.	0.95	272.	0.95
S3-3/8-3	288.	272.	0.94	272.	0.94	272.	0.94	272.	0.94
S3-3/8-4	278.	267.	0.96	267.	0.96	267.	0.96	267.	0.96
S3-3/8-5	287.	271.	0.94	271.	0.94	271.	0.94	271.	0.94
S3-3/8-6	289.	272.	0.94	272.	0.94	272.	0.94	272.	0.94
S3-1/4-1	187.	179.	0.95	179.	0.95	179.	0.95	179.	0.95
S3-1/4-2	217.	178.	0.82	178.	0.82	178.	0.82	178.	0.82
S3-1/4-3	208.	175.	0.84	175.	0.84	175.	0.84	175.	0.84

** note : case (I):wmb; (II):wma+b-t-c; (III):wma+b-t; (IV):wma+b
** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

TABLE 5.9b
COMPARISON OF EXPERIMENTAL FAILURE LOADS
AND LOADS CALCULATED ACCORDING TO ECCS - 1985
Strength based on nominal dimensions

SPECIMEN	P	CASE	CASE	CASE	CASE	CASE	CASE	CASE	CASE
	TEST	I	I	II	II	III	III	IV	IV
	(kN)	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO	LOAD	RATIO
S5-5/16-1	422.	537.	1.27	537.	1.27	537.	1.27	501.	1.19
S5-5/16-2	446.	537.	1.20	537.	1.20	537.	1.20	501.	1.12
S5-5/16-3	440.	537.	1.22	537.	1.22	537.	1.22	501.	1.14
S4-1/4-1	278.	318.	1.14	318.	1.14	318.	1.14	297.	1.07
S4-1/4-2	286.	318.	1.11	318.	1.11	318.	1.11	297.	1.04
S4-1/4-3	311.	318.	1.02	318.	1.02	318.	1.02	297.	0.95
S3.5-5/16-1	250.	298.	0.85	298.	0.85	298.	0.85	298.	0.85
S3.5-5/16-2	366.	298.	0.81	298.	0.81	298.	0.81	298.	0.81
S3.5-5/16-3	350.	298.	0.85	298.	0.85	298.	0.85	298.	0.85
S3-3/8-1	287.	253.	0.88	253.	0.88	253.	0.88	253.	0.88
S3-3/8-2	287.	253.	0.88	253.	0.88	253.	0.88	253.	0.88
S3-3/8-3	288.	253.	0.88	253.	0.88	253.	0.88	253.	0.88
S3-3/8-4	278.	253.	0.91	253.	0.91	253.	0.91	253.	0.91
S3-3/8-5	287.	253.	0.88	253.	0.88	253.	0.88	253.	0.88
S3-3/8-6	289.	253.	0.88	253.	0.88	253.	0.88	253.	0.88
S3-1/4-1	187.	169.	0.90	169.	0.90	169.	0.90	169.	0.90
S3-1/4-2	217.	169.	0.78	169.	0.78	169.	0.78	169.	0.78
S3-1/4-3	208.	169.	0.81	169.	0.81	169.	0.81	169.	0.81

** note : case (I):w=b; (II):w=a+b-t-c; (III):w=a+b-t; (IV):w=a+b
** See Fig. 1.3 for notation;RATIO='Load P as per spec.'/'P Test'

FIGURES

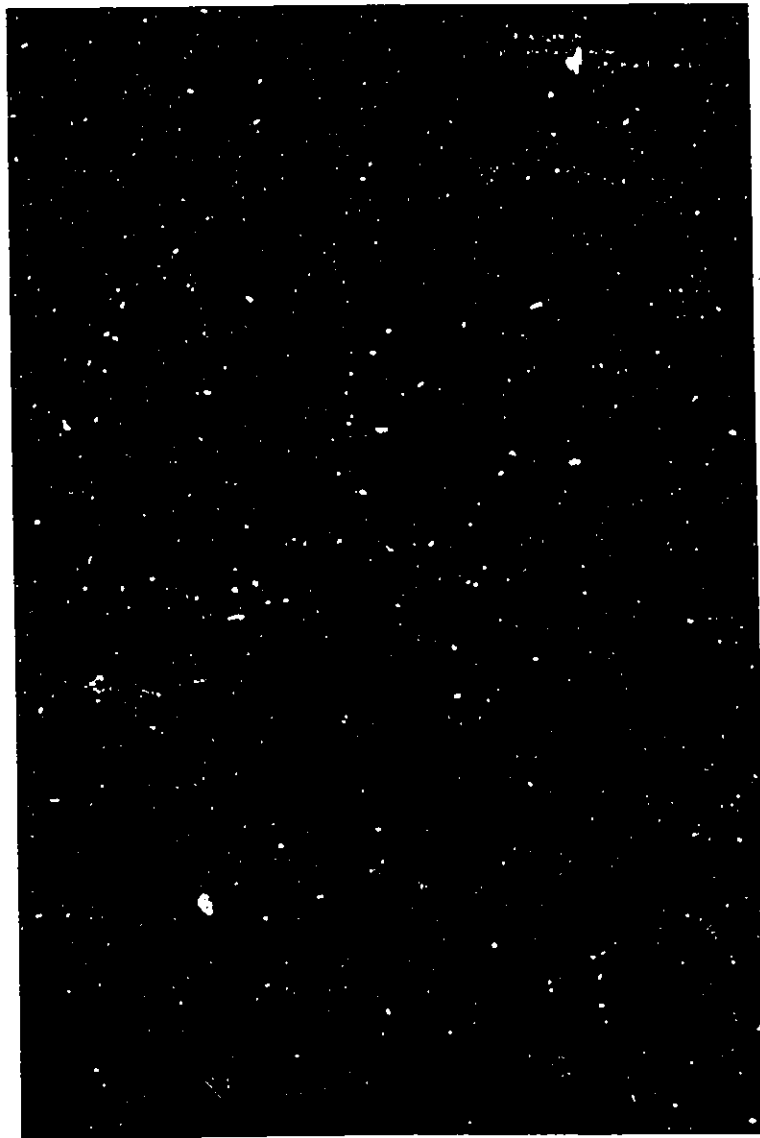


Fig.1.1
300m-high Guyed Television Mast
at Barrie, Ontario



Fig.1.2
Typical Self-supporting Antenna Tower

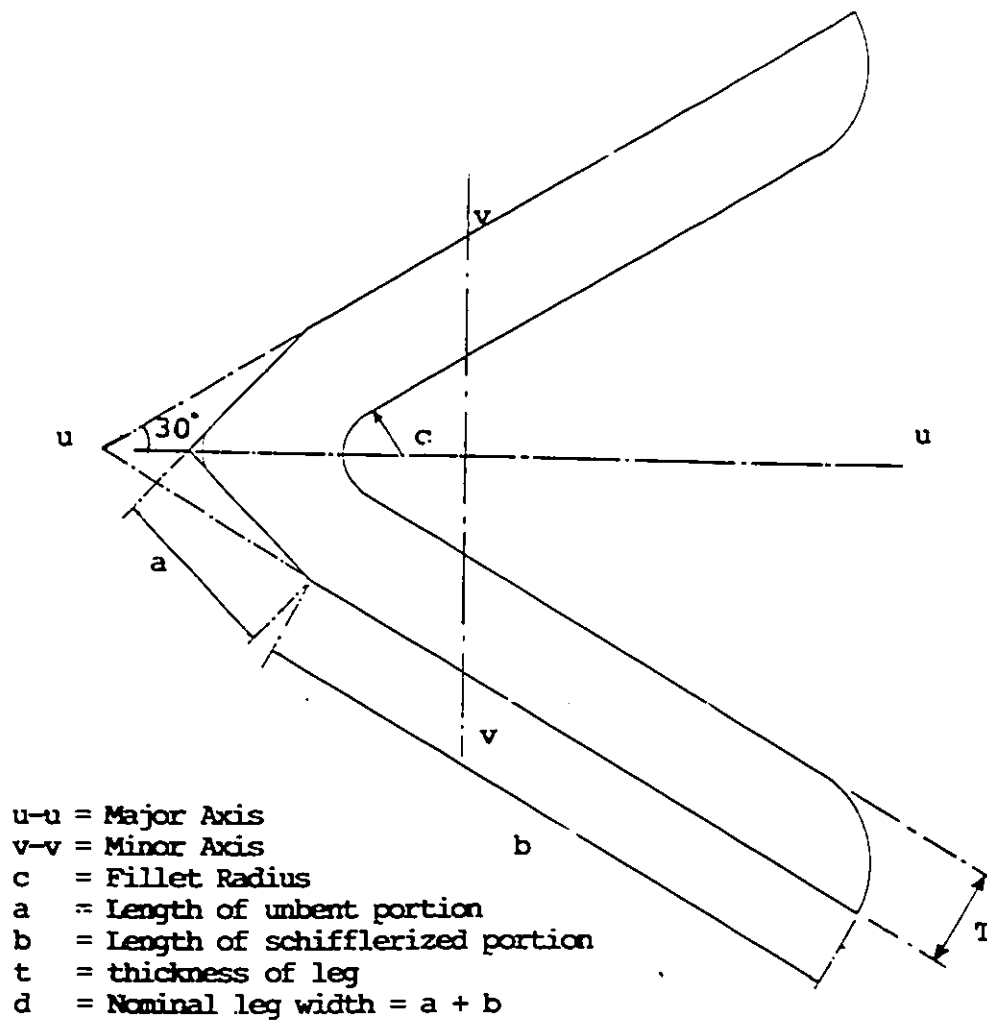


Fig.1.3
Typical Cross-section of a Schifflerized Angle

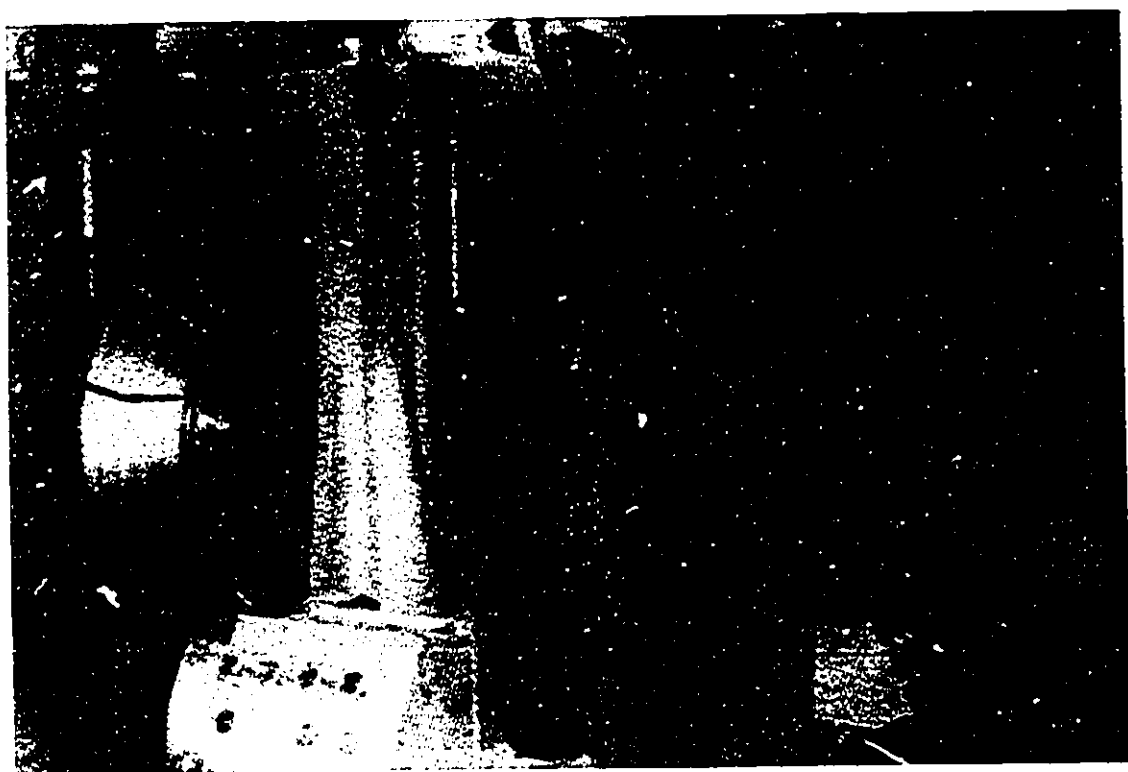


Fig.1.4
Rollers used for Schifflerization

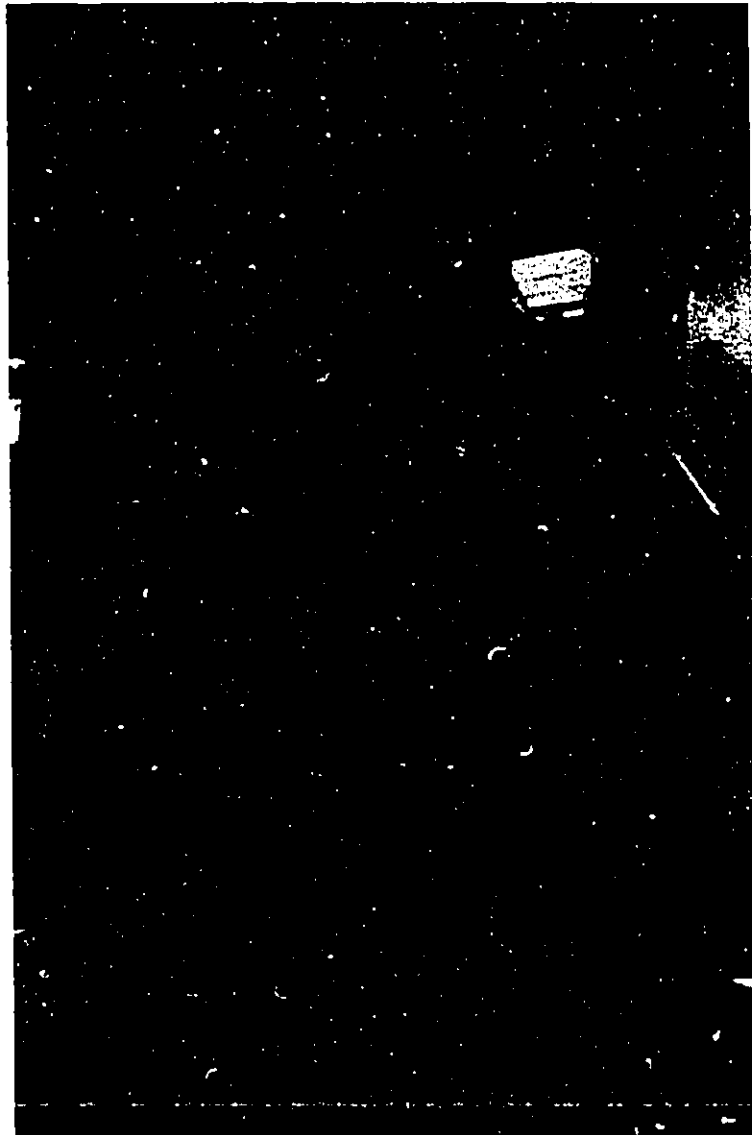


Fig.1.5
Brake-Press used for Schifflerizaton

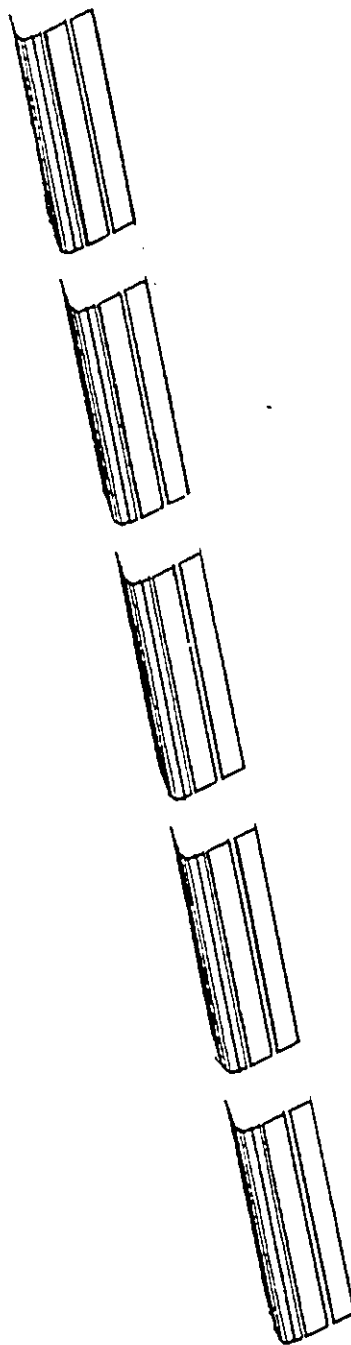


Fig.3.1
Finite Element Discretization of Schifflerized Angle
using Rectangular Eight-Node Shell Elements

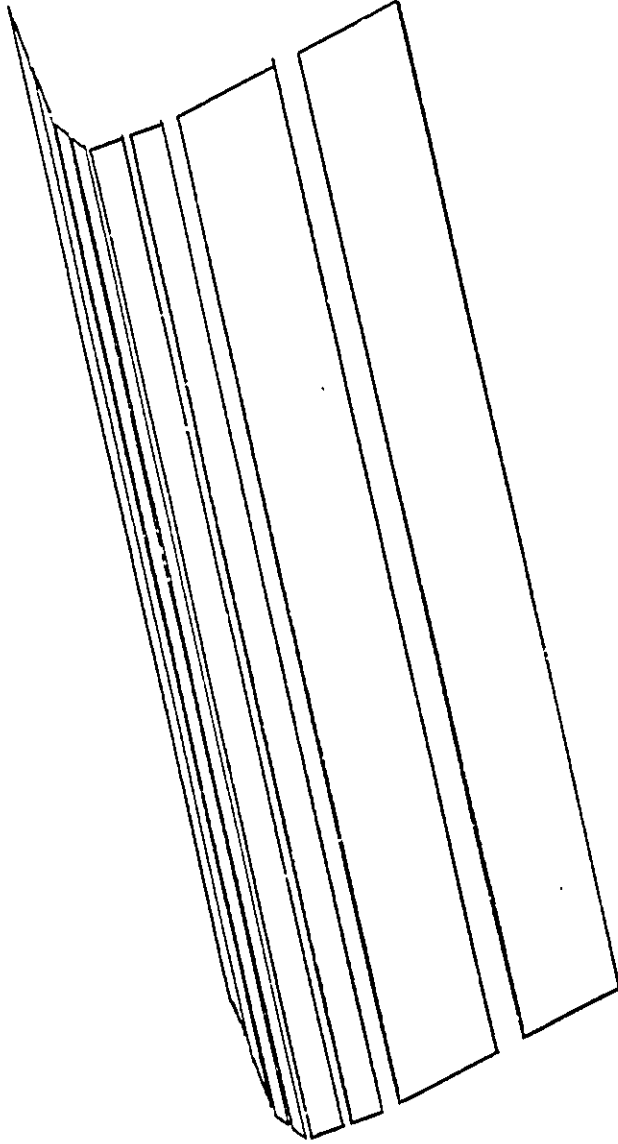


Fig.3.2
Enlarged View of a Single Segment of the Finite Element
Model for Schifflerized Angle

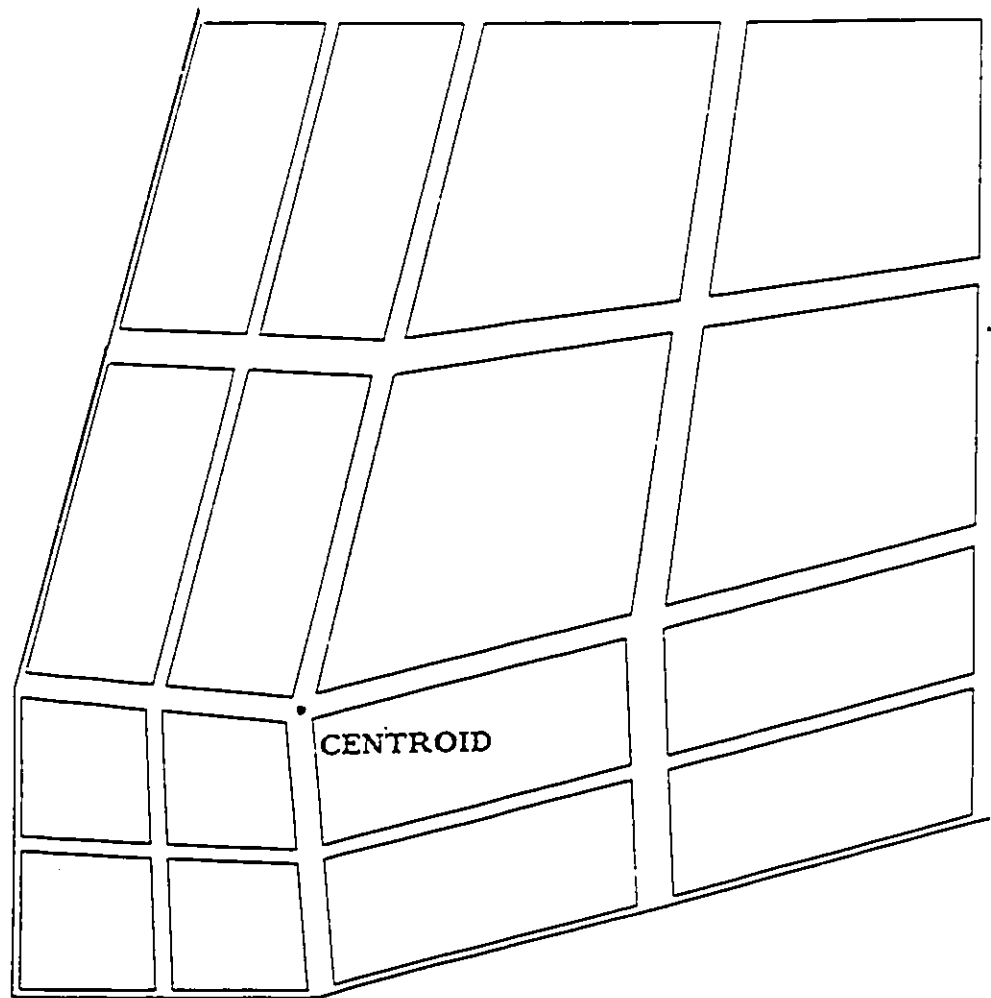


Fig.3.3
Finite Element Discretization of the End Plate
using Eight-Node Shell Elements

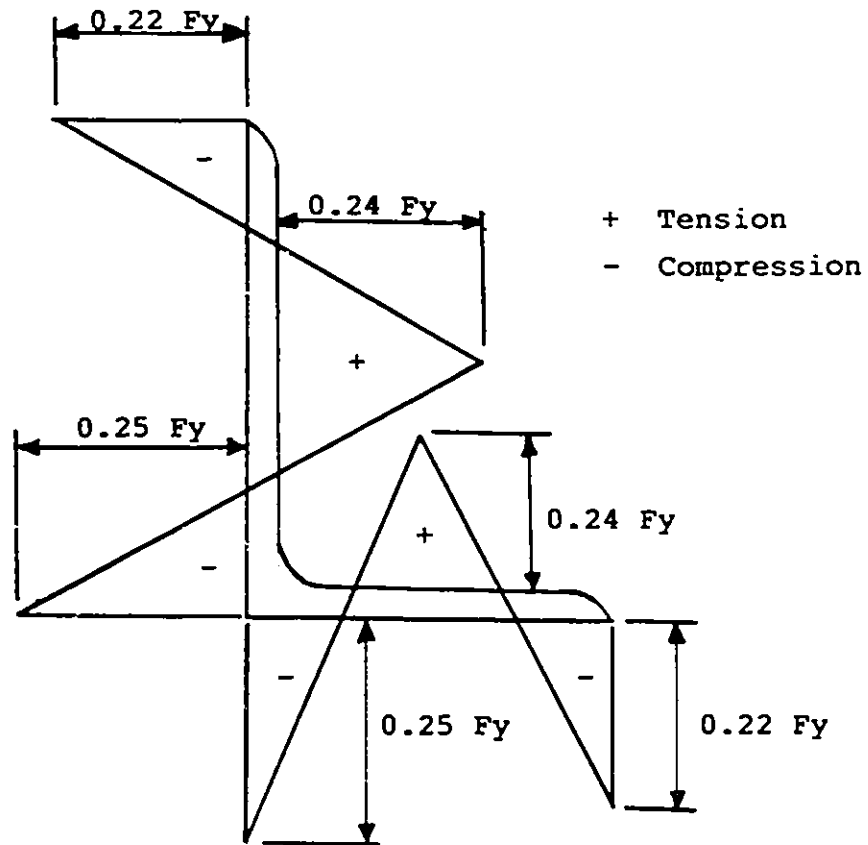


Fig.3.4
Residual Stress distribution over the
Cross-section of a Hot-Rolled Angle [ECCS]

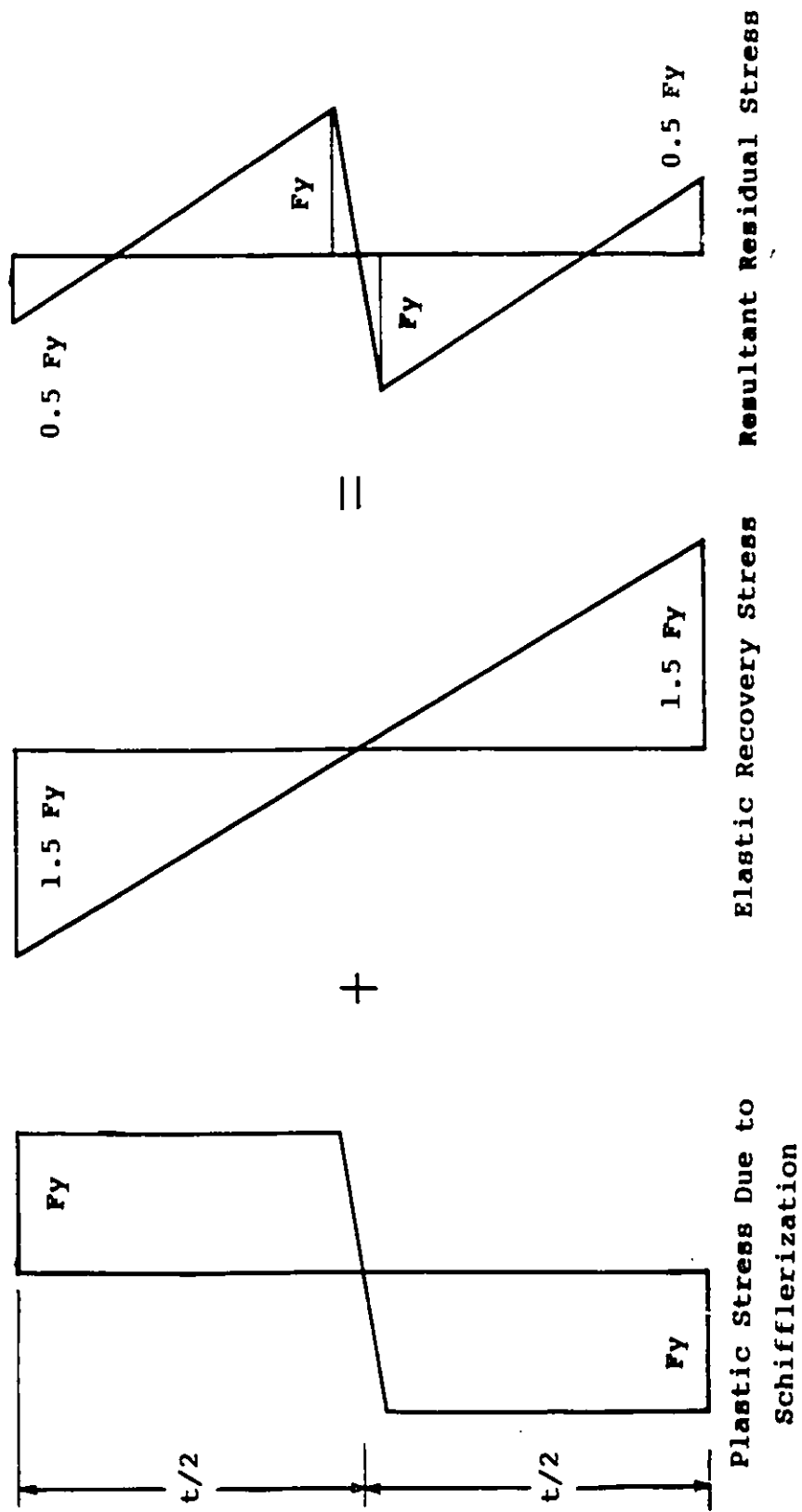


Fig.3.5
Residual Stress distribution through the
thickness of a Schifflerized Angle Leg

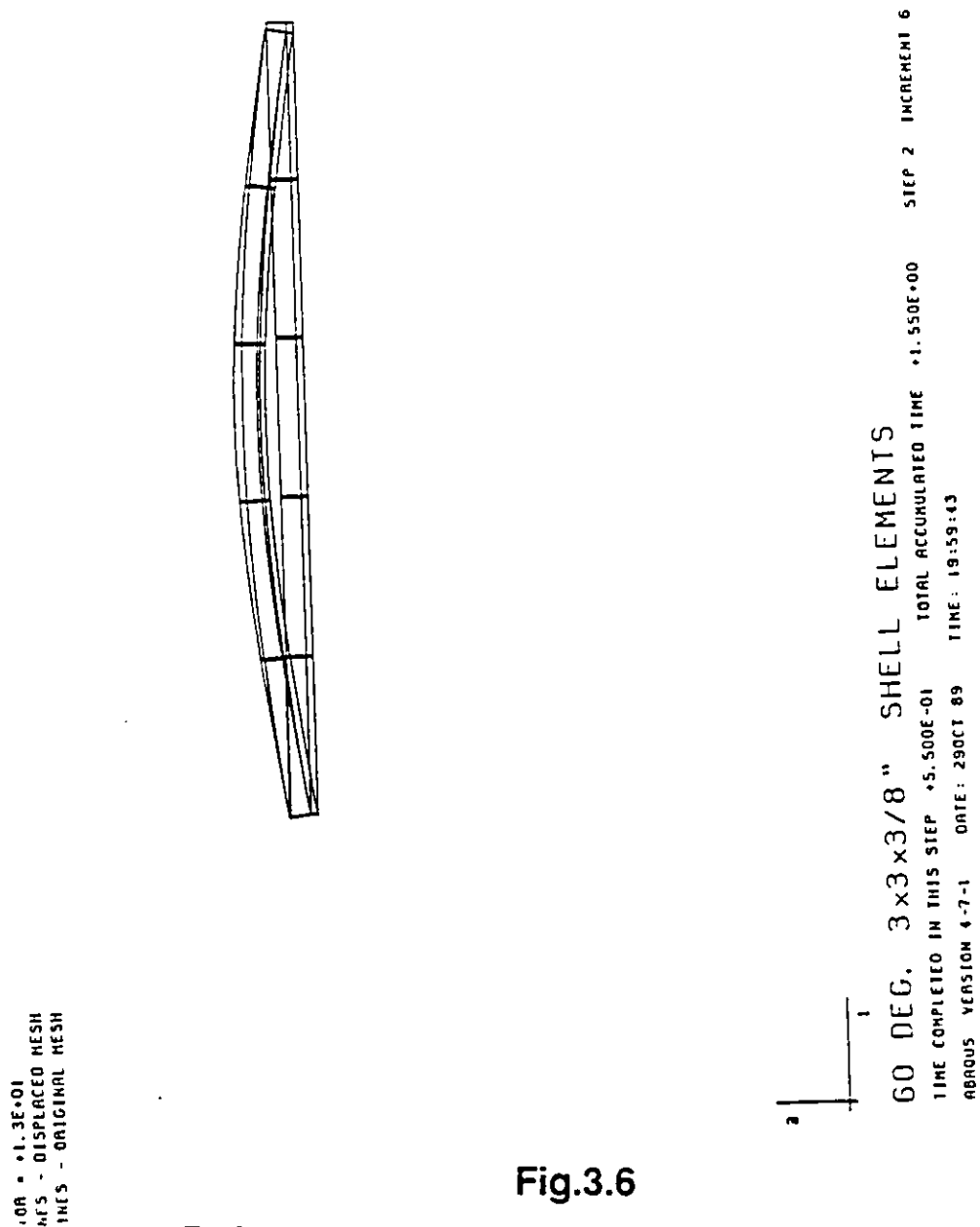
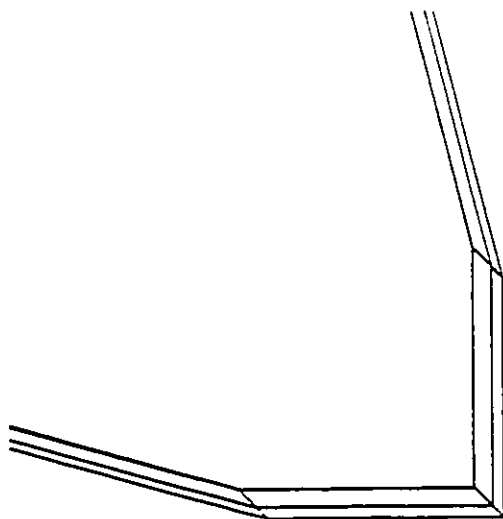
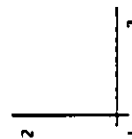


Fig.3.6
Deformed Shape in Flexural Buckling Mode



U
MAG. FACTOR = +7.1E-02
SOLID LINES - DISPLACED MESH
DASHED LINES - ORIGINAL MESH



TIME COMPLETED IN THIS STEP +2.541E-01 TOTAL ACCUMULATED TIME +1.354E+00 STEP 2 INCREMENT 9
ABAQUS VERS 4-7-1 DATE: 4SEP 89 TIME: 21:54:55

Fig.3.7
Deformed Shape in Flexural Buckling Mode
showing End View

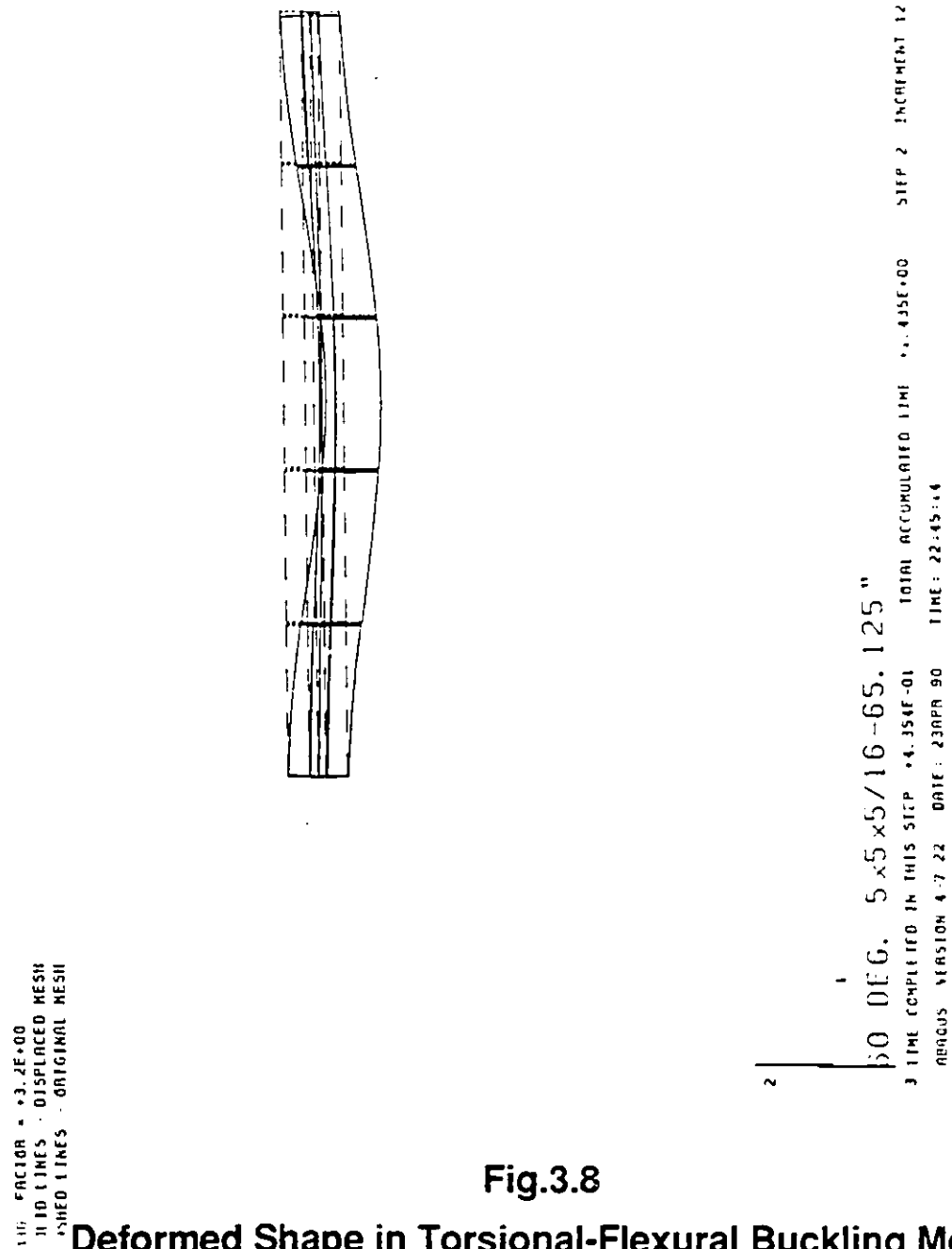


Fig.3.8

**Deformed Shape in Torsional-Flexural Buckling Mode
showing Major Axis Buckling**

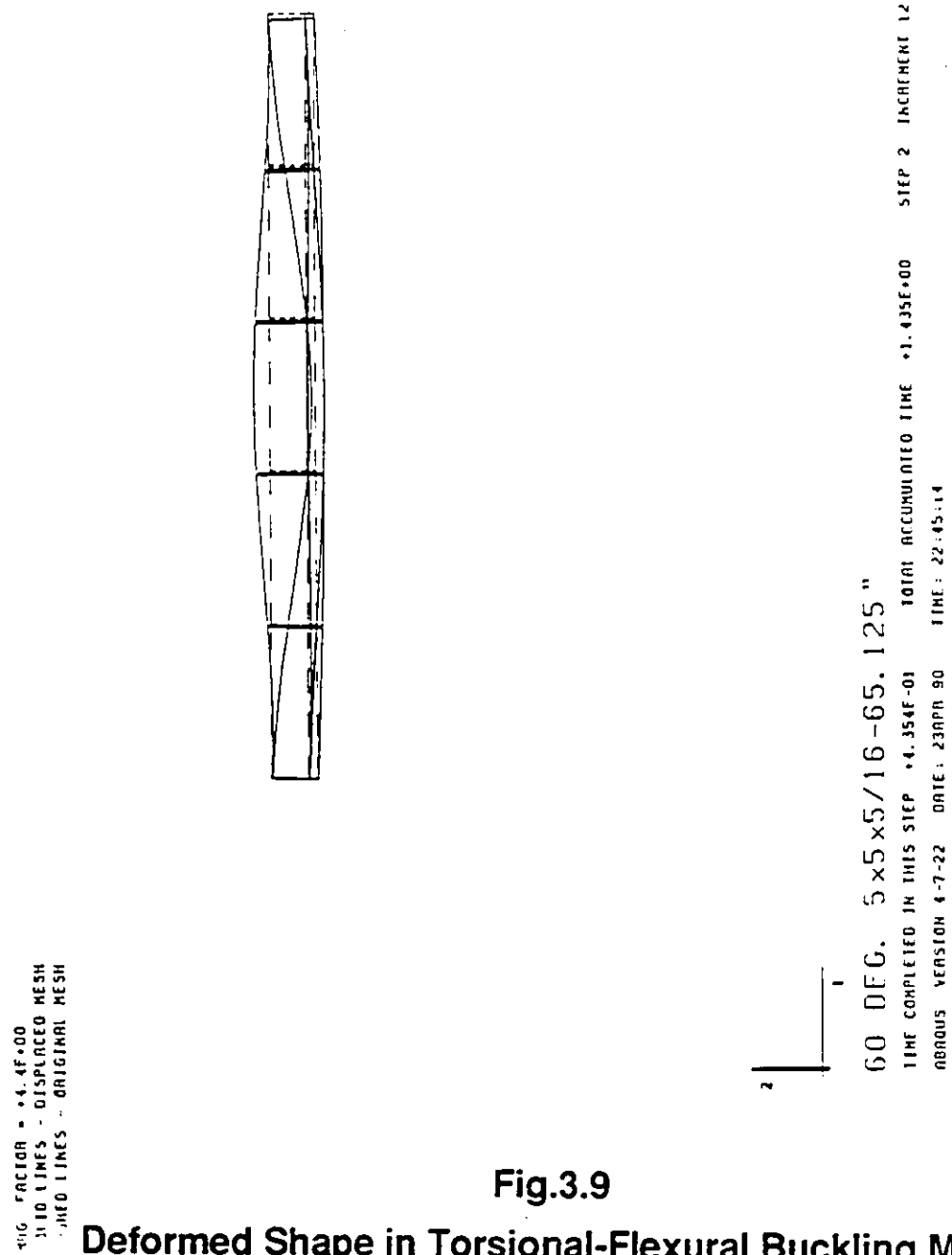


Fig.3.9
Deformed Shape in Torsional-Flexural Buckling Mode
showing Twist of the angle

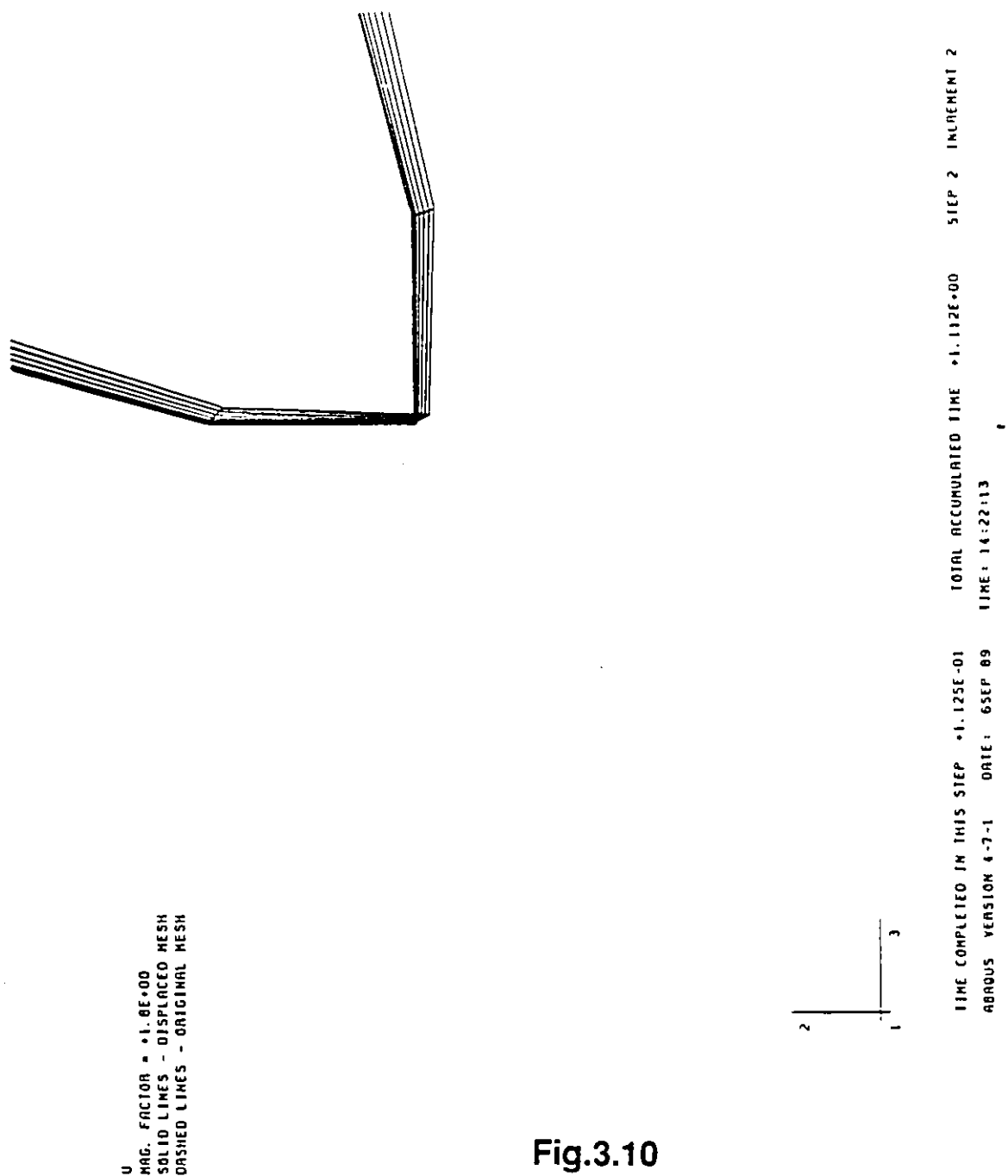
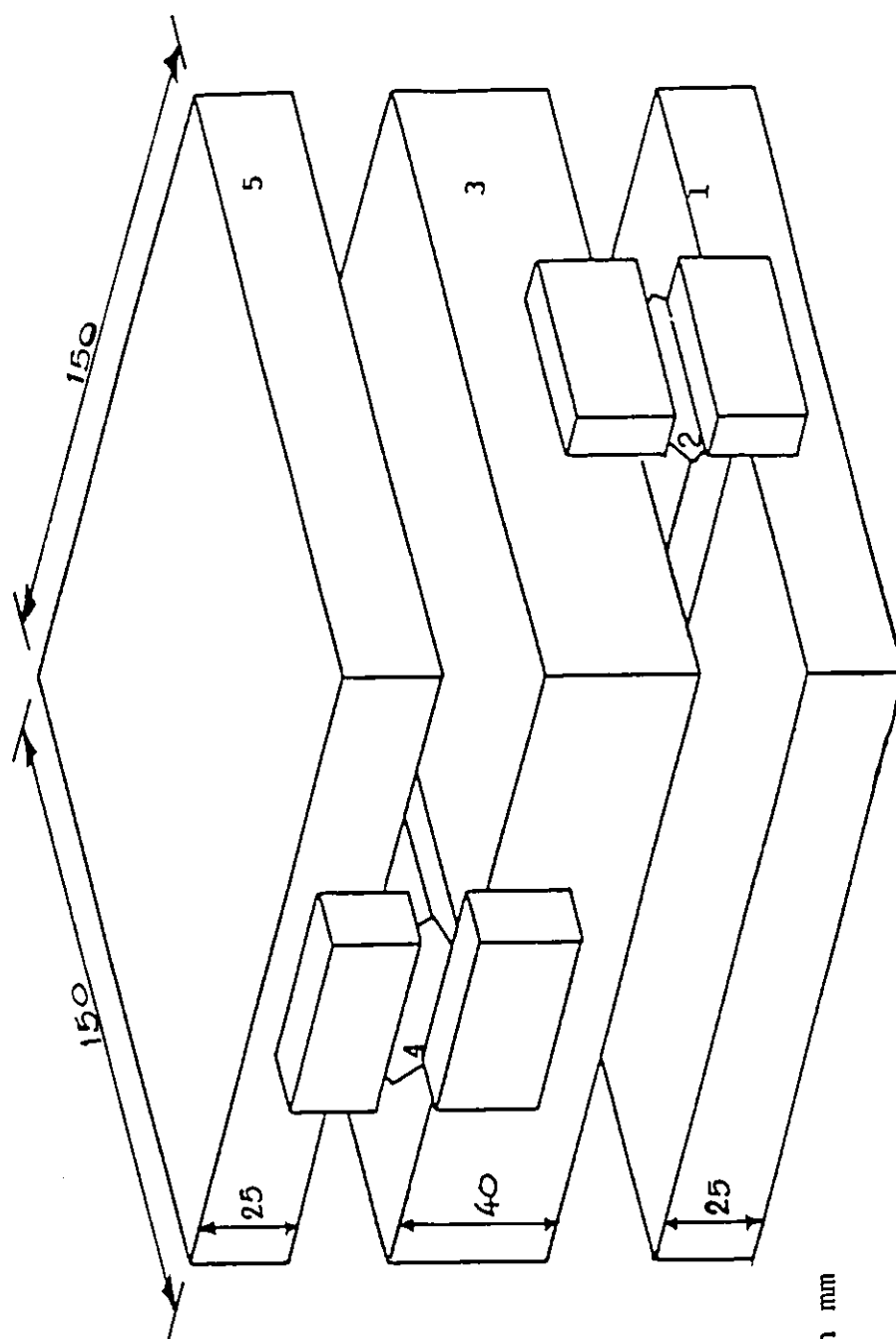


Fig.3.10
Deformed Shape in Torsional-Flexural Buckling Mode
showing End View



- 1 Bottom Plate
- 2 Bottom Knife Edge
- 3 Centre Plate
- 4 Top Knife Edge
- 5 Top Plate

* All dimensions in mm

Fig.4.1
End Plate Assembly for Hinged End Condition

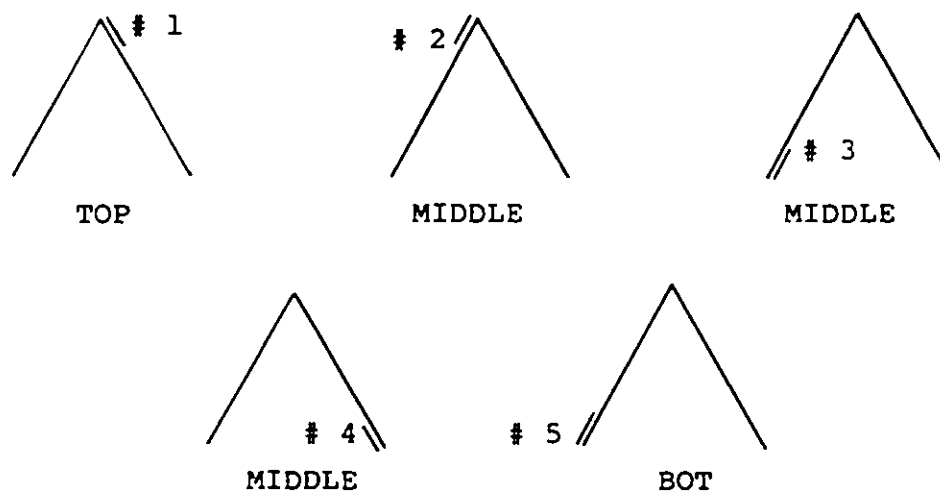


Fig.4.2

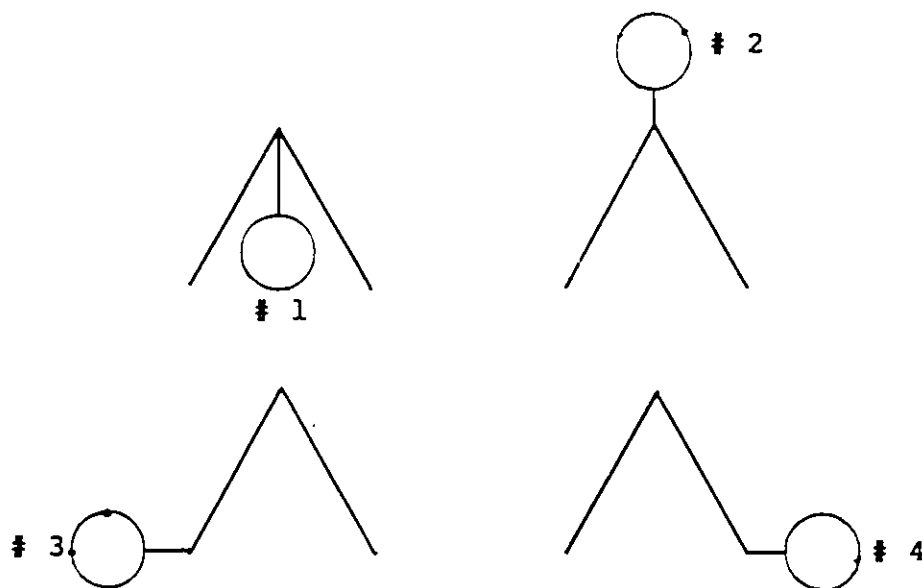
**Movable Blocking Plates to keep the Test Specimens
in Alignment**



Fig.4.3
Set-up showing a Test Specimen with
Electrical Strain Gauges attached



Location of Strain Gauges along Member Height



Location of Dial Gauges at Mid-height

Fig.4.4
Location of Strain Gauges and Dial Gauges

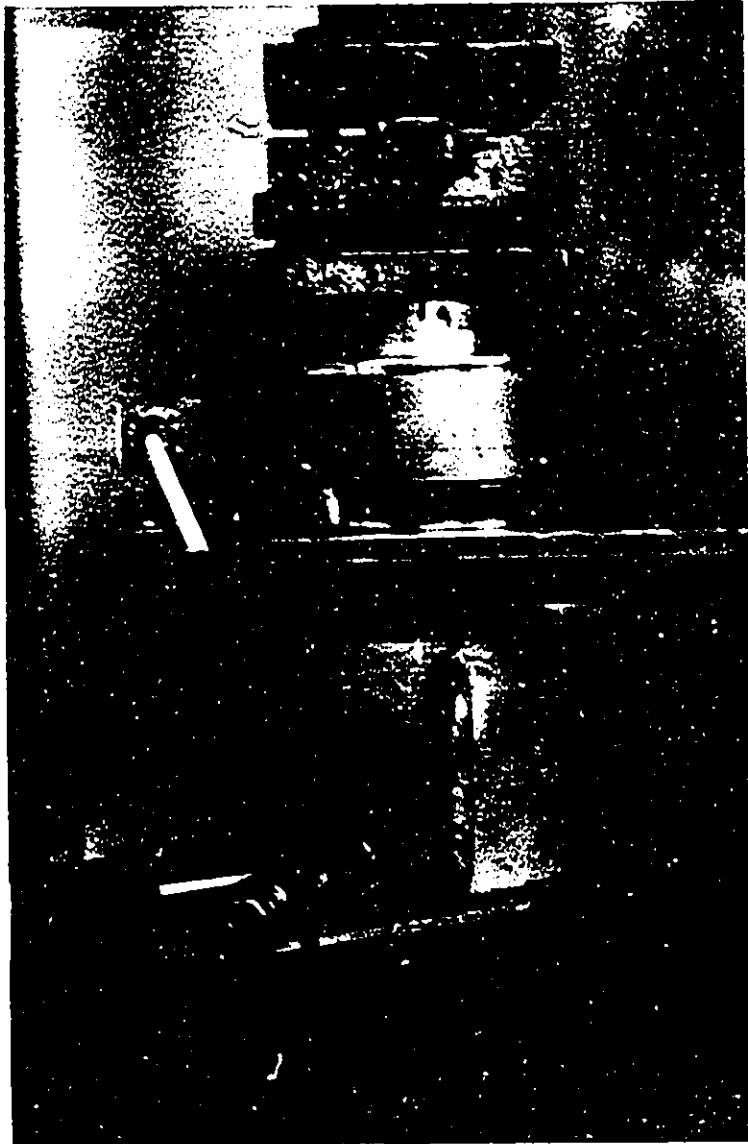


Fig.4.5
Hydraulic Jack, Load Cell and End-Plate Assembly



Fig.4.6
Test Set-up for the Schifflerized Angle showing
Pump, Strain and Load Indicators and Dial Gauges



Fig.4.7a
Specimen S4 - 1/4 - 1 showing
Torsional-Flexural Buckling



Fig.4.7b
Specimen S4 - 1/4 - 1 showing
Torsional-Flexural Buckling (another view)



Fig.4.7c
Specimen S4 - 1/4 - 1 showing closeup view

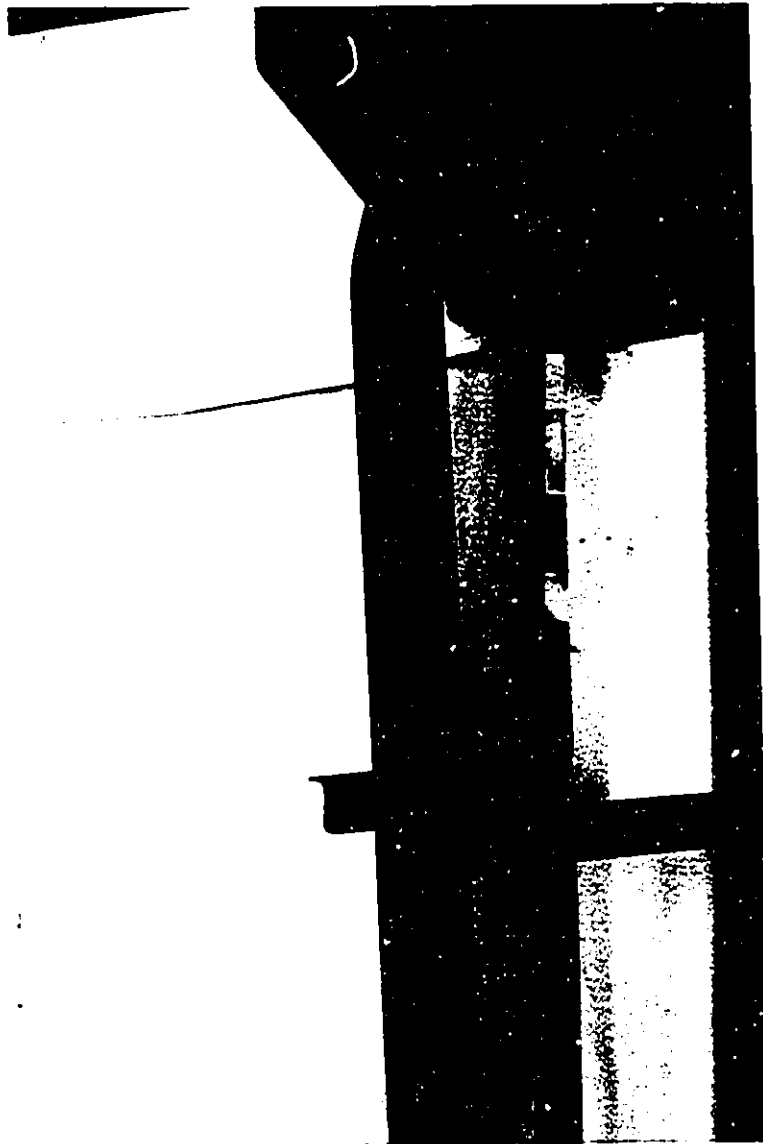


Fig.4.8
Specimen S4 - 1/4 - 3 showing
Torsional-Flexural Buckling



Fig.4.9a
Specimen S5 - 5/16 - 1 showing
Torsional-Flexural Buckling

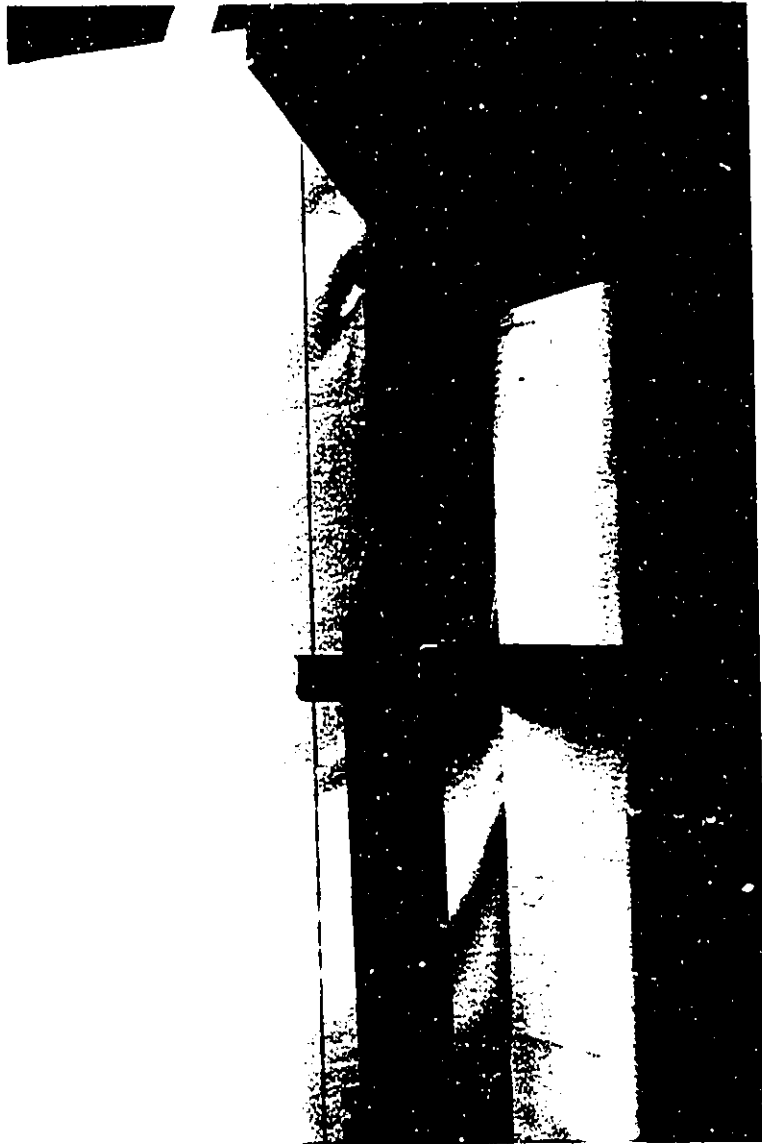


Fig.4.9b
Specimen S5 - 5/16 -1 showing
Torsional-Flexural Buckling (another view)



Fig.4.10a
Specimen S3 - 1/4 - 3 showing Major Axis Buckling

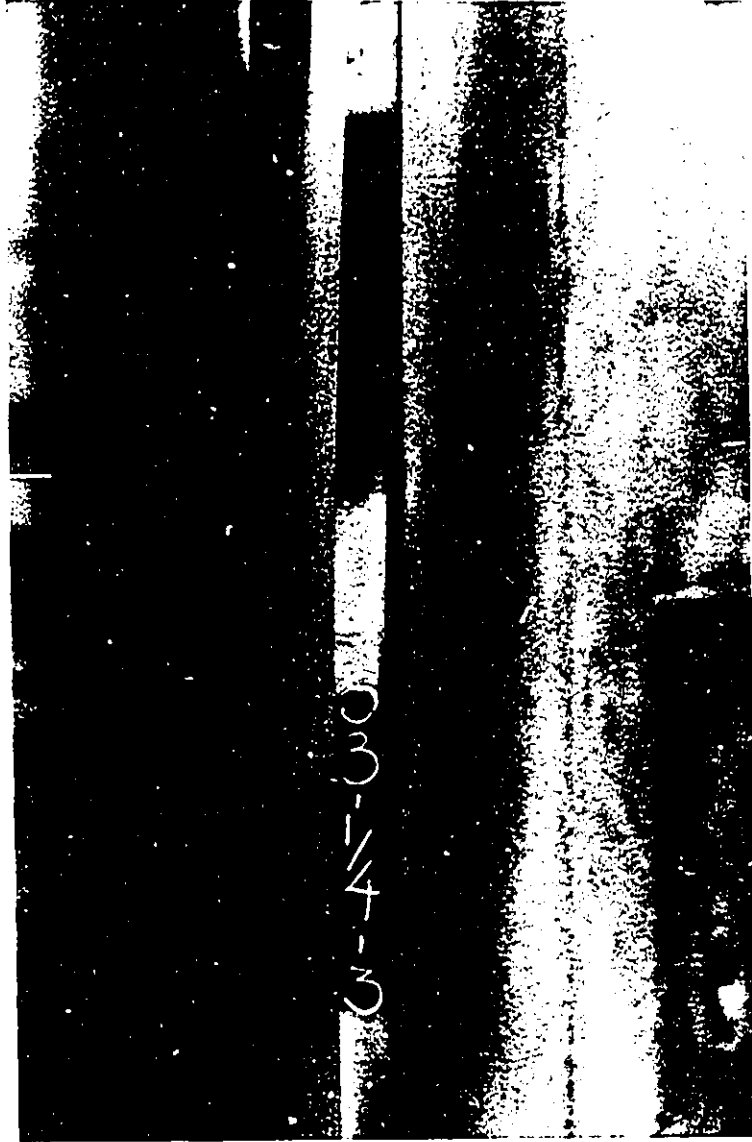


Fig.4.10b

Specimen S3 - 1/4 - 3 showing Minor Axis Buckling



Fig.4.11
Specimen S3.5-5/16-1 showing Minor Axis Buckling

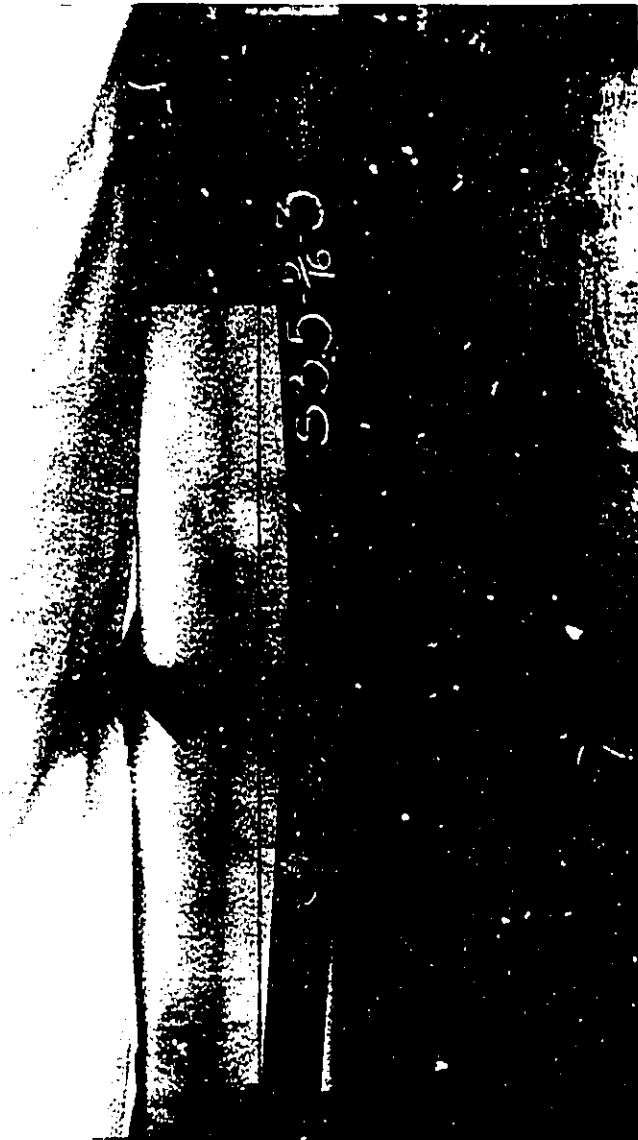


Fig.4.12
Specimen S3.5-5/16-3 showing Minor axis Buckling



Fig.4.13
Specimen S3 - 3/8 - 1 showing Minor Axis Buckling

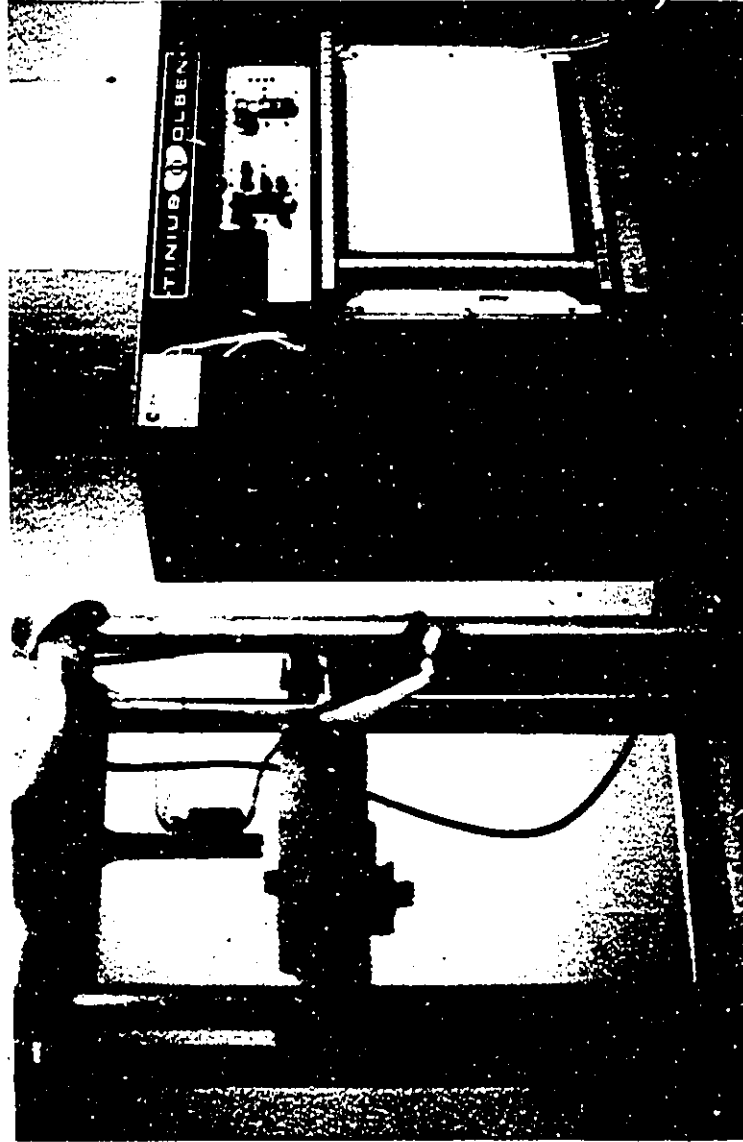


Fig.4.14
Tensile Test Set-up showing Tensile Coupon,
Extensometer, X-Y Recorder and Universal
Testing Machine

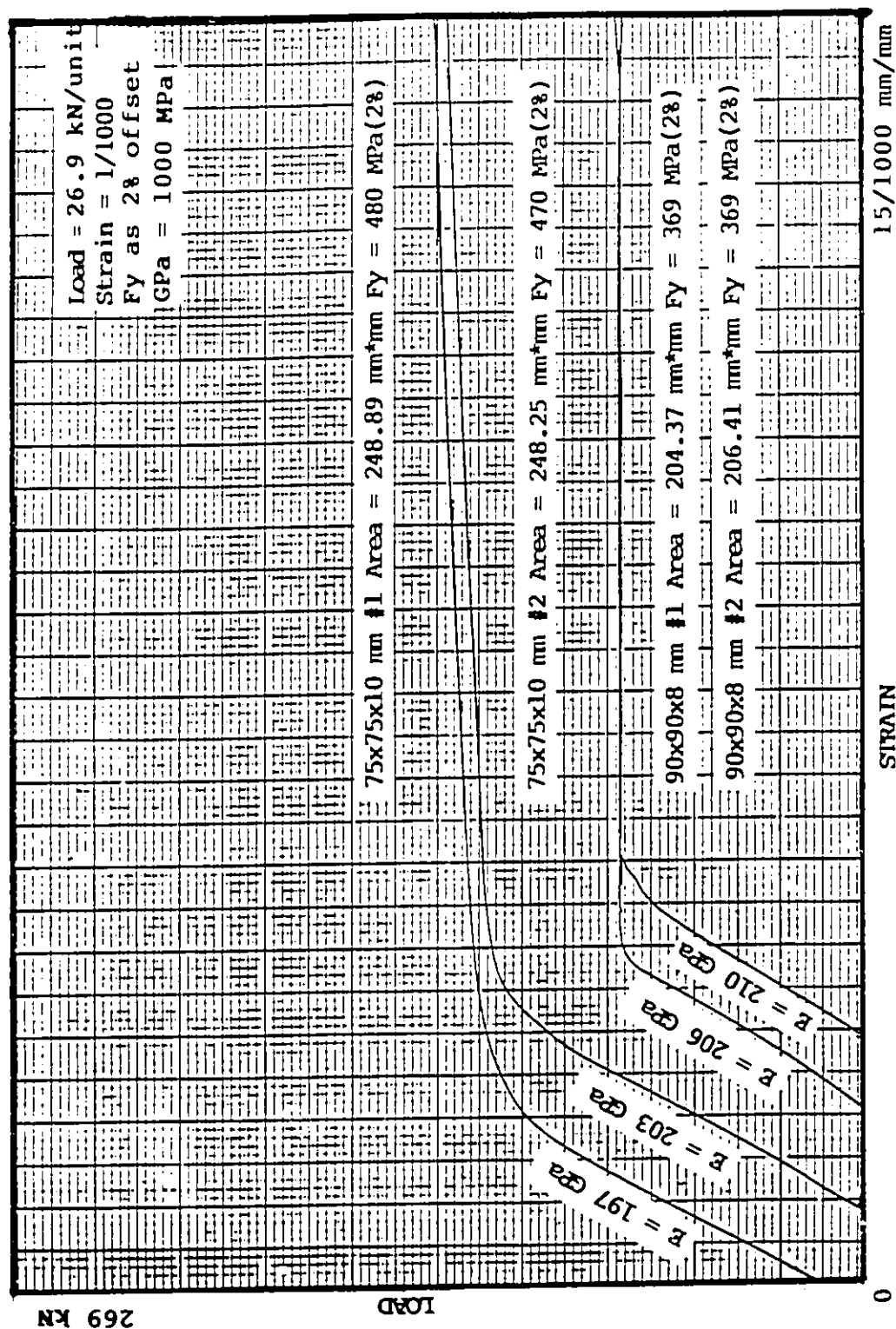


Fig. 4.15a

Standard Tension Test Curves - Set A

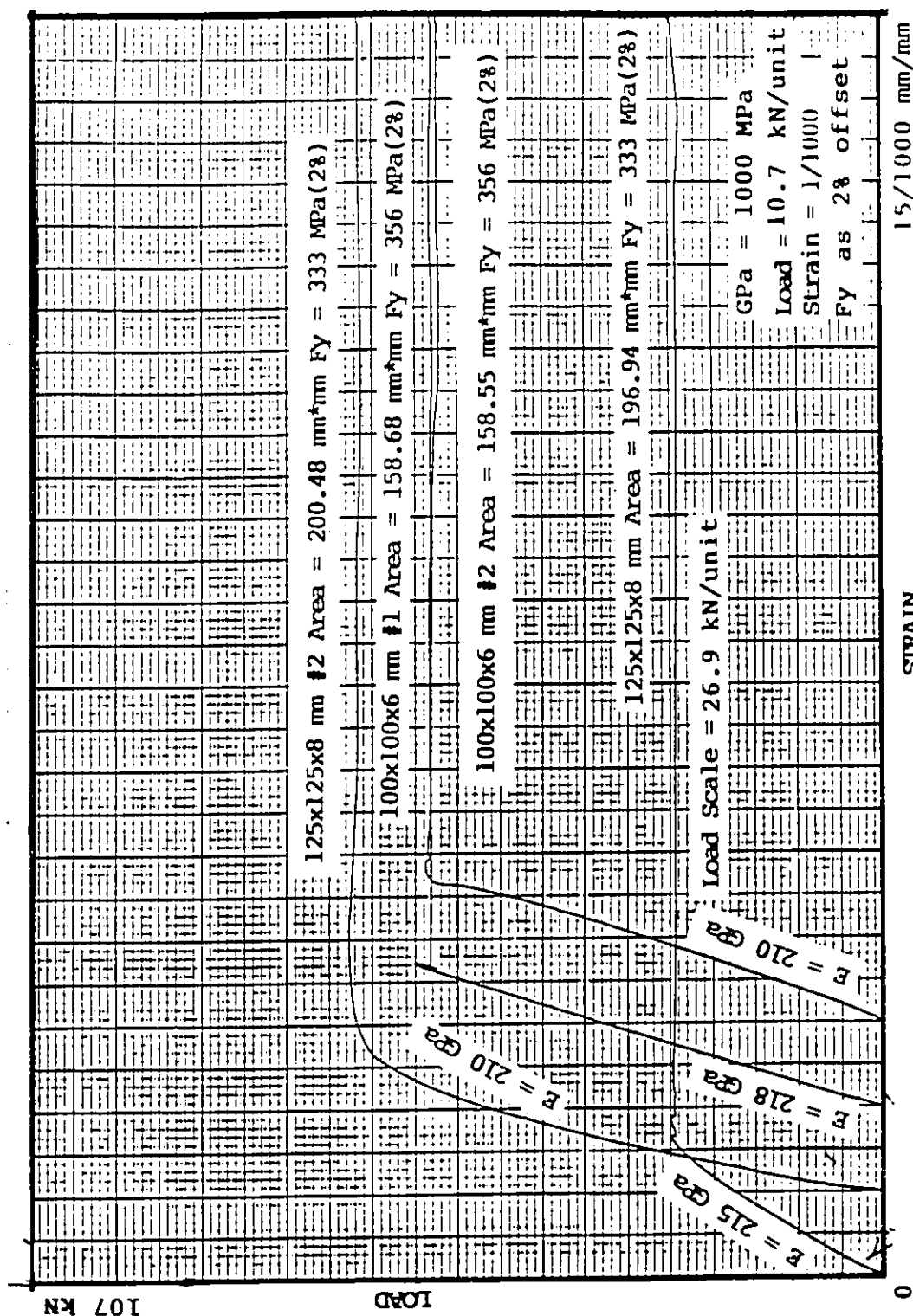
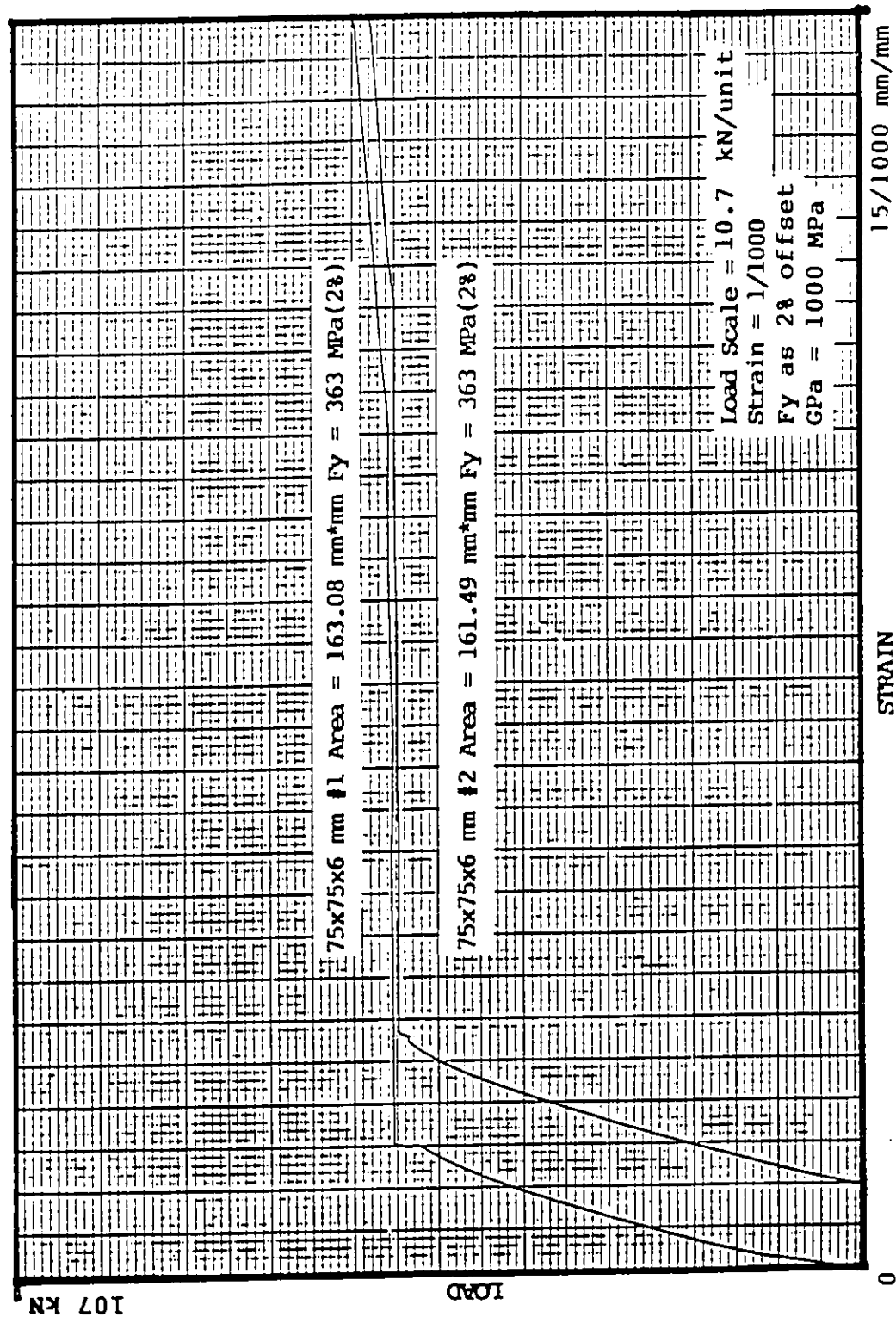


Fig. 4.15b

Standard Tension Test Curves - Set B



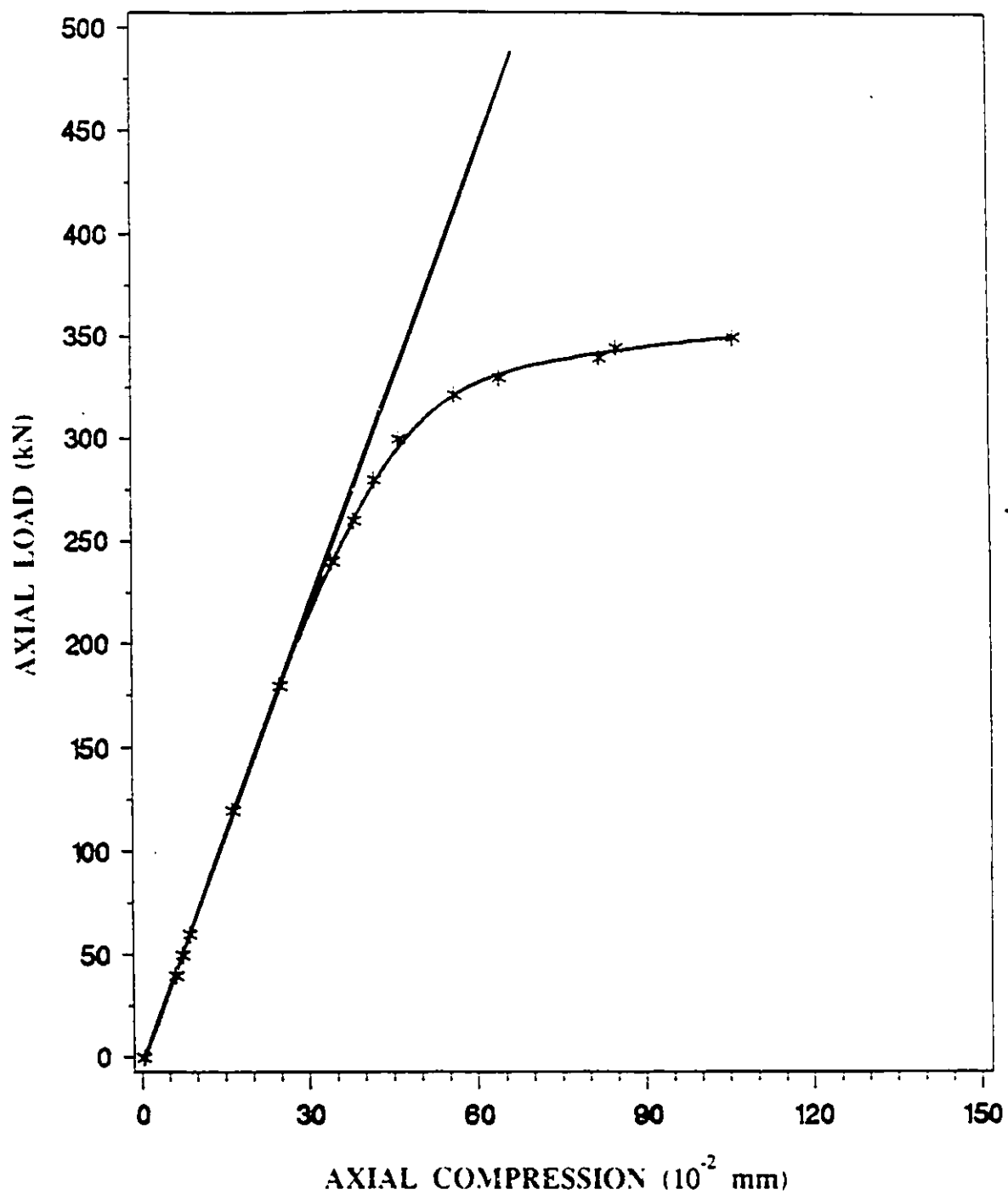


Fig.4.16
STUB-COLUMN TEST RESULTS
for 3x3x1/4 in. SCHIFFLERIZED ANGLE

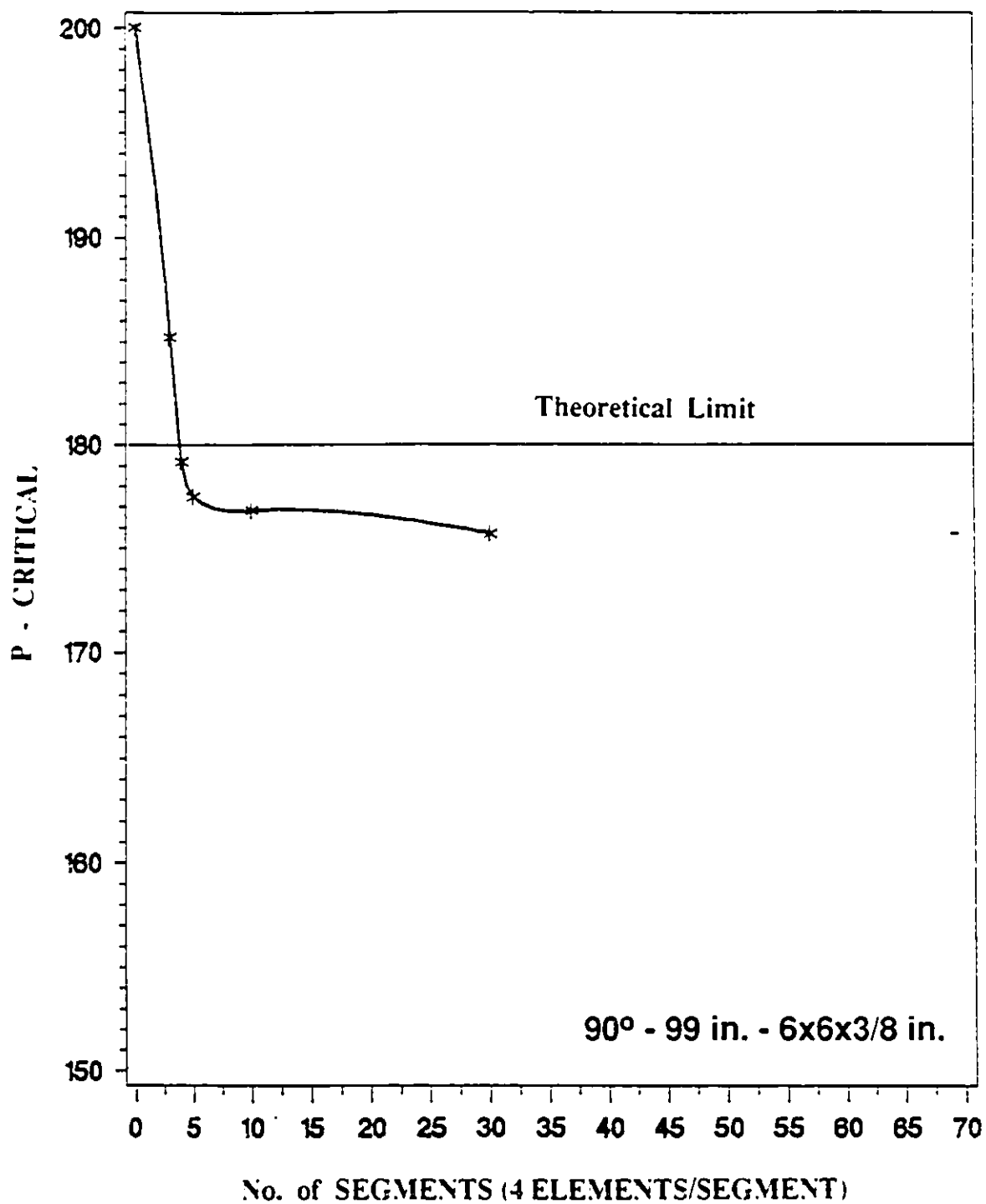


Fig.5.1
TEST FOR CONVERGENCE OF FINITE ELEMENT LOAD
FOR FLEXURAL BUCKLING ANALYSIS

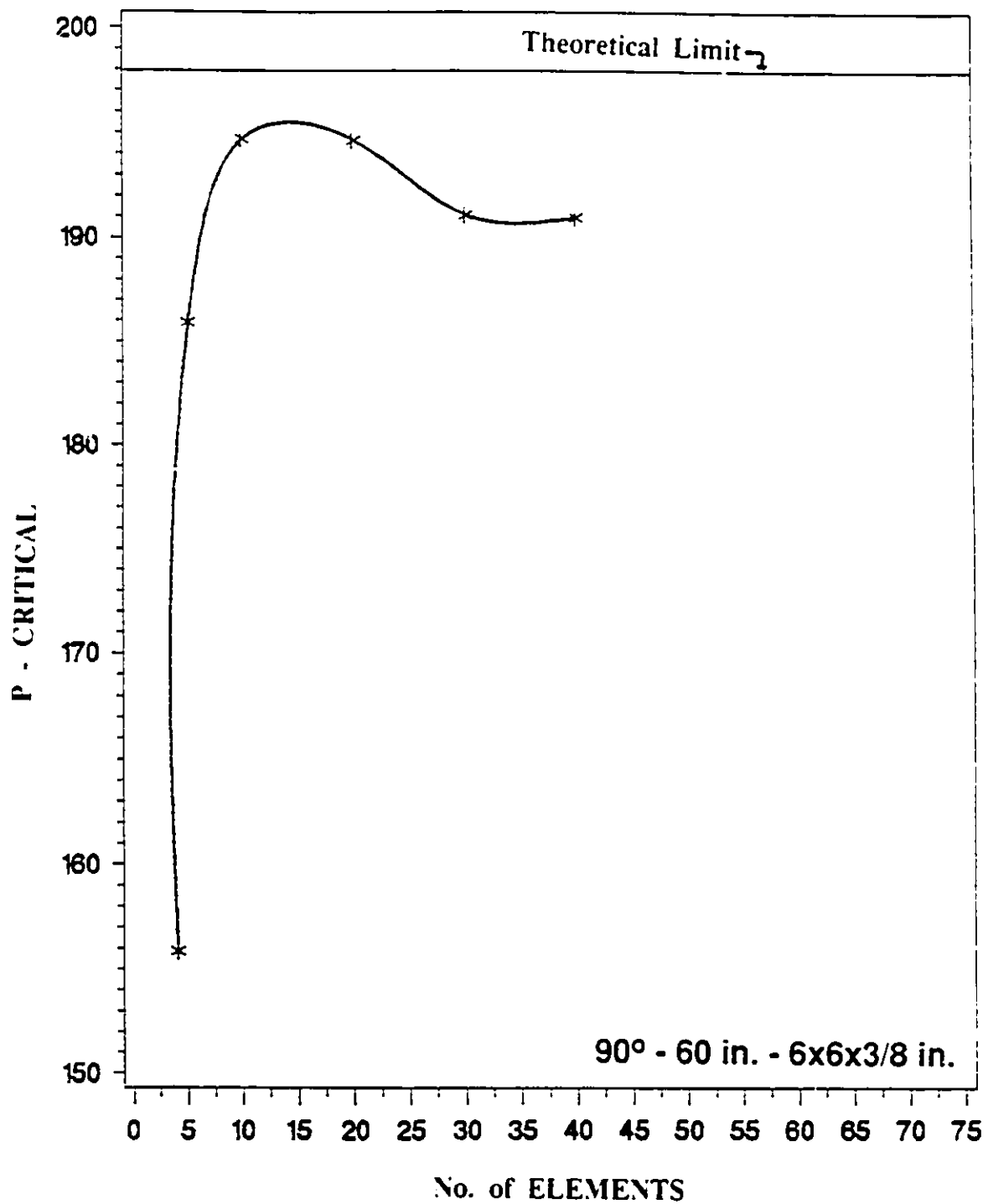


Fig.5.2
TEST FOR CONVERGENCE OF FINITE ELEMENT LOAD
FOR TORSIONAL-FLEXURAL BUCKLING ANALYSIS

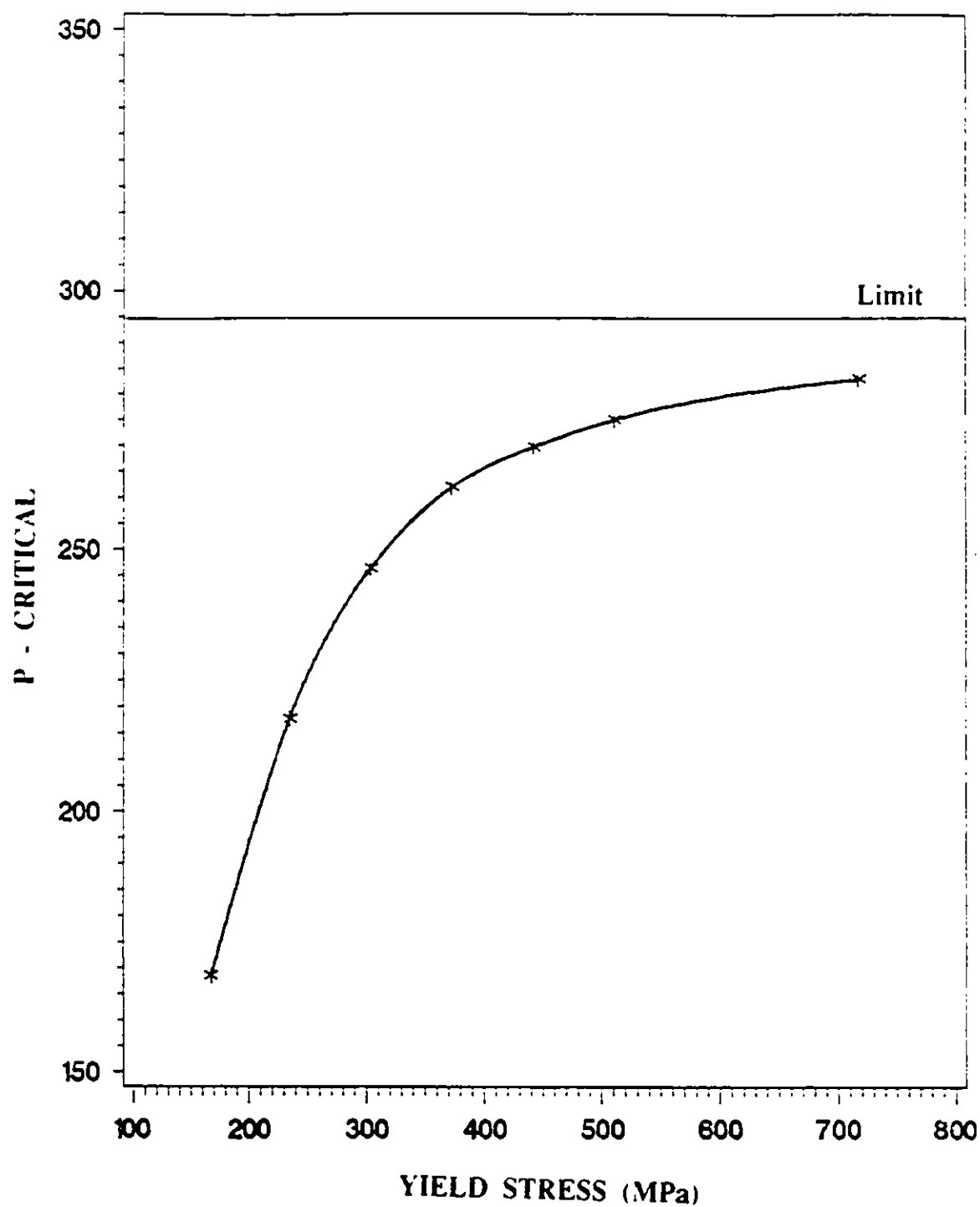


Fig.5.3
LOAD vs YIELD STRESS
75x75x10mm SCHIFFLERIZED ANGLE

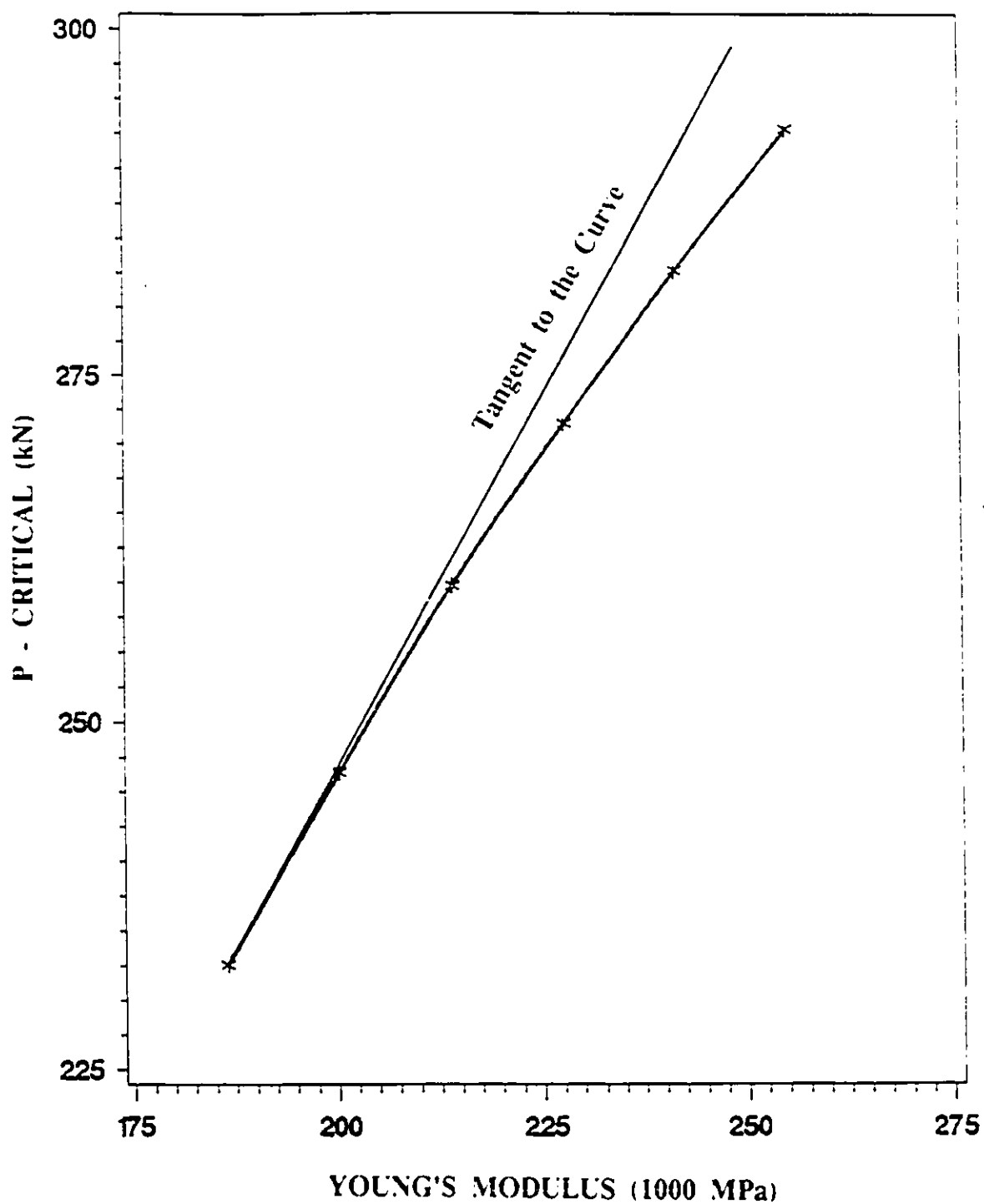


Fig.5.4
LOAD vs YOUNG'S MODULUS
75x75x10mm SCHIFFLERIZED ANGLE

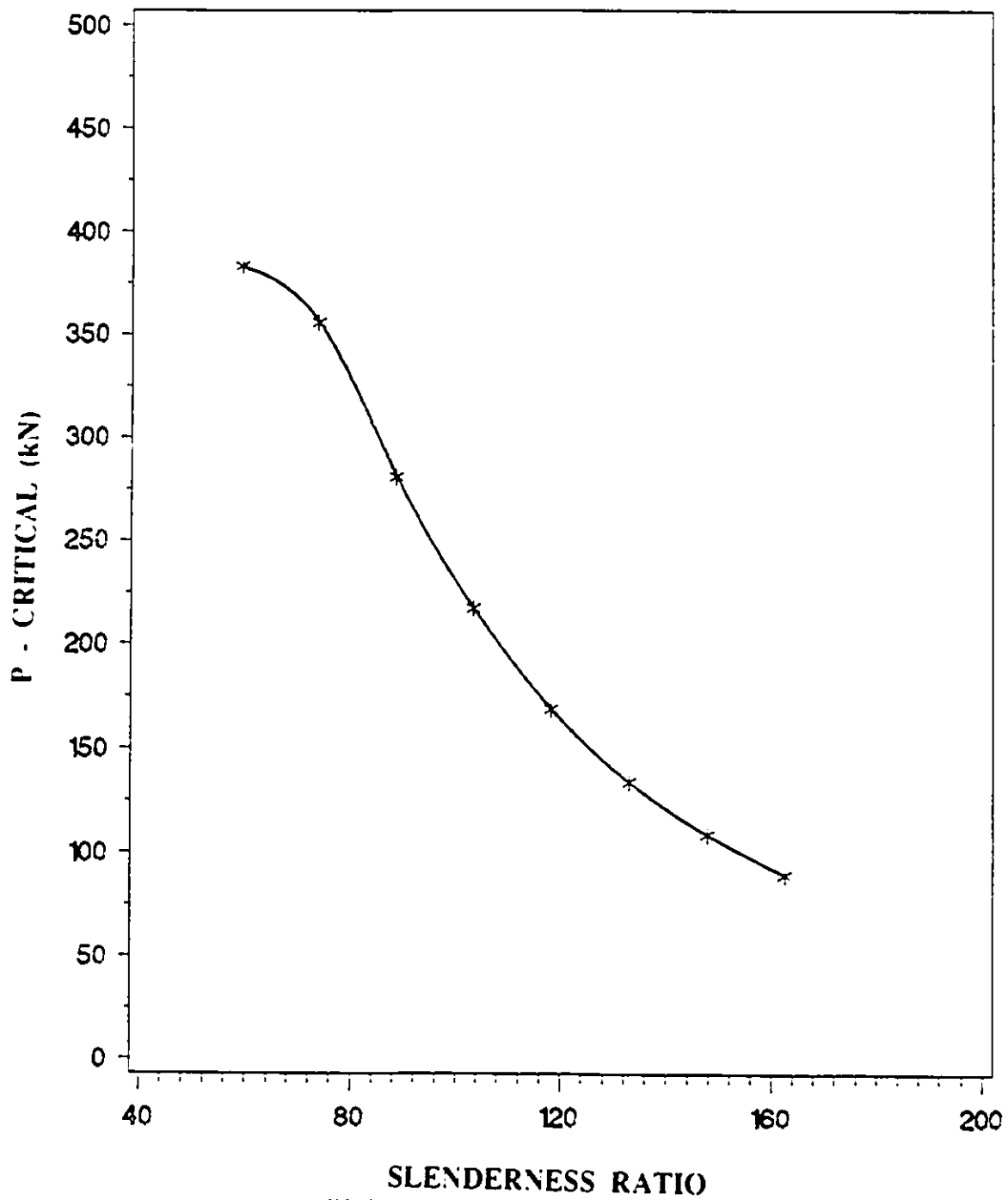


Fig.5.5
LOAD vs SLENDERNESS RATIO
75x75x10mm SCHIFFLERIZED ANGLE

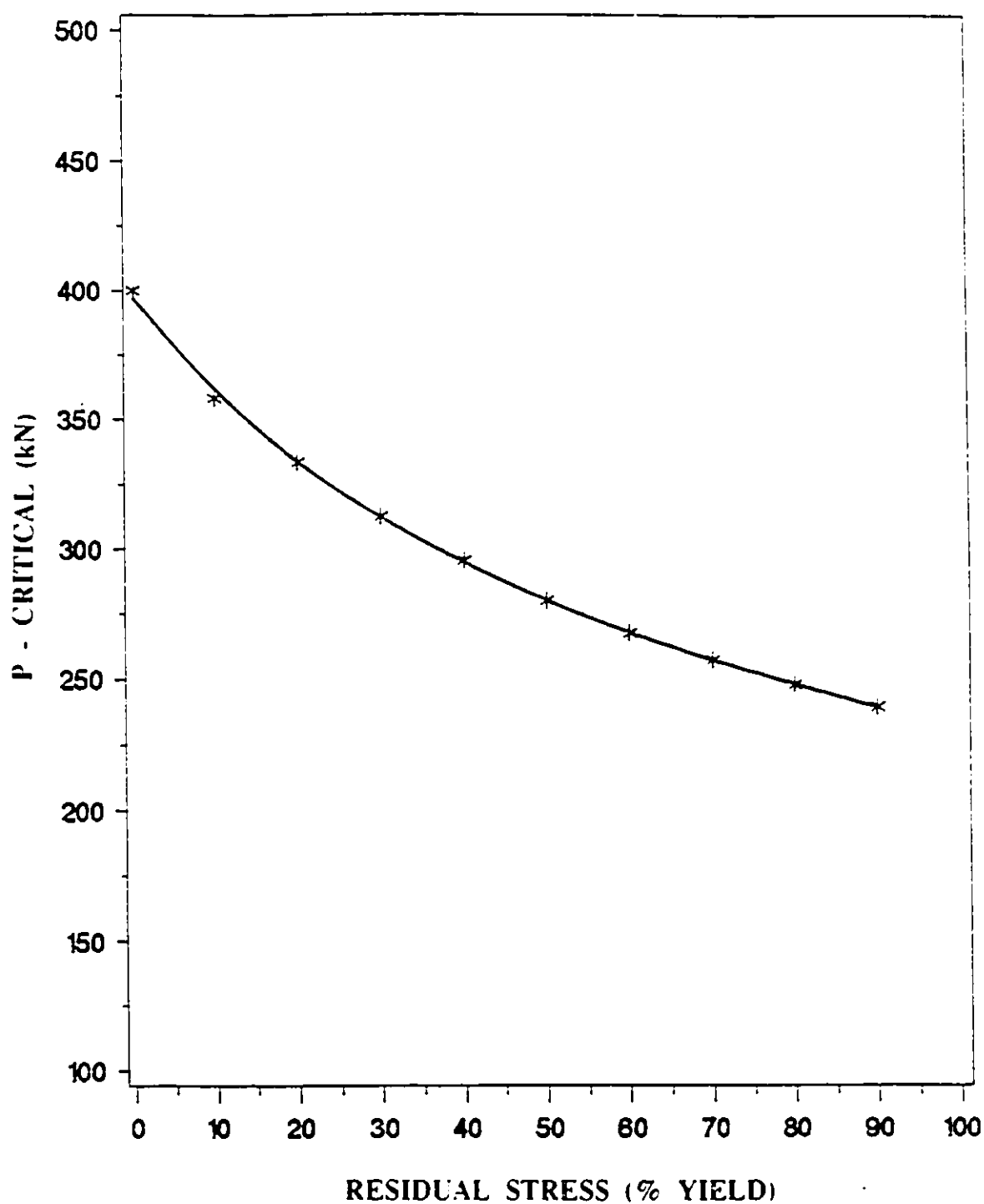


Fig.5.6

LOAD vs RESIDUAL STRESS
75x75x10mm SCHIFFLERIZED ANGLE

Appendix A
TYPICAL FIGURES FOR STRAIN GAUGE
READINGS,
MID-HEIGHT DEFLECTION AND MID-HEIGHT TWIST

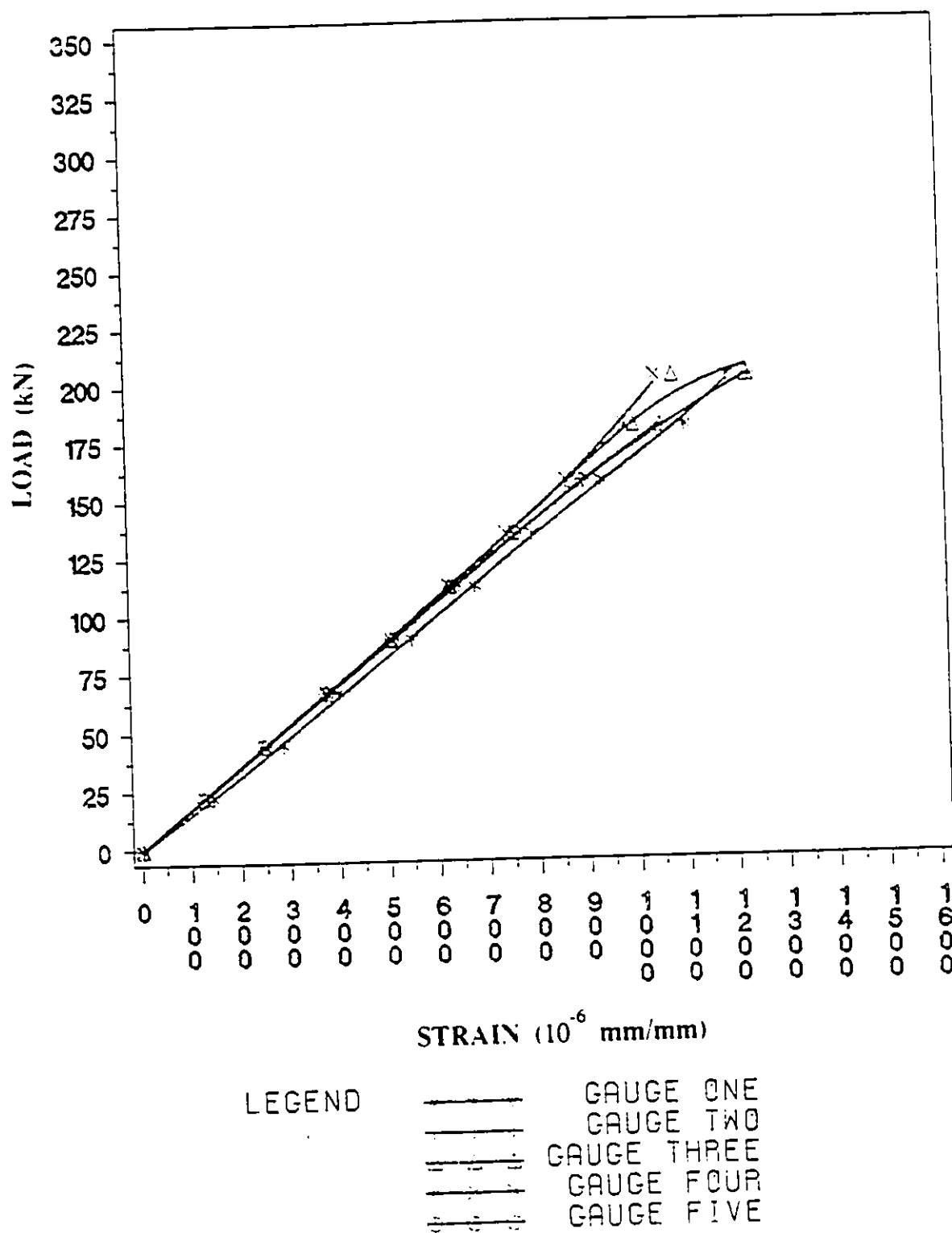


Fig.A.1a

LOAD vs SURFACE STRAIN, SPECIMEN S3 - 1/4 - 3

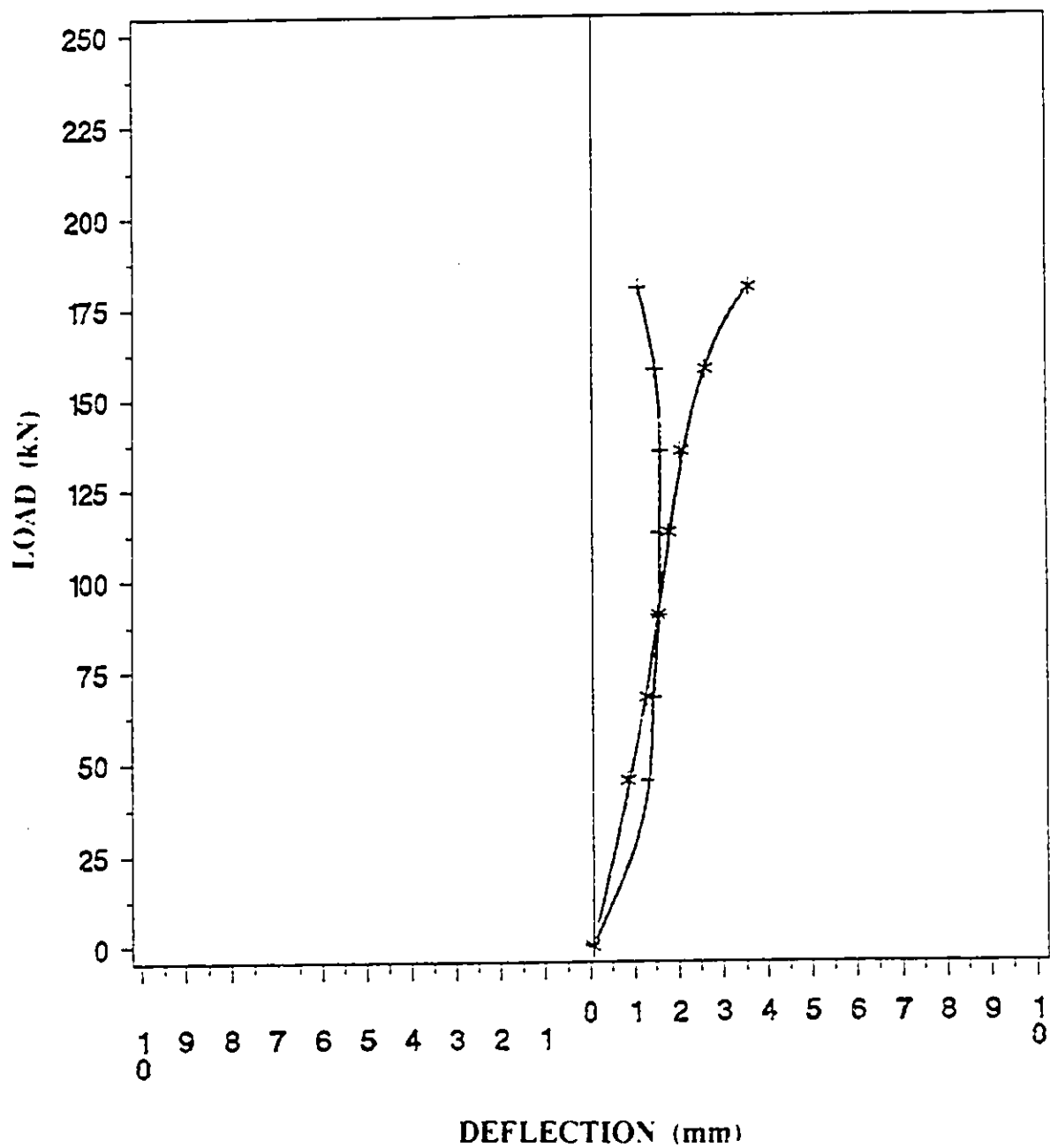


Fig.A.1b
LOAD vs DEFLECTION, SPECIMEN S3 - 1/4 - 3

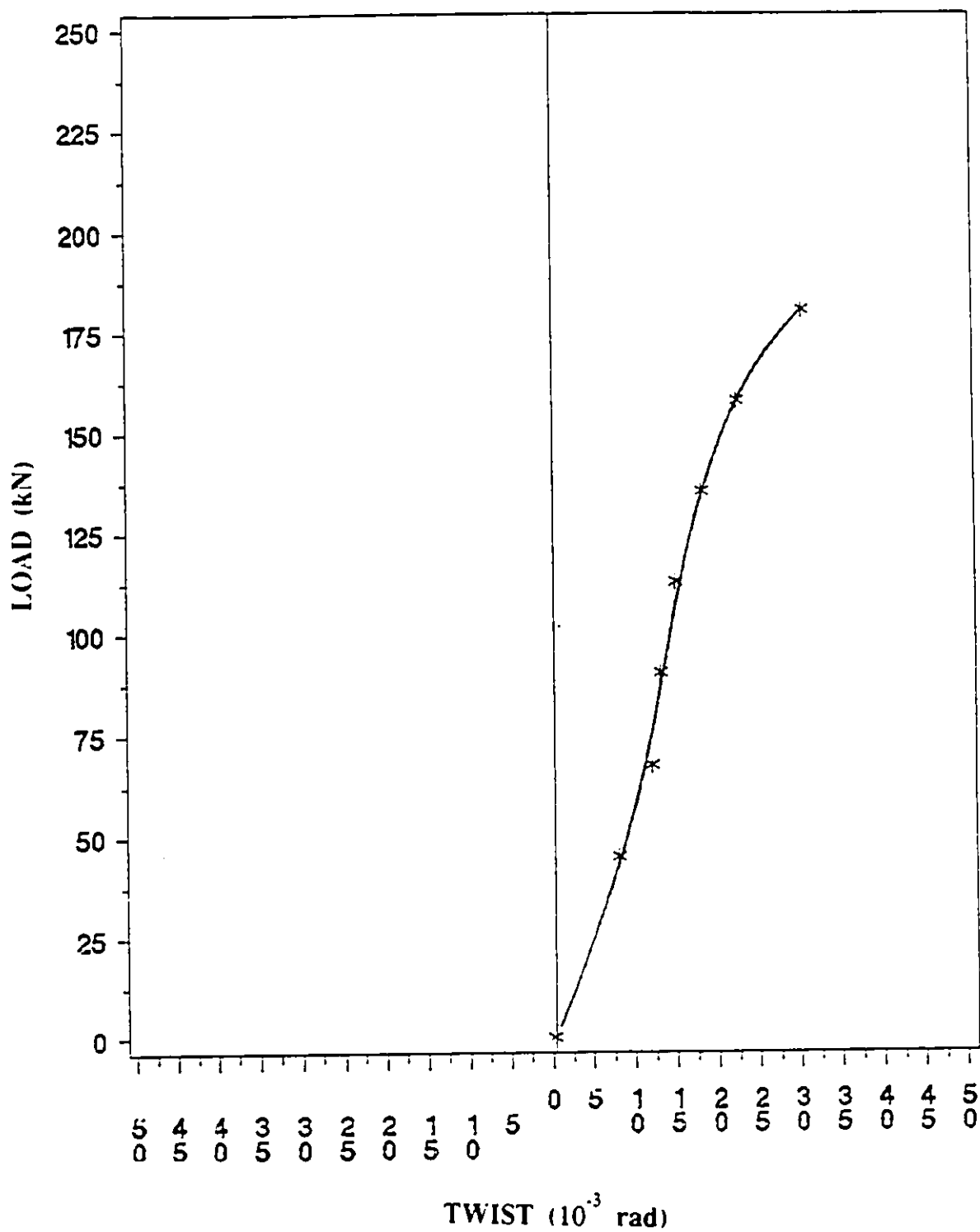
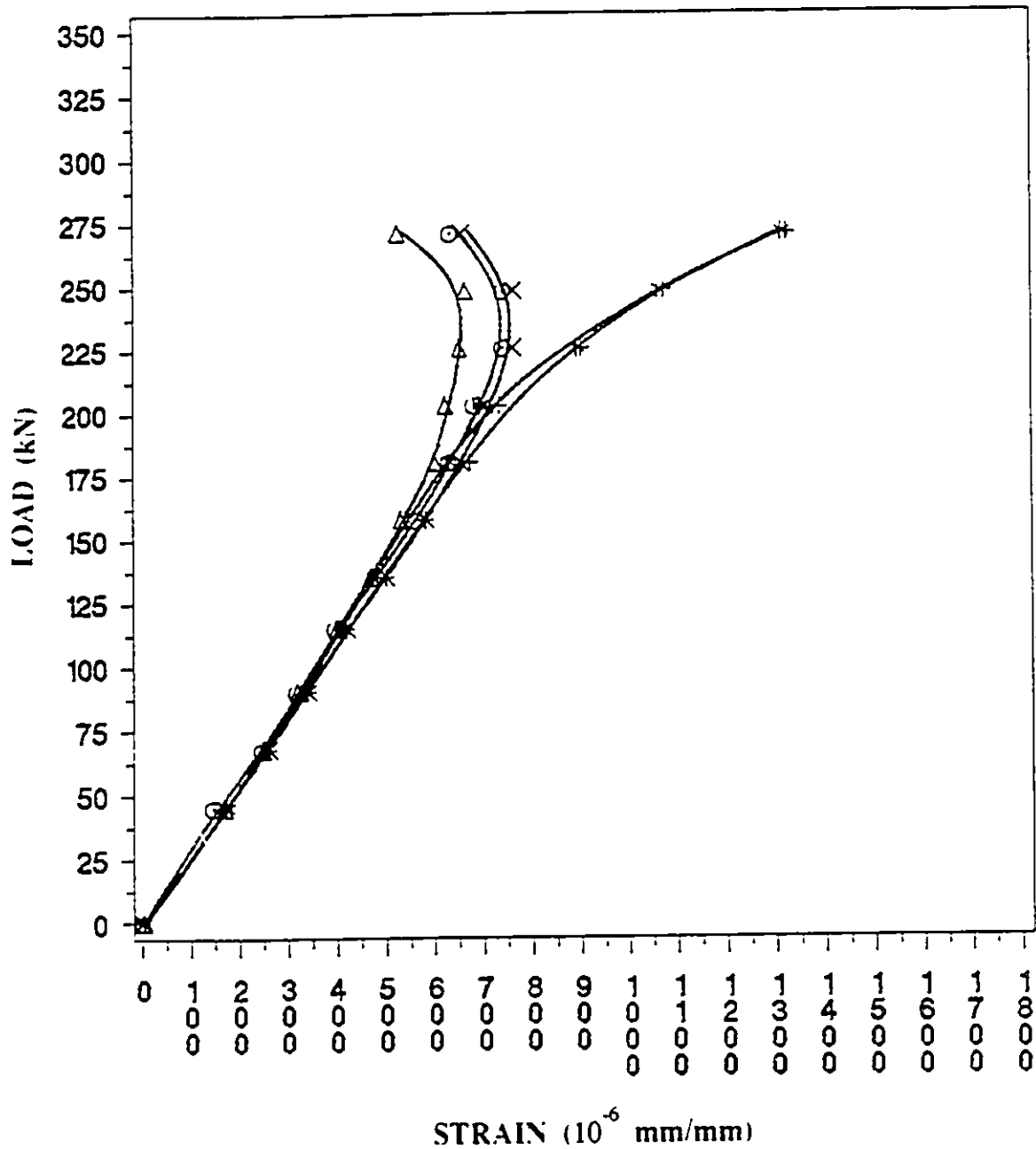


Fig.A.1c

LOAD vs MID-HEIGHT TWIST, SPECIMEN S3 - 1/4 - 3

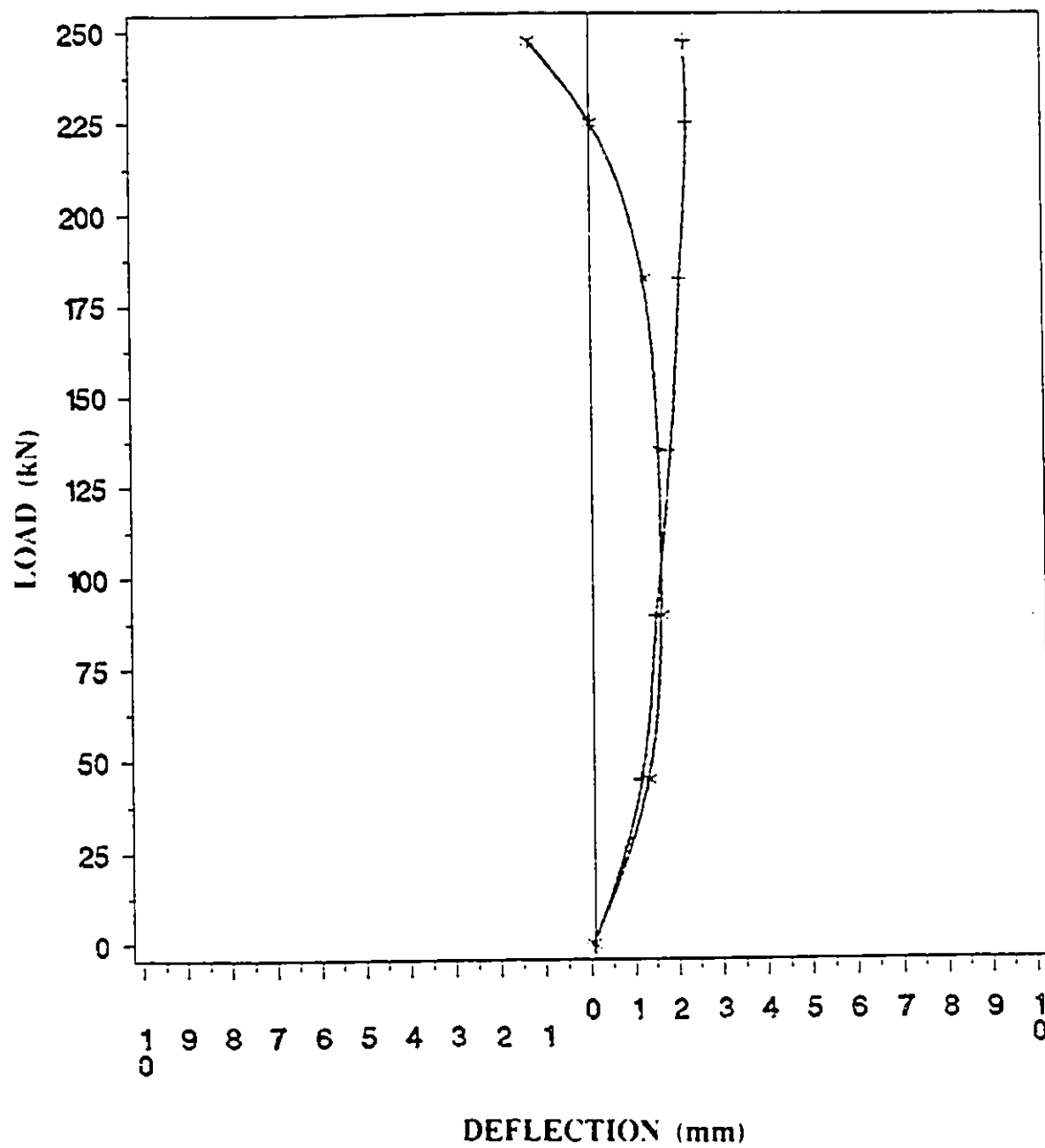


LEGEND

***	GAUGE ONE
++	GAUGE TWO
△△△	GAUGE THREE
×××	GAUGE FOUR
○○○	GAUGE FIVE

Fig.A.2a

LOAD vs SURFACE STRAIN, SPECIMEN S3 - 3/8 - 2



LEGEND
x x x U-U DEFLECTION
+ + + V-V DEFLECTION

Fig.A.2b

LOAD vs DEFLECTION, SPECIMEN S3 - 3/8 - 2

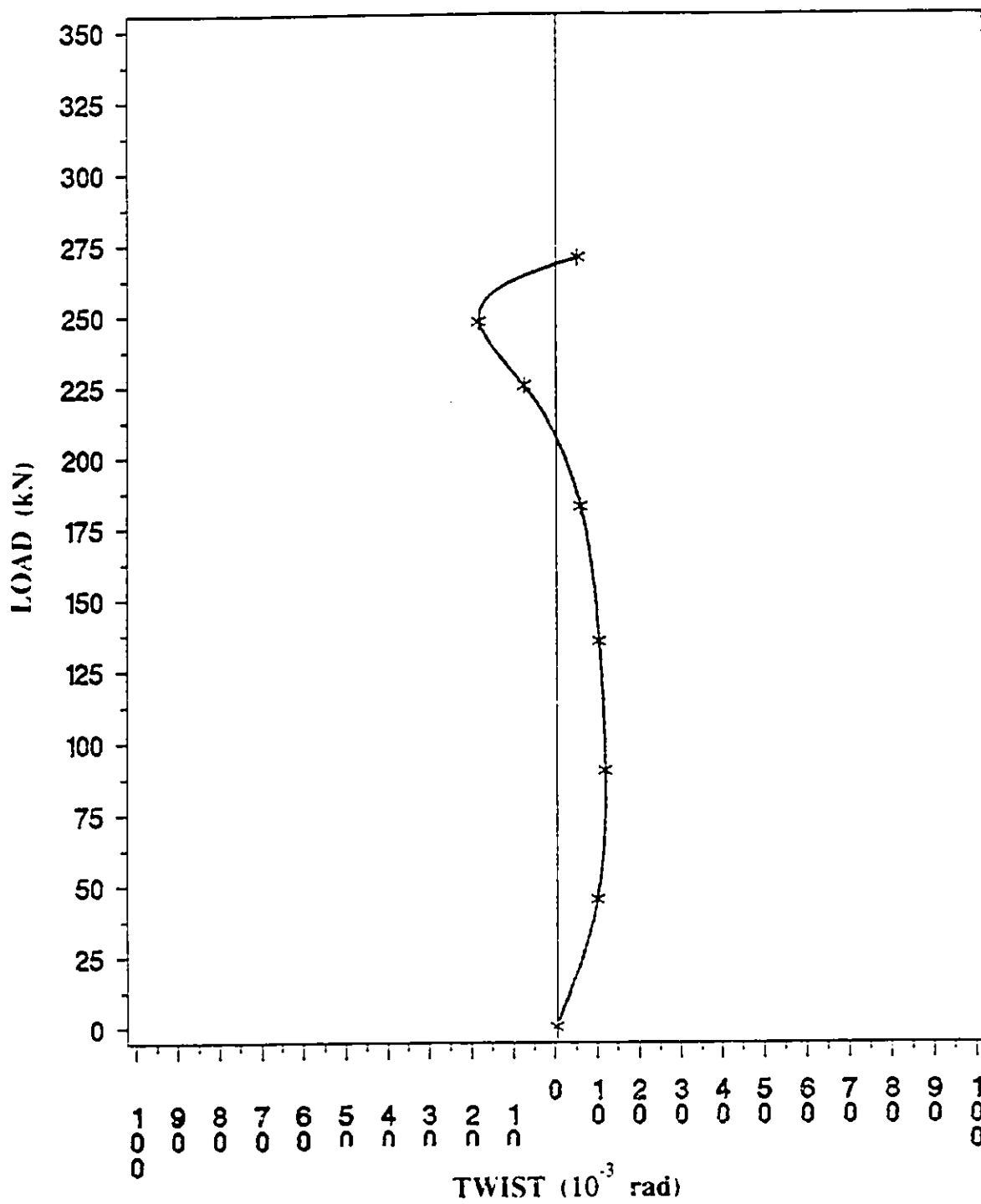
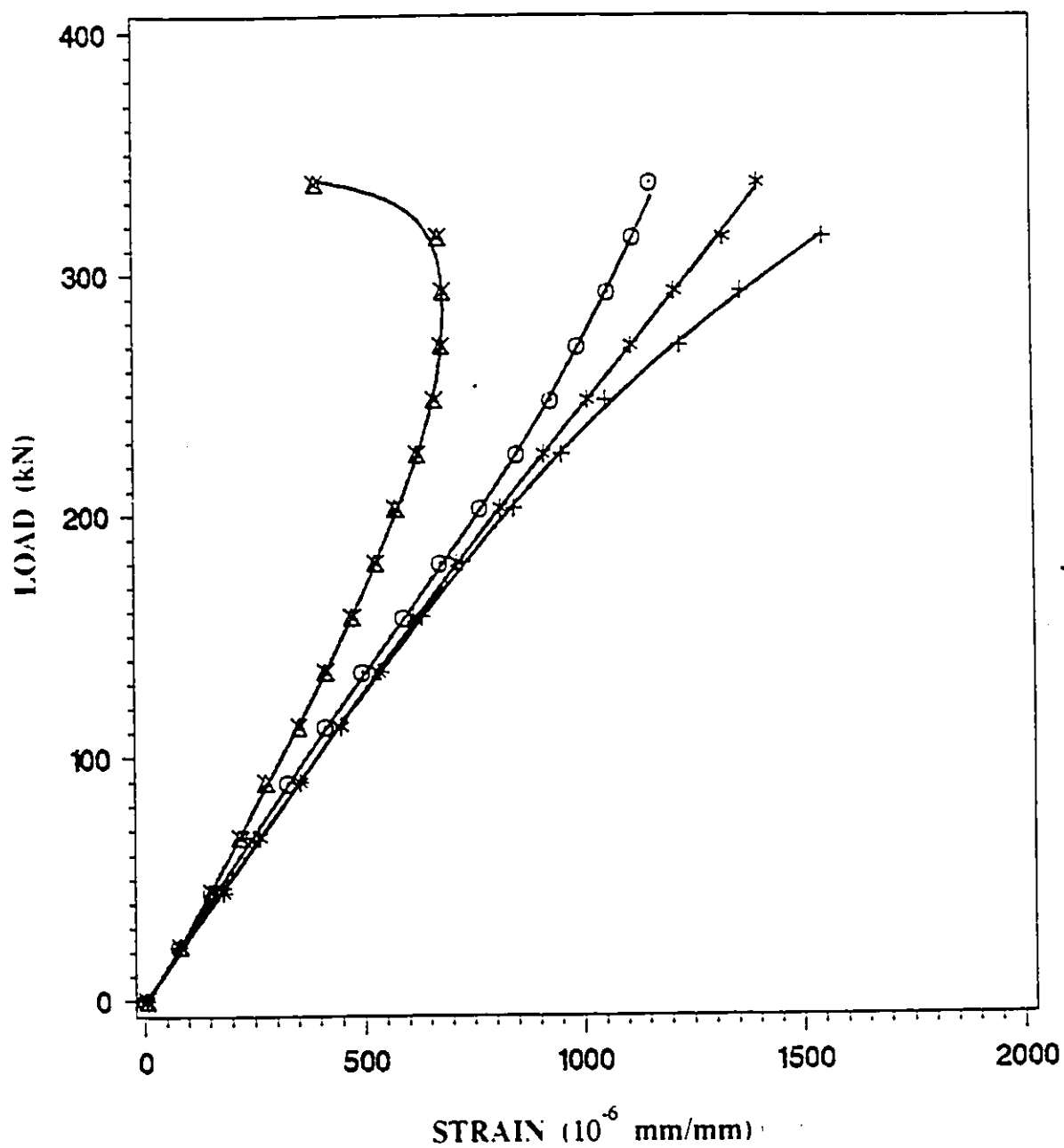


Fig.A.2c

LOAD vs MID-HEIGHT TWIST, SPECIMEN S3 - 3/8 - 2

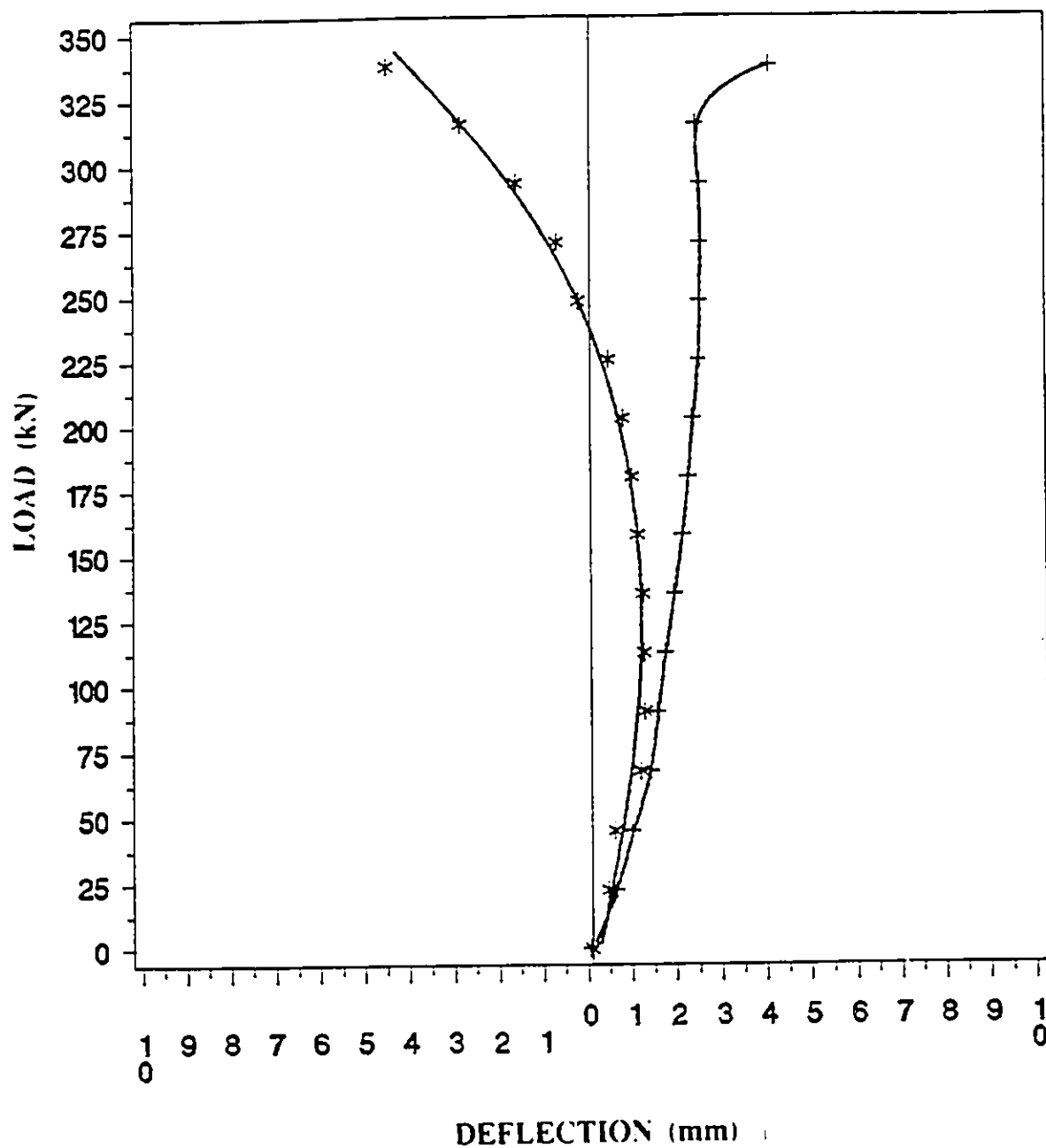


LEGEND

- *-*-* GAUGE ONE
- +--+ GAUGE TWO
- △-△-△ GAUGE THREE
- *-*-* GAUGE FOUR
- GAUGE FIVE

Fig.A.3a

LOAD vs SURFACE STRAIN, SPECIMEN S3.5 - 5/16 - 1



LEGEND
* * * U-U DISPLACEMENT
+ + + V-V DISPLACEMENT

Fig.A.3b

LOAD vs DEFLECTION, SPECIMEN S3.5-5/16-1

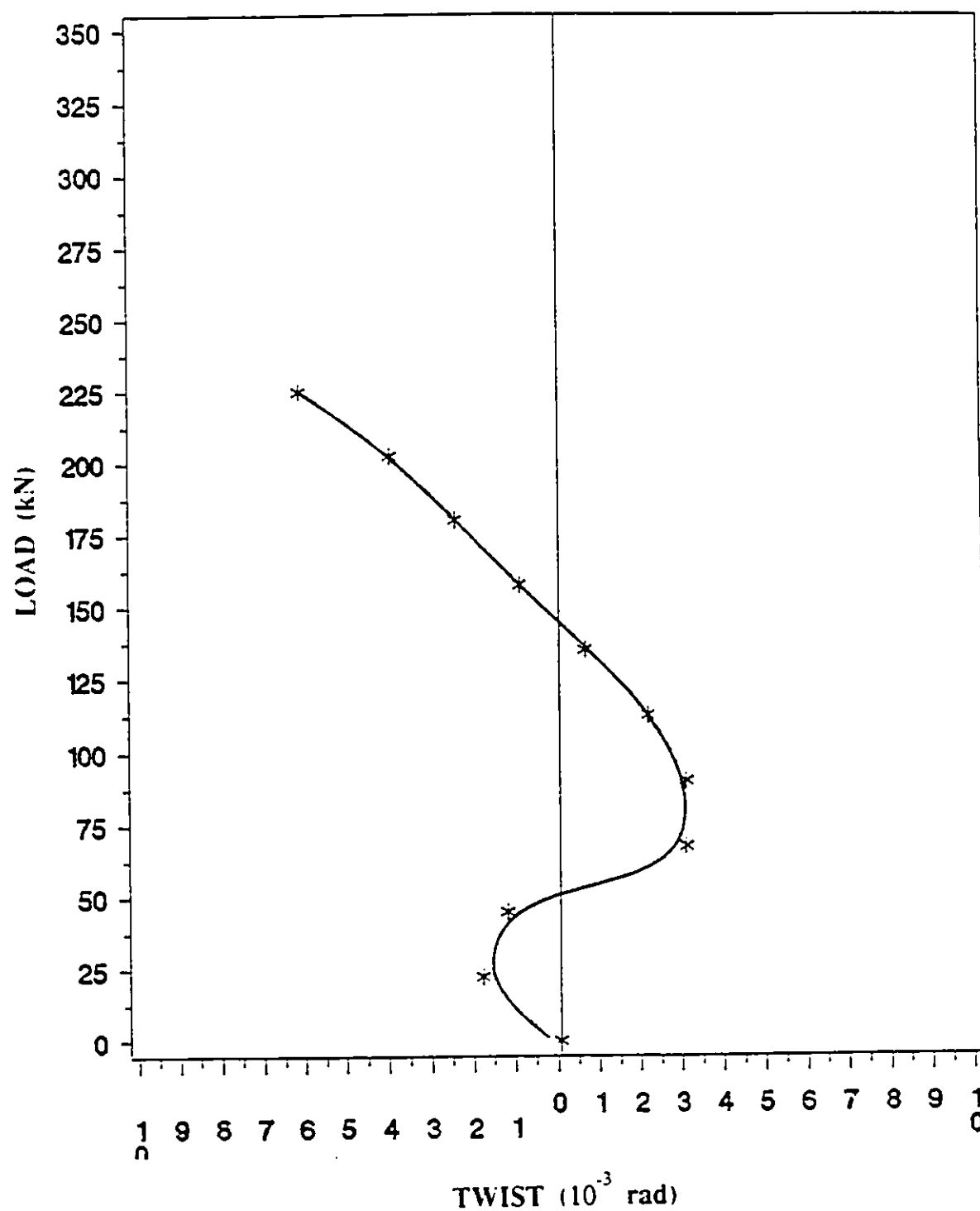
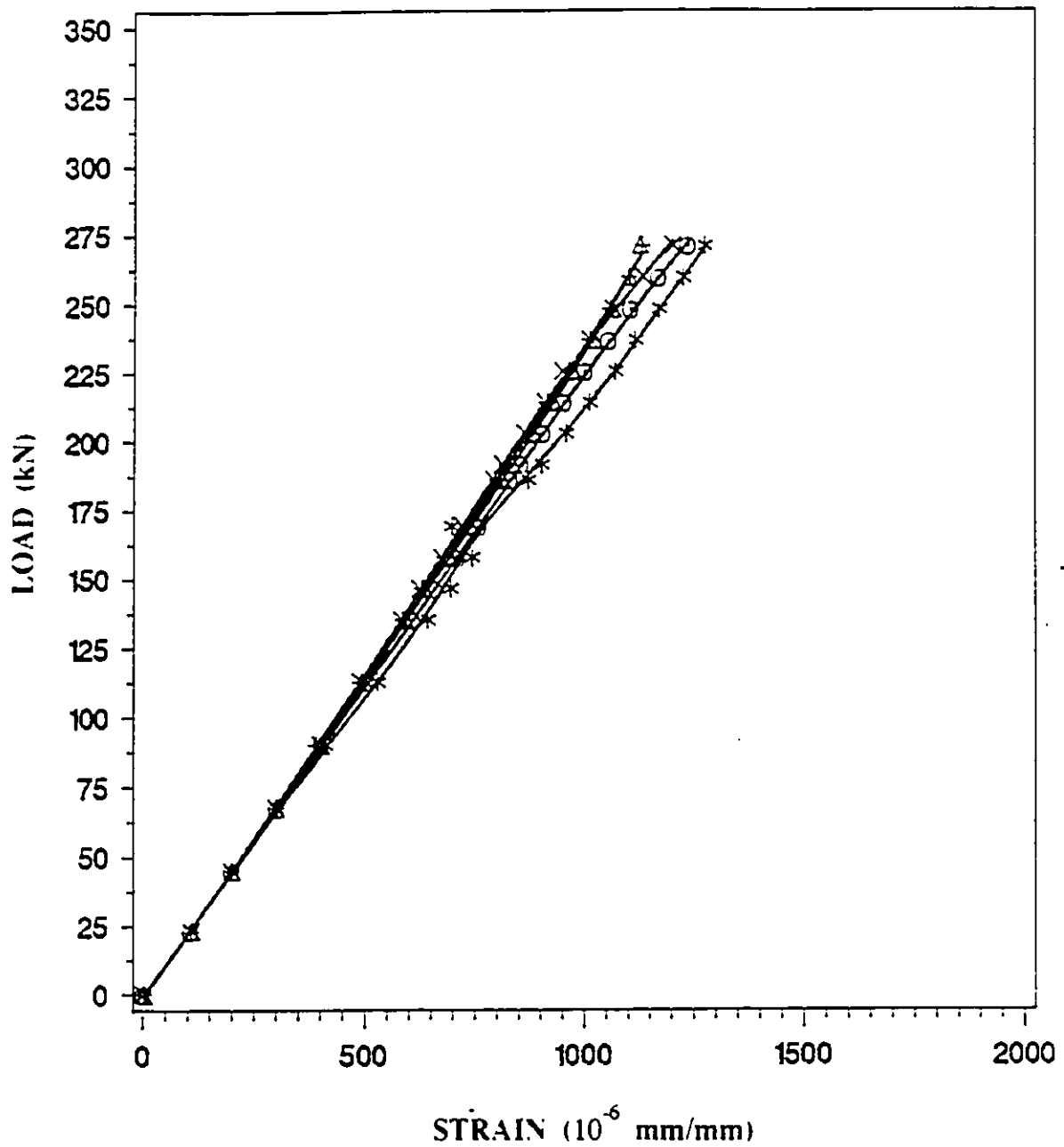


Fig.A.3c

LOAD vs MID-HEIGHT TWIST, SPECIMEN S3.5-5/16-1

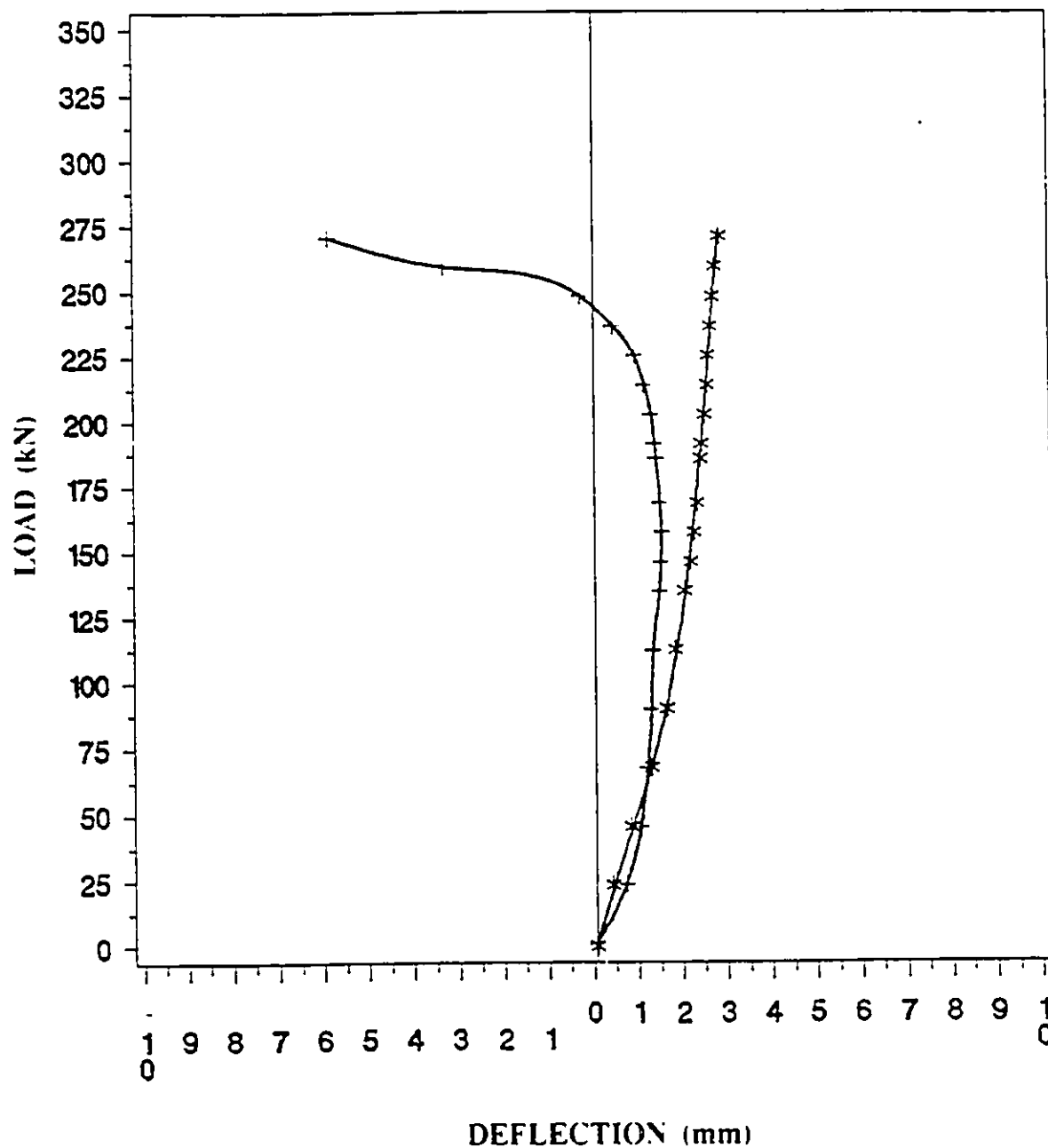


LEGEND

--*	GAUGE ONE
+--+	GAUGE TWO
△-△-△	GAUGE THREE
×-×-×	GAUGE FOUR
○-○-○	GAUGE FIVE

Fig.A.4a

LOAD vs SURFACE STRAIN, SPECIMEN S4 - 1/4 - 1



LEGEND

x x x U-U DEFLECTION

+ + + V-V DEFLECTION

Fig.A.4b

LOAD vs DEFLECTION, SPECIMEN S4 - 1/4 - 1

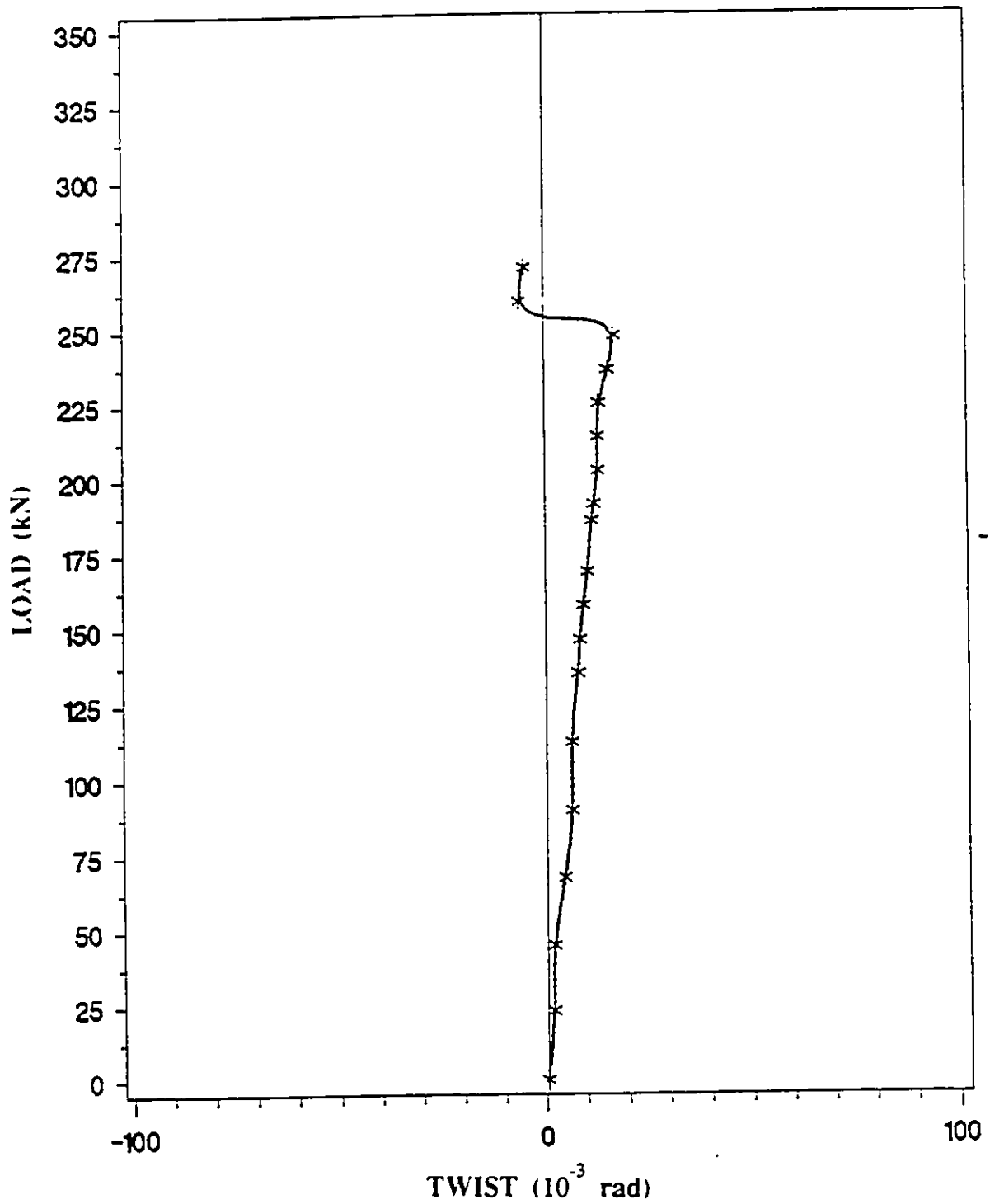


Fig.A.4c

LOAD vs MID-HEIGHT TWIST, SPECIMEN S4 - 1/4 - 1

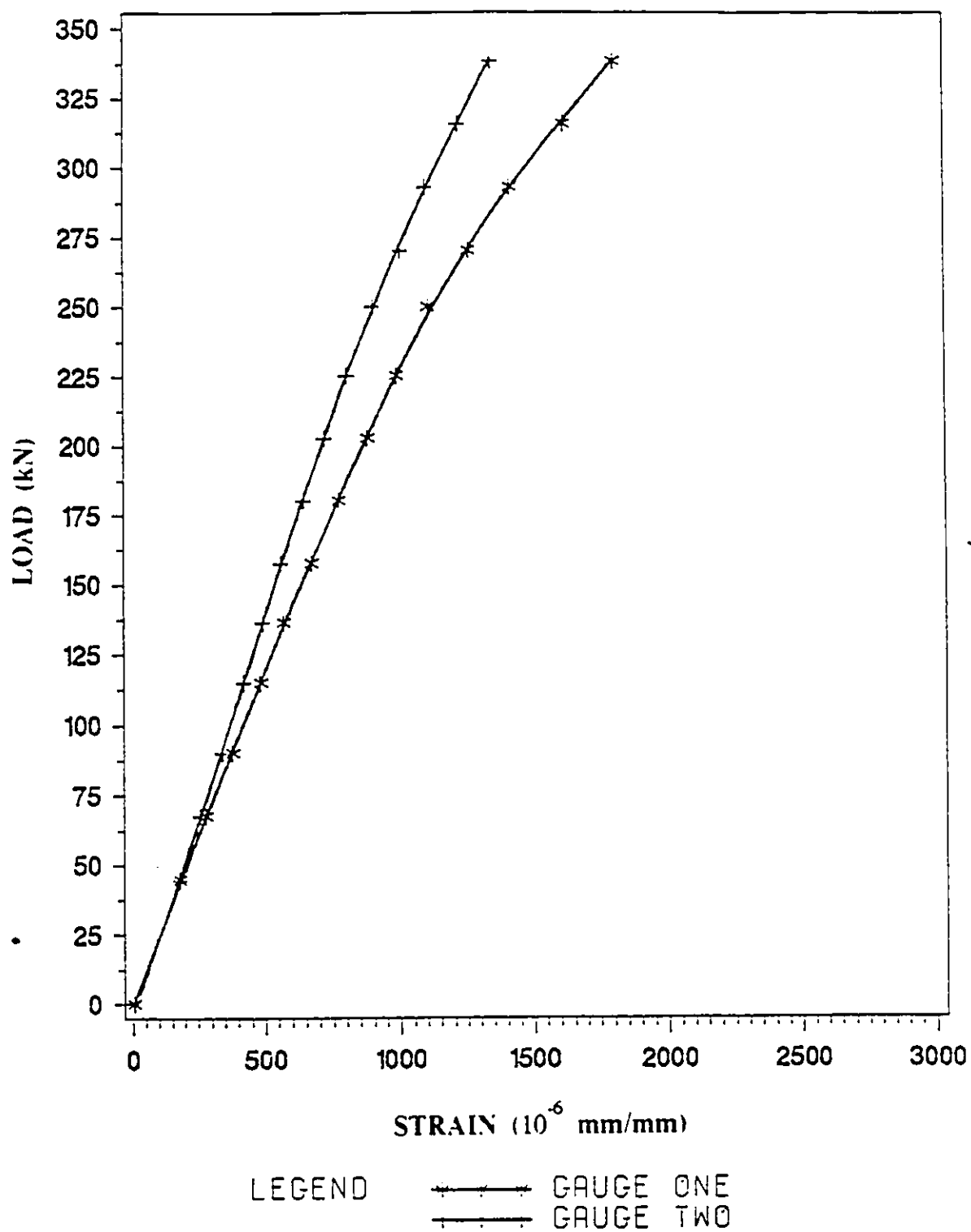
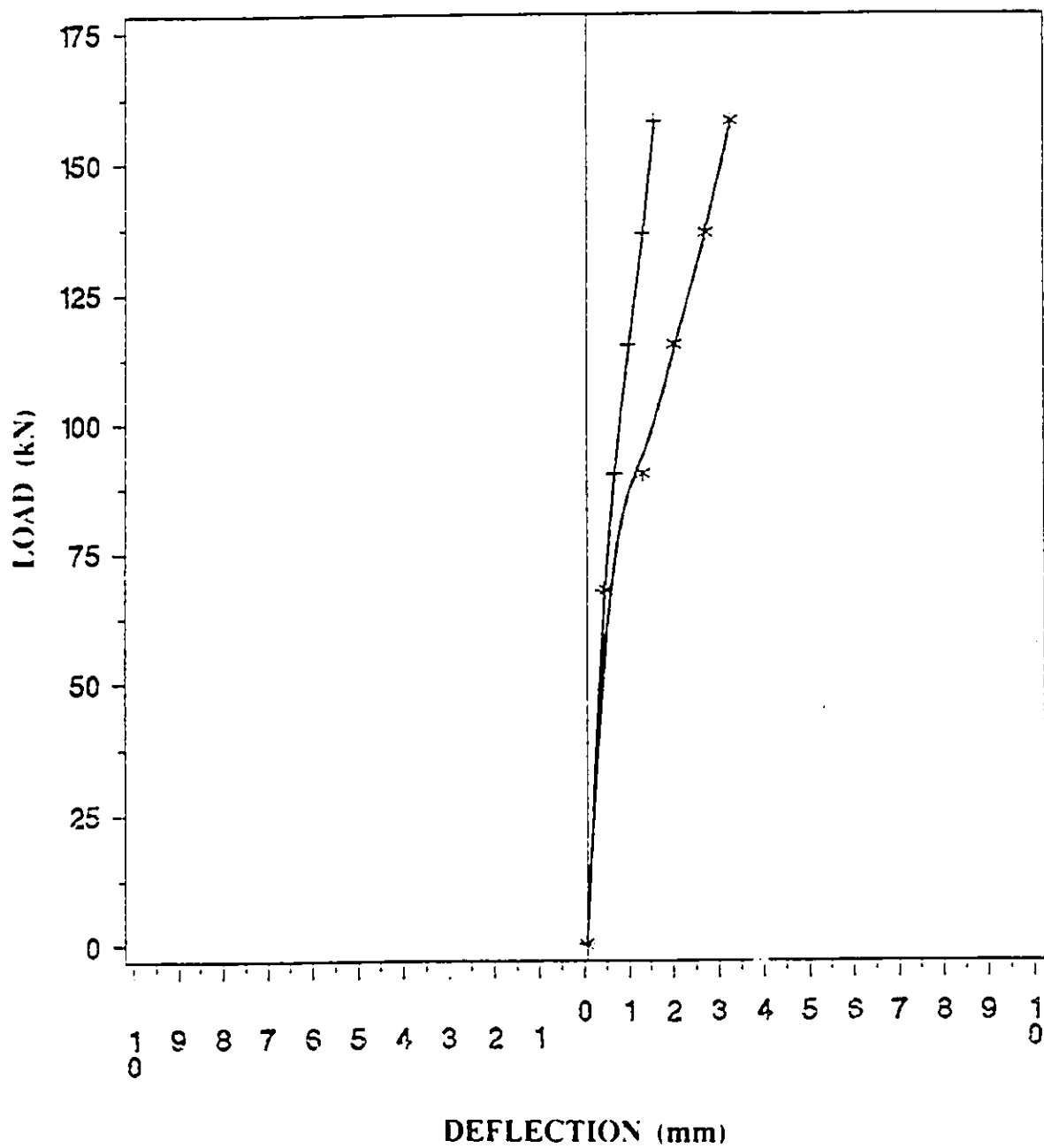


Fig.A.5a

LOAD vs SURFACE STRAIN, SPECIMEN S5 - 5/16 - 1



LEGEND

x x x U-U DEFLECTION

+ + + V-V DEFLECTION

Fig.A.5b

LOAD vs DEFLECTION, SPECIMEN S5 - 5/16 - 1

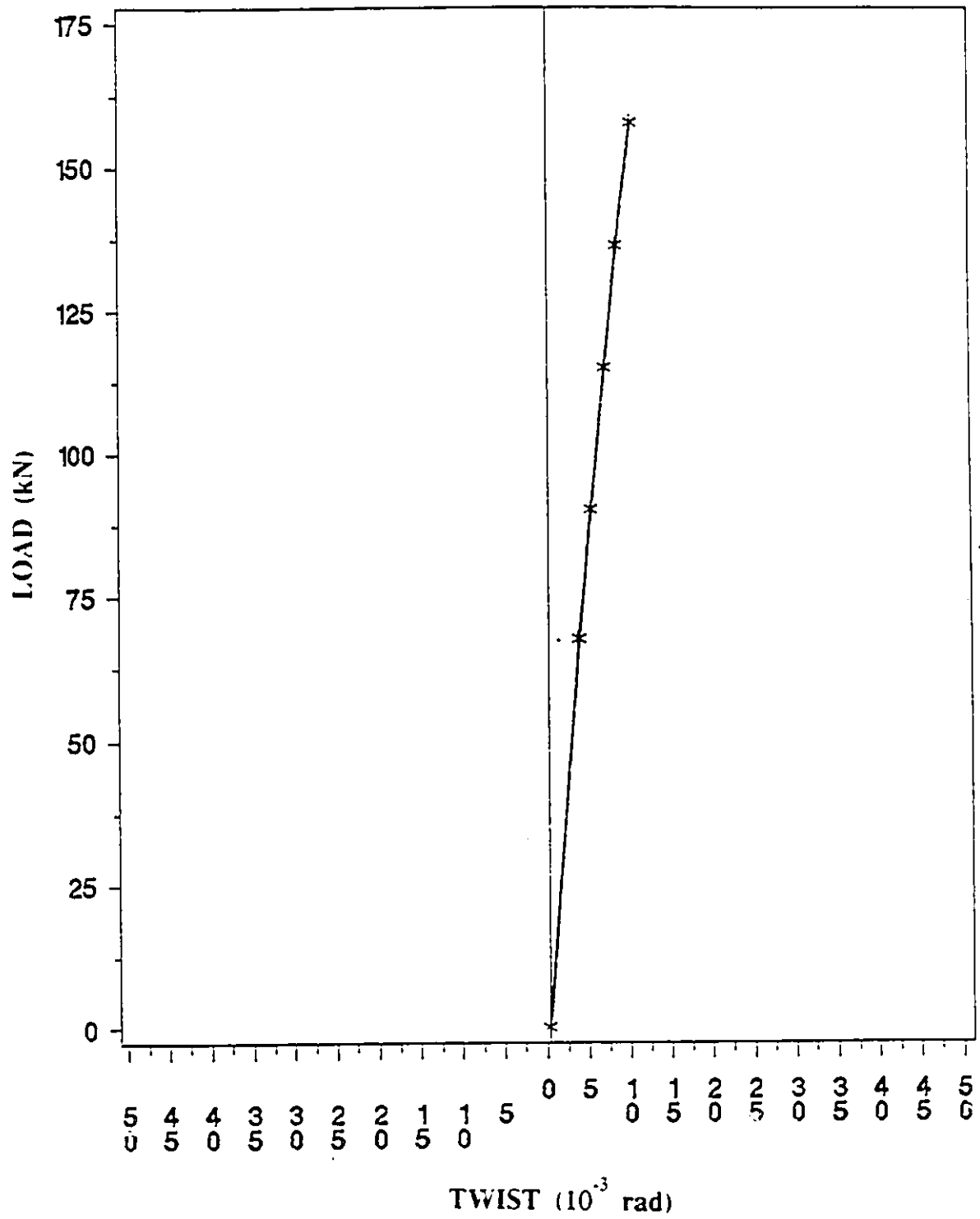


Fig.A.5c

LOAD vs MID-HEIGHT TWIST, SPECIMEN S5 - 5/16 - 1

Appendix B
COMPUTER PROGRAM TO CALCULATE
CROSS-SECTIONAL PROPERTIES
OF SCHIFFLERIZED ANGLES

PAGE 00001

FILE: B1 FORTRAN A1 UNIVERSITY OF MINNESOTA

```

.....
PROGRAM TO COMPUTE SECTION PROPERTIES FOR C-DEGS. SUBPROGRAMS:
.....
DEF-ROLL-ANGLE
.....
M=NOMINAL LEG WIDTH + TERMINAL LEG THICKNESS
.....
A=NOMINAL WIDTH OF UNSCHIFFERED STRAIGHT PORTION
.....
RHO= ROOT RADIUS OF THE ANGLE
.....
AL=EFFECTIVE LENGTH OF THE MEMBER
.....
THETA=ANGLE OF SCHIFFERATION = 15 DEGREES
.....
CC
FOR EXPLANATIONS, SEE PROGRAM IN APPENDIX C
PROGRAM PROPT
REAL SLAB,SLAB2,SLABH,SLABDAE
CHARACTER*12 SPECT
CHARACTER*20 PR(40)
DIMENSION COOR(500,3),WD(20),TD(20),AD(20),ALD(20),NJ(19)
DIMENSION ASCE(8),ATSC(8),CSA(8),RS(8,2),ECCS(8,2),S(40,40)
DIMENSION MORITISH(13,3),TDRTISH(13),ABRIVISH(13)
DIMENSION WJUNITS(13,3),TJUNITS(13),ASJUNITS(13)
DATA LTR,LOUT,PI,THETA/5.6,3.141592654,15.0/
DATA ((MORITISH(I,J),J=1,3),I=1,13)/65.125,1/
DATA NJ/1,9,17,337,169,161,329,321/
DATA (PR(I),I=1,22)/LOG width (mm),a (mm),b (mm),c (mm),
  1,c (mm),Area (mm**2),
  1,up (mm),I-min 10**6(mm**4),I-min 10**6(mm**4),
  1,I-up 10**6(mm**4),I-up 10**6(mm**4),R-u (mm),
  1,I 10**6(mm**4),C-u 10**6(mm**4),R-v (mm),
  1,R-v (mm),R-q (mm),
  1,R-q (mm),Length (mm),
  1,Sleakness KL/r,Non-Dim. KL/r,Yield stress MPa,
  1,Young's Mod. GPa,Ultimate kN/
.....
THETA=45.
THETA=0.0    : TEST CASE FOR REGULAR ANGLES
E=29.0E+06
G=E/2.6
DO 10 I=1,500
  DO 10 J=1,3
    COOR(I,J)=0.0
  THETA=PI*THETA/180.0
  READ(11,*,N,E,AMU,AL
  G=E/(2.0*(1.0+AMU))
  DO 200 DMCH=1,N
    READ(11,*,J,1,A,r,FIELD,PHO,PTEST,SPECT
    PT)=PT*51*10**3.
  RHO=T
  B*W-A
  AT=A-T/2.0
  AREA=2.0*PT*(AT+B)
  G=(AT*AT+2.0*B*(AT+B)+B*(COS(THETA)+SIN(THETA)))/(4.0*(AT+B))

```


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FILE: D1 FORTRAN A3 UNIVERSITY OF WISCONSIN

```

      S(1,16)=0.0
      S(1,17)=AL
      S(1,18)=AL/100
      S(1,19)=AL/(RV*PI)*SQRT(YIELD/E)
      S(1,20)=YIELD
      S(1,21)=E/1000.
      S(1,22)=E*PI*17/1000.

2000  CONTINUE
      WRITE(IOUT,3020)
3020  FORMAT(28X,'TABLE 5.1/4X,'PROPERTIES OF TEST SPECIMENS',
      *,'NOMINAL SIZE : 5x5x5/16 IN.','PROPERTY',10X,'NOMINAL',
      *,' SECTION-1    SECTION-2    SECTION-3'/65('---'))

      DO 3010 J=1,7
3010  WRITE(IOUT,3000)PP(J),(S(I,J),I=1,4)
      DO 3050 J=8,12
3050  WRITE(IOUT,3030)PP(J),(S(I,J),I=1,4)
      DO 3040 J=13,17
3040  WRITE(IOUT,3000)PP(J),(S(I,J),I=1,4)
      WRITE(IOUT,3060)
3060  FORMAT(65('---'))    * For explanations ref. Fig.1.6 and NOTATION
3030  FORMAT(A19,1X,4(F9.3,3X))
3000  FORMAT(A19,1X,4(F7.1,3X))
      STOP
      END

```

Appendix C
COMPUTER PROGRAM TO CALCULATE ULTIMATE
LOADS
ACCORDING TO DIFFERENT STANDARD
SPECIFICATIONS

-

FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

.....
** PROGRAM TO COMPUTE ULTIMATE STRENGTHS AS PER VARIOUS CODES
** HOT-ROLLED SHIPPLERIZED ANGLES UNDER CONCENTRIC LOAD
** FLEXURAL AND TORSIONAL-FLEXURAL BUCKLING LOADS
** W-LEG WIDTH * T-LEG THICKNESS
** A-NOMINAL WIDTH OF UNSHIPPLERIZED STRAIGHT PORTION
** RHO=ROOT RADIUS OF THE ANGLE
** AL=EFFECTIVE LENGTH OF THE MEMBER
** THETA=ANGLE OF SHIPPLERIZATION = 15 DEGREES
** CODES=TAG FOR DIFFERENT STANDARD SPECIFICATIONS
** SLAM=SLENDERNESS RATIOS FOR DIFFERENT CASES
.....

```

```

PROGRAM PROPT
REAL SLAM,SLAM2,SLAMR,SLAMDAE
CHARACTER*12 SPECI
CHARACTER*20 CODES(10),CODE,NOMINAL(2)
DIMENSION COOR(500,3),WD(20),TD(20),AB(20),ALR(20),NJ(9)
DIMENSION ASCE(8),AISC(8),CSA(8),BS(8),ECCS(8),FACTR(80)
DATA LIN,LOUT,PL,THETA/5,6,3,141592654,15.0/
DATA NJ/1,9,17,337,169,161,329,321/
DATA CODES(1)/'CAN/CSA-S37-M86'/
DATA CODES(2)/'ASCE-MANUAL 52-1988'/
DATA CODES(3)/'AISC-LRPD-1986'/
DATA CODES(4)/'BS 5960:PART 1:1985'/
DATA CODES(5)/'ECCS - 1985'/
DATA CODES(6)/'BS 5960:PART 1:1985'/
DATA CODES(7)/'ECCS - 1985'/
DATA NOMINAL/'actual','nominal'/

```

C THETA=0.0 : TEST CASE FOR REGULAR ANGLES

```

**
DO 10 I=1,500
DO 10 J=1,3
10 COOR(I,J)=0.0
THETA=PI*THETA/180.0

```

```

** READ(LIN,*)N,E,AMU,AL,PHI,KODE,KNOHINA,ITABLE
** N=NO. OF MEMBERS
** E=YOUNG'S MODULUS
** AMU=POISSON'S RATIO
** AL=LENGTH OF MEMBERS
** KODE=SPECIFICATION NUMBER (IN THE ORDER OF DATA STATEMENT)
** ITABLE=TABLE NUMBER IN THE HEADING
** IF(KNOHINA.EQ.2)READ(LIN,20)
20 FORMAT(17(/))
CODES=CODES(KODE)
WRITE(IOUT,3070)ITABLE,CODE,NOMINAL(KNOHINA),PHI
3070 FORMAT(2,0*(1,0,A40))

```


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FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

..      AJ=2.0*(W-T/2.0)*T*T/3.0
..      GAMA=WARPING CONSTANT
..      GAMA=AREA*AREA/144.0
..      RHIN2= SQUARE OF MINIMUM RADIUS OF GYRATION
..      RHIN2=AIMIN/AREA
..      RHAX2= SQUARE OF MAXIMUM RADIUS OF GYRATION
..      RHAX2=AIMAX/AREA
..      ALPH= SLENDERNESS RATIO
..      ALPH=AL/SORT(RHIN2)
..      RP2=AIP/AREA
..      RZIN= SORT(RHIN2)
..      R=SHAPE FACTOR
..      R=1.0-Y02/RP2
..      RPHI2= SQUARE OF RADIUS OF GYRATION IN TORSIONAL MODE
..      RPHI2=AL*AL*G*AJ/(PI*PI*E*AIP)*GAMA/AIP
..      RZ= EQUIVALENT RADIUS OF GYRATION IN TORSIONAL-FLEXURAL MODE
..      RZ=(RHAX2+RPHI2-SORT((RHAX2+RPHI2)*2-4.*R*RHAX2+RPHI2))
..      RZ2=RZ2/(2.0*R)
..      RU= SORT(RHAX2)
..      RV= SORT(RHIN2)
..      RPHI= SORT(RPHI2)
..      RZ= SORT(RZ2)

..      PX= CRITICAL BUCKLING LOAD ABOUT MINOR AXIS
..      PY= CRITICAL LOAD - BUCKLING ABOUT MAJOR AXIS
..      PE= CRITICAL LOAD - BUCKLING ABOUT MINOR AXIS
..      PC= PI*PI*E*AIMIN/(AL*AL)
..      PY= PI*PI*E*AIMAX/(AL*AL)
..      PE= PI*PI*E*AREA*RE2/(AL*AL)
..      fact=(AIMIN*AIMAX)/AIP
..      :WRITE(100,1100)W,W*fact,ho,yo,yo*al
..      FORMAT(1X,' actual size',
..      . 17.3,'x',17.3,'x',16.3/1X,'failot radius = ',17.3/,'Yield stress',
..      . 169.4,' LENGTH = ',79.3)

1100

..      PY=YIELD
..      SLAH= NON-DIMENSIONAL COLUMN SLENDERNESS PARAMETER
..      SLAH=AL*SORT(PY/(PI*PI*E*RHIN2))
..      SLAH2=SLAH*SLAH

..      PHI=1.0
..      CAN3=S16.1-NB4 CLAUSE 13.3.1
..      PHI= RESISTANCE FACTOR
..      C= PD/AREA*PY
..      IF(0.0.LE.SLAH.AND.SLAH.LE.9.15)C=C1
..      IF(0.15.LT.SLAH.AND.SLAH.LE.1.1)C=C1*(1.035-.202*SLAH-.222*SLAH2)
..      IF(1.1.LT.SLAH.AND.SLAH.LE.2.1)C=C1*(-.111+.636/SLAH+.087/SLAH2)
..      IF(2.0.LT.SLAH.AND.SLAH.LE.3.6)C=C1*(0.009+0.877/SLAH2)
..      IF(3.6.LT.SLAH)C=C1/SLAH2
..      :WRITE(100,1200)C1

```

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FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

1200  FORMAT(5X,'CAN3-S16.1-H84 CLAUSE 11.3.1  C1= ',F12.5)
      PROPOSED REVISION FOR CSA S37-H86, PARAGRAPH 6.2.5
      WD=W-A
      IF(WB/T.LE.200/SQRT(YIELD)) THEN
        YCI=YIELD
      ELSE IF(WB/T.LE.380/SQRT(YIELD)) THEN
        YCI=YIELD*(1.677-0.677*(WB/T)/(200/SQRT(YIELD)))
      ELSE
        YCI=56415/(WB/T)**2
      END IF
      SLAM=AL*SQRT(YCI/(PI*PI*E*RHIN2))
      SLAM2=SLAM*SLAM
      CI=PHI*AREA*YCI
      IF(0.0.LE.SLAM.AND.SLAM.LE.0.15)CI=CI
      IF(0.15.LT.SLAM.AND.SLAM.LE.1.)CI=CI*(1.035-.202*SLAM-.222*SLAM2)
      IF(1.0.LT.SLAM.AND.SLAM.LE.2.)CI=CI*(-.111+.636/SLAM+.087/SLAM2)
      IF(2.0.LT.SLAM.AND.SLAM.LE.3.6)CI=CI*(0.009+0.877/SLAM2)
      IF(3.6.LE.SLAM)CI=CI/SLAM2
      CSA(1)=CI
      CSA(2)=PI*TEST/CI
      WRITE(1000,1300)WB,CI
1300  FORMAT(5X,'CSA-S37-H86 REV. REND WIDTH W = ',F7.3,' C1= ',F12.5)
      ..
      ..
      WD=W-RHO-T
      IF(WB/T.LE.200/SQRT(YIELD)) THEN
        YCI=YIELD
      ELSE IF(WB/T.LE.380/SQRT(YIELD)) THEN
        YCI=YIELD*(1.677-0.677*(WB/T)/(200/SQRT(YIELD)))
      ELSE
        YCI=56415/(WB/T)**2
      END IF
      SLAM=AL*SQRT(YCI/(PI*PI*E*RHIN2))
      SLAM2=SLAM*SLAM
      CI=PHI*AREA*YCI
      IF(0.0.LE.SLAM.AND.SLAM.LE.0.15)CI=CI
      IF(0.15.LT.SLAM.AND.SLAM.LE.1.)CI=CI*(1.035-.202*SLAM-.222*SLAM2)
      IF(1.0.LT.SLAM.AND.SLAM.LE.2.)CI=CI*(-.111+.636/SLAM+.087/SLAM2)
      IF(2.0.LT.SLAM.AND.SLAM.LE.3.6)CI=CI*(0.009+0.877/SLAM2)
      IF(3.6.LE.SLAM)CI=CI/SLAM2
      CSA(3)=CI
      CSA(4)=PI*TEST/CI
      WRITE(1000,1400)WB,CI
1400  FORMAT(5X,'CSA-S37-H86 REV. FILLFT W111 W = ',F7.3,' C1= ',F12.5)
      ..
      ..
      WD=W-T
      IF(WB/T.LE.200/SQRT(YIELD)) THEN
        YCI=YIELD
      ELSE IF(WB/T.LE.380/SQRT(YIELD)) THEN

```


FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

PCT=YIELD*(1.677-0.677*(WB/T)/(200/SORT(YIELD)))
ELSE
PCT=56415/(WB/T)**2
END IF
SLAH=AL*SQRT(PCT/(PI*PI*2*RHIN2))
SLAH2=SLAH*SLAH
CF=PHI*AREA*PCT
IF(0.0.LE.SLAH.AND.SLAH.LE.0.15)CF=CF
IF(0.15.LT.SLAH.AND.SLAH.LE.1.1)CF=CF*(1.035-.202*SLAH-.222*SLAH2)
IF(1.1.LT.SLAH.AND.SLAH.LE.2.1)CF=CF*(-.111+.636/SLAH+.087/SLAH2)
IF(2.0.LT.SLAH.AND.SLAH.LE.3.6)CF=CF*(0.009+0.877/SLAH2)
IF(3.6.LE.SLAH)CF=CF/SLAH2
CSA(5)=CF
CSA(6)=PTEST/CR
WRITE(IOUT,1450)W,CF
FORMAT(5X,'CSA-537-H86 REV. A+B-15/0 = .07+3.0 CF= ',E12.5)

```

1450

..
..

```

WB=W
IF(WB/T.LE.200/SORT(YIELD)) THEN
PCT=YIELD
ELSE IF(WB/T.LE.380/SORT(YIELD)) THEN
PCT=YIELD*(1.677-0.677*(WB/T)/(200/SORT(YIELD)))
ELSE
PCT=56415/(WB/T)**2
END IF
SLAH=AL*SQRT(PCT/(PI*PI*2*RHIN2))
SLAH2=SLAH*SLAH
CF=PHI*AREA*PCT
IF(0.0.LE.SLAH.AND.SLAH.LE.0.15)CF=CF
IF(0.15.LT.SLAH.AND.SLAH.LE.1.1)CF=CF*(1.035-.202*SLAH-.222*SLAH2)
IF(1.1.LT.SLAH.AND.SLAH.LE.2.1)CF=CF*(-.111+.636/SLAH+.087/SLAH2)
IF(2.0.LT.SLAH.AND.SLAH.LE.3.6)CF=CF*(0.009+0.877/SLAH2)
IF(3.6.LE.SLAH)CF=CF/SLAH2
CSA(7)=CF
CSA(8)=PTEST/CR
WRITE(IOUT,1500)C1
FORMAT(5X,'CSA-537-H86 REVISION W= NOMINAL LRG WIDTH,CF= ',E12.5)

```

1500

..
..
..
..
C

```

AISC - LRFD 1986
PHI=1.0
SLAH=76./SQRT(YIELD/6.8)4757)
WB=W-A
WBYT=WB/T
IF(WBYT.LT.SLAH) THEN
Q=1.0
ELSE IF(SLAH.LE.WBYT.AND.WBYT.LE.1.55*SLAH/7.0) THEN
Q=1.00+0.0047*WBYT*SQRT(YIELD/6.8)4757)

```

156

FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

ELSE
  Q=15500/(YIELD*WBYT*WBYT/6.894757)
ENDIF
PY=YIELD/6.894757
SLAM=AL*SQRT(PY*6.894757/(PI*PI*E))/SQRT(RMIN2)
SLAM2=SLAM*SLAM
IF(SLAM.LE.1.5)FCF=(0.658**((SLAM2*Q)))*PY*Q
IF(SLAM.GT.1.5)FCF=0.877*PY/SLAM2
PNO=PIJ*AREA*FCF
SLAMDBAE=SQRT(AREA*YIELD/PE)
SLAMQ=SLAMDBAE*SQRT(Q)
IF(SLAMQ.LE.1.5)FCF=(0.658**((SLAMQ*SLAMQ)))*PY*Q
IF(SLAMQ.GT.1.5)FCF=0.877*PY*Q/(SLAMQ*SLAMQ)
Pphi=PHI*AREA*FCF
CR=6.894757*AMIN1(PNO,Pphi)
AISC(1)=CR
AISC(2)=PTEST/CR
WRITE(IOUT,1600)WB,CT,PNE,Pphi
FORMAT(1X,'AISC-LRFD186 PLAT W=',F1.3,' CT=',F12.4,E12.4,F12.0)
1600
..
..
C
PHI=1.0
SLAMR=76./SQRT(YIELD/6.894757)
W=M-T-RUB
WBYT=WBYT
IF(WBYT.LT.SLAMR) THEN
  Q=1.0
ELSE IF(SLAMR.LE.WBYT.AND.WBYT.LT.155*SLAMR/76) THEN
  Q=1.340-0.00447*WBYT*SQRT(YIELD/6.894757)
ELSE
  Q=15500/(YIELD*WBYT*WBYT/6.894757)
ENDIF
PY=YIELD/6.894757
SLAM=AL*SQRT(PY*6.894757/(PI*PI*E*RMIN2))
SLAM2=SLAM*SLAM
IF(WBYT.LT.LE.76/SQRT(PY)) THEN
  IF(SLAM.LE.1.5)FCF=(0.658**SLAM2)*PY
  IF(SLAM.GT.1.5)FCF=0.877*PY/SLAM2
ELSE IF(SLAM.LE.1.5) THEN
  FCF=(0.658**SLAM2*Q)*PY
ELSE
  FCF=(0.877*PY)/SLAM2
ENDIF
PNO=PIJ*AREA*FCF
SLAMDBAE=SQRT(AREA*YIELD/PE)
SLAMQ=SLAMDBAE*SQRT(Q)
IF(SLAMQ.LE.1.5)FCF=(0.658**((SLAMQ*SLAMQ)))*PY*Q
IF(SLAMQ.GT.1.5)FCF=0.877*PY*Q/(SLAMQ*SLAMQ)
Pphi=PHI*AREA*FCF

```

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FILZ: C1 PORTAM A1 UNIVERSITY OF WINDSOR

```

C1=0.894757*AMINI(PNO,PUPH1)
AISC(3)=CR
AISC(4)=PTEST/CR
WRITE(100,1600)WB,CR,PMB,PMPI
1610  FORMAT(1X,'AISC-LRPD1986 FLAT W=',P7.3,' CR=',E12.4,E12.4,E12.4)
      ..
      C
      PHI=1.0
      SLAMR=76./SQRT(YIELD/6.894757)
      WB=M-T
      WBYT=WB/T
      IF(WBYT.LT.SLAMR) THEN
        Q=1.0
      ELSE IF(SLAMR.LE.WBYT.AND.WBYT.LT.155*SLAMR/76) THEN
        Q=1.340-0.00447*WBYT*SQRT(YIELD/6.894757)
      ELSE
        Q=15500/(YIELD*WBYT*WBYT/6.894757)
      ENDIF
      PY=YIELD*Q/6.894757
      SLAM=AL*SQRT(PY*6.894757/(PI*PI*E*MIN2))
      SLAM2=SLAM*SLAM
      IF(SLAM.LE.1.5)YCT=(0.658**SLAM2)*PY
      IF(SLAM.GT.1.5)YCT=0.877*PY/SLAM2
      PPH1=PHI*AREA*YCT
      SLAMDAE=SQRT(AREA*YIELD/E)
      SLAMQ=SLAMDAE*SQRT(Q)
      IF(SLAMQ.LE.1.5)FCT=(0.658**(.SLAMQ*SLAMQ))*PY
      IF(SLAMQ.GT.1.5)FCT=0.877*PY/(SLAMQ*SLAMQ)
      PPH1=PHI*AREA*FCT
      CR=6.894757*AMINI(PNO,PUPH1)
      AISC(5)=CR
      AISC(6)=PTEST/CR
      WRITE(100,1620)WB,CR,PMB,PMPI
1620  FORMAT(1X,'AISC-LRPD1986 FLAT W=',P7.3,' CR=',E12.4,E12.4,E12.4)
      ..
      C
      PHI=1.0
      SLAMR=76./SQRT(YIELD/6.894757)
      WB=M
      WBYT=WB/T
      IF(WBYT.LT.SLAMR) THEN
        Q=1.0
      ELSE IF(SLAMR.LE.WBYT.AND.WBYT.LT.155*SLAMR/76) THEN
        Q=1.340-0.00447*WBYT*SQRT(YIELD/6.894757)
      ELSE
        Q=15500/(YIELD*WBYT*WBYT/6.894757)
      ENDIF
      PY=YIELD*Q/6.894757
      SLAM=AL*SQRT(PY*6.894757/(PI*PI*E*MIN2))
      SLAM2=SLAM*SLAM

```

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FILE: C1 PORTHAM A1 UNIVERSITY OF WINDSOR

```

IF(SLAW.LE.1.5)FCF=(0.654*(SLAM2))*FY
IF(SLAW.GT.1.5)FCF=0.877*FY/SLAM2
PWA=PHI*AREA*FCF
SLABDAZ=SQRT(AREA*YIELD/PE)
SLAM0=SLABDAZ*SQRT(0)
IF(SLAW.LE.1.5)FCF=(0.658*((SLAM0*SLAM0))*FY
IF(SLAW.GT.1.5)FCF=0.877*FY/(SLAM0*SLAM0)
PWA=PHI*AREA*FCF
CT=6.894757*AHIN1(PWA*PWA)
AISC(7)=CR
AISC(8)=PTEST/CR
WRITE(100,1630)WB,CT,PWZ,PWPHI
FORMAT(1X,'AISC-LRPD1986 FLAT W= ',F7.3,' CR= ',E12.4,E12.4,E12.4)
1630
..
..
..
..
ASCE MANUAL # 52
FY=YIELD/6.894757
WB=W-A
WYT=WB/T
WTLH=80/SQRT(FY)
IF(WBT.LT.WTLH) THEN
PCR=PY
ELSE IF(WBT.LE.144/SQRT(FY)) THEN
PCR=FY*(1.677-0.677*WYT/WTLH)
ELSE
PCR=3500/WYT**2
ENDIF
CC=PI*SQRT(2.0*E/6.0)4757/FY
WHIN=SQRT(RMIN2)/25.4
IF((AL/25.4/RHIN).LE.CC)FI=PCR*(1.0-0.5*(AL/25.4/RHIN/CC)**2)
IF((AL/25.4/RHIN).GT.CC)FI=29000/(AL/25.4/RHIN)**2
PCR=FA*AREA*6.894757
ASCE(1)=PCR
ASCE(2)=PTEST/PCR
WRITE(100,1700)WB,PCR
FORMAT(1X,'ASCE MANUAL #52 FLAT W= ',F7.3,' PCR = ',E12.4)
1700
..
..
FY=YIELD/6.894757
WB=W-RHO-T
WYT=WB/T
WTLH=80/SQRT(FY)
IF(WBT.LT.WTLH) THEN
PCR=PY
ELSE IF(WBT.LE.144/SQRT(FY)) THEN
PCR=FY*(1.677-0.677*WYT/WTLH)
ELSE
PCR=3500/WYT**2
ENDIF

```

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FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

CC=PI*SQRT(2.0*E/6.894757/FY)
RHIN=SQRT(RHIN2)/25.4
IF((CAL/25.4/RHIN).LE.CC)FA=PCR*(1.0-0.5*(AL/25.4/RHIN/CC)**2)
IF((AL/25.4/RHIN).GT.CC)FA=286000/(AL/25.4/RHIN)**2
PCR=FA*AREA*6.894757

```

```

ASCP(3)=PCR
ASCE(4)=PTEST/PCR
WRITE(IOUT,1710)WB,PCR
FORMAT(1X,'ASCE MANUAL #52 PLAT W = ',F7.3,' PCR = ',F12.4)

```

```

1710
..
..

```

```

PY=YIELD/6.894757
WB=W-T
WBY=WB/T
WTLN=80/SORT(FY)
IF(WBYT.LT.WTLN) THEN
  PCR=PY
ELSE IF(WBYT.LE.144/SORT(FY)) THEN
  PCR=PY*(1.677-0.677*WBYT/WTLN)
ELSE
  PCR=9500/WBYT**2
ENDIF
CC=PI*SQRT(2.0*E/6.894757/FY)
RHIN=SQRT(RHIN2)/25.4
IF((CAL/25.4/RHIN).LE.CC)FA=PCR*(1.0-0.5*(AL/25.4/RHIN/CC)**2)
IF((AL/25.4/RHIN).GT.CC)FA=286000/(AL/25.4/RHIN)**2
PCR=FA*AREA*6.894757
ASCT(5)=PCR
ASC(6)=PTEST/PCR
WRITE(IOUT,1720)WB,PCR
FORMAT(1X,'ASCE MANUAL #52 PLAT W = ',F7.3,' PCR = ',F12.4)

```

```

1720
..
..

```

```

PY=YIELD/6.894757
WB=W
WBYT=WB/T
WTLN=80/SORT(FY)
IF(WBYT.LT.WTLN) THEN
  PCR=PY
ELSE IF(WBYT.LE.144/SORT(FY)) THEN
  PCR=PY*(1.677-0.677*WBYT/WTLN)
ELSE
  PCR=9500/WBYT**2
ENDIF
CC=PI*SQRT(2.0*E/6.894757/FY)
RHIN=SQRT(RHIN2)/25.4
IF((CAL/25.4/RHIN).LE.CC)FA=PCR*(1.0-0.5*(AL/25.4/RHIN/CC)**2)
IF((AL/25.4/RHIN).GT.CC)FA=286000/(AL/25.4/RHIN)**2
PCR=FA*AREA*6.894757
ASCE(7)=PCR

```


PAGE 00011

FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

1920      !WRITE(IOUT,1920)WBYT,WTLM,REDUCE,SLAM
      FORMAT(1X,'05 5950 : PART 1 : 199.0/10.0/1.0 *F7.3,0.0 W/T LIM. *
      * F7.3/1X,' REDUCTION FACTOR FOR COMPACT SECTION *F7.3,0.0
      * * SLENDERNESS SLAMUDA : *.P10.0)
      ..
      ..
      EPSI=SQRT(275/YIELD)
      WBI=J
      WBYT=WB/T
      WTLIM=11.5*EPSI
      REDUCE=AMIN1(11.0/((WB/T/EPST)-4),19.0/((2.0*WB/T/EPST)-4))
      REDUCE=AMIN1(1.0,REDUCE)
      SLAM=AL/RMIN
      B5(7)=SLAM
      B5(8)=REDUCE*YIELD
      !WRITE(IOUT,*)AL,RMIN,SLAM
      !WRITE(IOUT,1830)WBYT,WTLM,REDUCE,SLAM
1830      FORMAT(1X,'05 5950 : PART 1 : 1985.0/1X.0 B/T *.F7.3,0.0 B/T LIM. *
      * F7.3/1X,' REDUCTION FACTOR FOR COMPACT SECTION *F7.3,0.0
      * * SLENDERNESS SLAMUDA : *.P10.0)
      ..
      ..
      ECCS = 1985
      RMIN=SQRT(RMIN2)
      EPSI=SQRT(275/YIELD)
      WBI=J-A
      WBYT=WB/T
      WTLIM=260./SQRT(YIELD)
      WTLIM=200./SQRT(YIELD)
      IF(WBYT-L*WTLIM)THEN
        FY=YIELD
      ELSE IF(WBYT-L*WTLIM/3.0) THEN
        FY=YIELD*(2.-WBYT/WTLIM)
      ELSE
        FY=60000/(WBYT*WBYT)
      ENDIF
      ECCS(2)=FY/YIELD
      WB=W-T-RBI
      WBYT=WB/T
      WTLIM=260./SQRT(YIELD)
      WTLIM=200./SQRT(YIELD)
      IF(WBYT-L*WTLIM)THEN
        FY=YIELD
      ELSE IF(WBYT-L*WTLIM/3.0) THEN
        FY=YIELD*(2.-WBYT/WTLIM)
      ELSE
        FY=60000/(WBYT*WBYT)
      ENDIF
      ECCS(2)=FY/YIELD

```

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FILE: C1 PORTMAN AT UNIVERSITY OF WINDSOR

```

      MB=M-T
      WBYT=WB/T
      WTLH=260./SQRT(YIELD)
      WTLH=200./SORT(YIELD)
      IF(WBYT.LE.WTLH)THEN
        FY=YIELD
      ELSE IF(WBYT.LT.4.*WTLH/3.0) THEN
        FY=YIELD*(2.-WBYT/WTLH)
      ELSE
        FY=80000/(WBYT*WBYT)
      ENDIF
      ECCS(6)=FY/YIELD
      MB=M
      WBYT=WB/T
      WTLH=260./SQRT(YIELD)
      WTLH=200./SORT(YIELD)
      IF(WBYT.LE.WTLH)THEN
        FY=YIELD
      ELSE IF(WBYT.LT.4.*WTLH/3.0) THEN
        FY=YIELD*(2.-WBYT/WTLH)
      ELSE
        FY=80000/(WBYT*WBYT)
      ENDIF
      ECCS(8)=FY/YIELD

      ECCS(1)=AL*AL*JBT(FY/(PI*PI*E*RHIN2))
      ECCS(3)=AL*AL*JBT(FY/(PI*PI*E*RHIN2))
      ECCS(5)=AL*AL*JBT(FY/(PI*PI*E*RHIN2))
      ECCS(7)=AL*AL*JBT(FY/(PI*PI*E*RHIN2))
      DO 4010 I1=1,7,2
        FY=YIELD*ECCS(I1+1)
        ALAM=ECCS(I1)
        CALL ECCSV(ALAM,FY,FC,ALSA,PP)
        ECCS(I1)=PP/1000.
        ECCS(I1+1)=ECCS(I1)*1000./PTST
4010  CONTINUE
      DO 4020 I1=1,7,2
        ALAM=ECCS(I1)
        FY=ECCS(I1+1)
        CALL BSV(ALAM,FY,FC,AREA,PP)
        RS(I1)=PP/1000.
        RS(I1+1)=RS(I1)*1000./PTST
4020  CONTINUE
      DO 4030 I1=1,7,2
        CSA(I1)=CSA(I1)/1000.
        CSA(I1+1)=1/CSA(I1+1)
4030  CONTINUE
      DO 3005 I1=1,7,2
        ALAM(I1)=ALAM(I1)/1000.
        ALAM(I1)=ALAM(I1)/1.

```


[illegible]

F FILE: C1 FORTRAN A1 UNIVERSITY OF WINDSOR

```

      . 4431.,4426.,4372.,4319.,4266.,4215.,4164.,4113.,4062.,4011,
      . 3960.,3909.,3858.,3807.,3756.,3705.,3654.,3603.,3552.,3501.,3450.,
      . 3399.,3348.,3297.,3246.,3195.,3144.,3093.,3042.,2991.,2940.,2889.,
      . 2838.,2787.,2736.,2685.,2634.,2583.,2532.,2481.,2430.,2379.,
      . 2328.,2277.,2226.,2175.,2124.,2073.,2022.,1971.,1920.,1869.,
      . 1818.,1767.,1716.,1665.,1614.,1563.,1512.,1461.,1410.,1359.,
      . 1308.,1257.,1206.,1155.,1104.,1053.,1002.,951.,900.,849.,800.,
      . 748.,697.,646.,595.,544.,493.,442.,391.,340.,289.,238.,187.,136.,
      . 85.,34.,23.,12.,1.,110/

```

```

      DATA (ECCSL(I),I=1,110)/
      . 0.60,0.61,0.62,0.63,0.64,0.65,0.66,0.67,0.68,0.69,
      . 0.70,0.71,0.72,0.73,0.74,0.75,0.76,0.77,0.78,0.79,
      . 0.80,0.81,0.82,0.83,0.84,0.85,0.86,0.87,0.88,0.89,
      . 0.90,0.91,0.92,0.93,0.94,0.95,0.96,0.97,0.98,0.99,
      . 1.00,1.01,1.02,1.03,1.04,1.05,1.06,1.07,1.08,1.09,
      . 1.10,1.11,1.12,1.13,1.14,1.15,1.16,1.17,1.18,1.19,
      . 1.20,1.21,1.22,1.23,1.24,1.25,1.26,1.27,1.28,1.29,
      . 1.30,1.31,1.32,1.33,1.34,1.35,1.36,1.37,1.38,1.39,
      . 1.40,1.41,1.42,1.43,1.44,1.45,1.46,1.47,1.48,1.49,
      . 1.50,1.51,1.52,1.53,1.54,1.55,1.56,1.57,1.58,1.59,
      . 1.60,1.61,1.62,1.63,1.64,1.65,1.66,1.67,1.68,1.69/

```

```

      RETURN
      END

```

```

CC
**
**
**

```

```

      SUBROUTINE BSV(ALAM,PY,PC,AREA,P)
      ROUTINE TO CALCULATE PC AS PER BS : 5950, TABLE 27C
      block data supplies Perry-Robertson formula values
      DIMENSION DST(16,100),BSLAM(100),BSPY(16),ECCSL(300),ECCST(300)
      COMMON/CODETAN/DST,BSLAM,BSPY,ECCSL,ECCST,MXBS,NYBS,NPCCS

```

```

      IX=NXUS
      IY=NYBS

```

```

      IV1=0
      IX1=0

```

```

      IF(ALAM.LT.BSLAM(1))THEN
      IV1=1

```

```

      ELSE IF(ALAM.LE.BSLAM(IV1)) THEN
      DO 100 I=1,IV

```

```

      IF(IV1.EQ.0.AND.ALAM.LE.BSLAM(I))THEN
      IV1=I

```

```

      ENDIF
      100 CONTINUE

```

```

      ELSE
      IV1=IV

```

```

      ENDIF
      IF(PY.LE.BSPY(1))THEN

```

```

      IX1=1
      ELSE IF(PY.LE.BSPY(IX1))THEN

```

```

      DO 200 I=1,IX
      IF(PY.LE.BSPY(I).AND.IX1.EQ.0)THEN

```

```

      IX1=I-1
      ENDIF

```

```

      200 CONTINUE
      ELSE

```

FILE: C1 PORTMAN A1 UNIVERSITY OF WINDSOR

```

IX1=IX
ENDIF
IF(IX1.NE.IX) THEN
PC=BST(IX1+1,IV1)
ELSE
PC=BST(IX1,IV1)
ENDIF
P=PC*AREA
RETURN
END

SUBROUTINE ECCSV(ALAM,PY,PC,AREA,P)
ROUTINE TO COMPUTE P AS PER ECCS RECOMMENDATIONS
BLOCK DATA SUPPLIES TABLE VALUES FROM THE NON-DIMENSIONAL COLUMN
BUCKLING CURVE FROM ECCS RECOMMENDATIONS
DIMENSION BST(16,100),BSLAM(100),BSPY(16),ECCSL(300),ECCST(300)
COMMON/COUETAB/BST,BSLAM,BSPY,ECCSL,ECCST,NXHS,NVBS,NECCS
IN1=0
IF(ALAM.LT.ECCSL(1)) THEN
IN1=1
ELSE IF(ALAM.LE.ECCSL(NECCS)) THEN
DO 100 I=1,NECCS
IF(ALAM.LE.ECCSL(I).AND.IN1.EQ.0) THEN
IN1=I
ENDIF
100 CONTINUE
ELSE
IN1=NECCS
ENDIF
FACT=ECCST(IN1)
PC=PY*FACT
P=AREA*PC
RETURN
END

```

Appendix D
TYPICAL FINITE ELEMENT MODEL FOR
SCHIFFLERIZED ANGLES
USING ABAQUS

ABAQUS

THIS PROGRAM HAS BEEN DEVELOPED BY

HIBBITT, KARLSSON AND SORENSEN, INC.
100 MEDWAY STREET
PROVIDENCE, R.I. 02906

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SUPERVISION AND CONTROL OF THE DESIGNATED USER.
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PAYMENT OF A MONTHLY CHARGE. ASSISTANCE AND
OTHER INFORMATION MAY BE OBTAINED FROM THE
DESIGNATED USER.

FOR ASSISTANCE OR ANY OTHER INFORMATION CALL
901-861-0920

NOTICE

THIS IS ABAQUS VERSION 4-7.

SOME INPUT DATA OPTIONS AND USER SUBROUTINE INTERFACES
ARE INCOMPATIBLE WITH VERSION 4-5.

PLEASE MAKE SURE YOU ARE USING VERSION
4-6 OR 4-7 MANUALS.

ABAQUS PRODUCTION VERSION 4-7-22 DATE MAY 90 TIME 17:26:15 PAGE 2
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

•PREPRINT,ECHO=YES,MODEL=YES,HISTORY=YES

ABBAQUS INPUT ECHO

[illegible]

HEADING

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING
60 DEG. 4x4x1/4" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 4x4x1/4" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING
60 DEG. 3-5x3-5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 3-5x3-5x5/16" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING
60 DEG. 3x3x3/8" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 3x3x3/8" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING
60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING
60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-FLEXURAL BUCKLING

SCHIFFERLISED 60-DEG. HOT ROLLED ANGLE - 65x125" long
modelled with 8-node rectangular shell elements (curves at root and toe neglected). Constant element thickness = log thickness of the element. Length of unbut original 90-deg. angle taken as per industry standards.

Residual stress patterns are taken from ECCS recommendations. Through the thickness variation is estimated as Poissons ratio times the superposition of full section plastic stress and full section elastic unloading stress around the bend line of schiffelisation. The residual stresses are input as initial stresses through user defined subroutine SIGINI. All residual stress is given at the Gauss integration points.

boundary conditions : the top and bottom centric points are prevented from lateral translation and twisting rotation along the member axis. loading : the member is loaded concentrically at section centric point located an end plate.

Initial out of straightness : the member buckling is achieved through usage of a nonlinear geometry option. For this to function, an initial crookedness in the geometry is introduced through triquet loads.

••• DATACHECK

.....

• 2002 •

•NODE					
•••5x5/16"angle section					
1.	0.00000000.	101.868546000.	-65.112274200		
1.	0.00000000.	14.902277000.	-14.902277000		

	5	10	15	20	25	30	35	40	45	50	55	60
<hr/>												
	5	10	15	20	25	30	35	40	45	50	55	60

ABAQUS PRODUCTION VERSION 4-7-22
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DATE 5MAY 90

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CARD 85      5  10  15  20  25  30  35  40  45  50  55  60  65  70  75  80
** 161,      0.00000000,  75.238861100, -26.696319600
** 329,      0.00000000,  75.238861100,  26.696319600
** 321,      0.00000000, 101.935195000,  0.000000000
*****
*NGEN,NSET=D1
1,9,2
9,17,2
*NGEN,NSET=D2
161,169,2
169,177,2
*NGEN,NSET=D3
321,329,2
329,337,2
*PFILL,NSET=D4
D1,D2,4,40
*PFILL,NSET=D5
D2,D3,4,40
*HSET,NSET=BOT
D4,D5
*HSET,NSET=END1,GENERATE
0,0
*HSET,NSET=END1,GENERATE
1,17,2
17,337,40
*HSET,NSET=END2,GENERATE
10001,10017,2
10017,10337,40
*PFILL,NSET=JANGLE
END1,END2,10,1000
*****
*ELEMENT,TYPE=S8R
**ELEMENT DATA
101,1,2001,2005,5,1001,2003,1005,3
105,17,2017,2097,97,1017,2057,1097,57
*ELGEN,ELSET=ANGLE
101,5,2000,100,4,4,1
105,5,2000,100,4,80,1
*ELSET,ELSET=E1,GENERATE
1,501,100
2,502,100
*ELSET,ELSET=E2,GENERATE
3,503,100
*****
      5  10  15  20  25  30  35  40  45  50  55  60  65  70  75  80

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5      10      15      20      25      30      35      40      45      50      55      60      65      70      75      80
-----
CARD 130
4,504,100
*ELSET,ELSET=E3,GENERATE
5,505,100
6,506,100
*ELSET,ELSET=E4,GENERATE
7,507,100
8,508,100
*ELSET,ELSET=FIGURE,GENERATE
1,8,1
*ELEMENT,TYPE=S8R,ELSET=PLATE
1,1,81,85,5,41,83,45,3
*ELGEN,ELSET=PLATE
1,4,4,1,4,80,10
*ELCOPY,ELEMENT SHIFT=50,OLD SET=PLATE,NEW SET=PLATE,SHIFT MODES=10000
*****
MATERIAL,NAME=M1
*ELASTIC
**IMPERIAL UNITS 29.026 ksi
200.023,0.3000
*PLASTIC
**IMPERIAL UNITS 44.23,0.0
**5-5-16 SECTION 2% YIELD STRESS (MPa)
332.0
**4-4-1/4 SECTION 2% YIELD STRESS (MPa)
**3 1/2 - 3 1/2 - 5/16 SECTION 2% YIELD STRESS (MPa)
**369.0
**3-3-3/8 SECTION 2% YIELD STRESS (475.0MPa)
**375.0
**3-3-1/4 SECTION 2% YIELD STRESS
**363.0
MATERIAL,NAME=M2
*ELASTIC
**MATERIAL FOR END PLATES ONLY ELASTIC
200.023,0.3000
*****
BOUNDARY
169,1,4
10169,2,4
*****
**SHELL SECTION,ELSET=ANGLE,MATERIAL=M1
**5-5-16 SECTION THICKNESS (MM)
7.833333,13
**4-4-1/4 SECTION
*****

```

```

CARD 175
*****
**6.252,13
**3 1/2 - 3 1/2 - 5/16 SECTION
**8.0912,13
**3-3-3/8 SECTION
**9.02,13
**3-3-1/4 SECTION
**6.4092,13
**SHELL SECTION,ELSET=PLATE,MATERIAL=M2
150.0
*****
**INITIAL CONDITIONS, TYPE=STRESS,USER
**USER SUBROUTINES
SUBROUTINE SIGINI(SIGMA,COORDS,MTENS,NCRDS,NOEL)
CC SUBROUTINE TO DEFINE AN INITIAL STRESS FIELD
CC 60 DEGREE SCHPFLERISED ANGLE
DIMENSION SIGMA(MTENS),COORDS(NCRDS)
CC TRIAL STRESS FIELD FOR 1/4 YIELD STRESS TRIANGULAR VARIATION
CC THROUGH THE THICKNESS VARIATION INCLUDED WITH POISSONS RATIO OF 0.3
CC C-UMBENT PORTION - THICKNESS / 2 ; T-THICKNESS
CC W-TOTAL LEG WIDTH OUTER DIMENSION ; A-UMBENT PORTION
**60 DEG. 5x5x16" SPECIMEN #1 SHELL ELEMENTS-END PLATES LOAD
DATA W,A,T,YIELD/125.4125,25.0,7.8483,332.0
**60 DEG. 4x4x1/4" SPECIMEN #1 SHELL ELEMENTS-END PLATES LOAD
DATA W,A,T,YIELD/100.81,24.0,6.23,356.0
**60 DEG. 3.5x3.5x5/16" SPECIMEN #1 SHELL ELEMENTS-END PLATES LOAD
DATA W,A,T,YIELD/90.091,25.0,7.952,369.0
**60 DEG. 3x3x3/8" SPECIMEN #1 SHELL ELEMENTS-END PLATES LOAD
DATA W,A,T,YIELD/76.2,26.0,9.577,375.0
**60 DEG. 3x3x1/4" SPECIMEN #1 SHELL ELEMENTS-END PLATES LOAD
DATA W,A,T,YIELD/77.0,24.0,6.229,363.0
YIELD=375.E3
PI=3.141592654
D=W-T/2.0
B=W-A
C=A-T/2.0
IF(NOEL.LT.100) AK=0.0
IF(NOEL.LT.100) RETURN
AK=AK+1.
IF(AK.GT.13.) AK=AK-13.
X=SQRT(COORDS(3)*2+COORDS(5)*2)
IF(X.LE.C)THEN
  X=X/(B+C)
ELSE
  XX=ABS(COORDS(3))-C/SQRT(2.0)
*****
5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80

```

```

5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80
-----
YY=ABS(COORDS(5))-C/SQRT(2.0)
X=(C+SQRT(XX+YY+YY))/(B+C)
ENDIF
CARD 220 IF(X.LE.0.5) THEN
        SIGMA(1)=0.25*YIELD*(X*0.0-1.0)
      ELSE
        SIGMA(1)=0.25*YIELD*(3.0-4.0*X)
      ENDIF
CARD 225 IF(X.LT.(C+B/2)/(C+B).AND.X.GT.(C/2)/(C+B)) THEN
        IF(AK.LT.7) THEN
          SIGMA(1)=0.3*(0.5*YIELD-1.50*YIELD*(AK-1)/5)+SIGMA(1)
        ELSE IF(AK.GT.7) THEN
          SIGMA(1)=SIGMA(1)+0.3*(1.5*YIELD*(13-AK)/5-0.5*YIELD)
        ENDIF
      ENDIF
CARD 230 CC PRINT 200,NOEL,AK,(SIGMA(1),I=1,NTENS)
        FORMAT(/5X,
        ., ELEMENT NUMBER: ',I5,'POINT ',I2,/' STRESSES : ',7E13.6)
        CC PRINT 300,(COORDS(I),I=1,NCRDS)
        CC PRINT 5X,'COORDINATES : ',6E15.8)
        CC PRINT 800,(SIGMA(I),I=1,NTENS)
        CC FORMAT(/5X,'INITIAL STRESS : ',/5X,7E13.6)
        CC PRINT 900
        CC FORMAT(1X,79('...'))
        RETURN
      END
*****
•PLOT
60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
•60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-PLXURAL BUCKLING
•60 DEG. 4x4x1/4" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
•60 DEG. 4x4x1/4" SHELL ELEMENTS-END PLATES LOAD-PLXURAL BUCKLING
•60 DEG. 3.5x3.5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
•60 DEG. 3.5x3.5x5/16" SHELL ELEMENTS-END PLATES LOAD-PLXURAL BUCKLING
•60 DEG. 3x3x3/8" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
•60 DEG. 3x3x3/8" SHELL ELEMENTS-END PLATES LOAD-PLXURAL BUCKLING
•60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
•60 DEG. 3x3x1/4" SHELL ELEMENTS-END PLATES LOAD-PLXURAL BUCKLING
0
0.20, . . . , 0.05
•NOERASE
•DETAIL,ELSET=ANGLE,SECTION SCALING=20.
•VIEW POINT,DEFINITION=MODEL AXIS ROTATION
0.0,90.0
-----
5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80

```

	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80
CARD 265	<pre> DRAW *DETAIL,ELSET=PLATE,SECTION SCALING=20. *SHRINK,FACTOR=0.1 *VIEW POINT,DEFINITION=MODEL AXIS ROTATION 0.0,90.0 DRAW *ERASE *VIEW POINT 0.5,1.0,0.5 *SHRINK,FACTOR=0.2 *DETAIL,ELSET=ANGLE DRAW *DETAIL,ELSET=FIGURE DRAW *DETAIL,MSET=JANGLE *PLOT MODE,DOTSIZE=0.002 DRAW,MODENUM *SHRINK ***** *STEP,NLGEOM ** TRIGGER LOADS *STATIC,PTOL=200.,NTOL=200. *MODE PRINT,FREQ=1 **U RF *ELPRINT,FREQ=0 *CLoad **FOR FLEXURAL BUCKLING - APPLY SMALL MOMENTS AT ENDS 169.6,-500.0 10169.6,500.0 **FOR TORSIONAL BUCKLING - APPLY SMALL MOMENTS IN MAJOR AXIS PLANE 169.5,-500.0 10169.5,500.0 *DETAIL,ELSET=ANGLE *VIEW POINT,DEFINITION=MODEL AXIS ROTATION 45.0 *DISPLACED U *END STEP ***** *STEP,NLGEOM,INC=500 *STATIC,PTOL=500.0,NTOL=500.0 0.1,1.0,0.001,0.1 *ELPRINT,FREQ=2 </pre>															
CARD 270																
CARD 275																
CARD 280																
CARD 285																
CARD 290																
CARD 295																
CARD 300																

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5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80
-----
CARD 305
**S
**E
**SP
**CE,CZEO
**MODE PRINT,FREQ=1
**U
**MODE PRINT,FREQ=1
RF
**ELFILE,FREQ=0
**SP
**CZ
**MODE FILE,FREQ=0
**U
**PRINT,RESIDUAL=NO
**CLOAD
10169,1,-900.0E3
**PLOT,FREQ=3
**PLOTMODE,DOTSIZE=0.005
**SHRINK,FACTOR=0.0
**ZOOM,FACTOR=1.5
**DETAIL,ELSET=E1
**CENTER
825.0,0.0,0.0
**VIEW POINT,DEFINITION=MODEL AXIS ROTATION
30.0
**MOERASZ
**CONTOUR
S11,4
**DETAIL,ELSET=E2
**CENTER
825.0,0.0,0.0
**VIEW POINT,DEFINITION=MODEL AXIS ROTATION
45.0
**CONTOUR
S11,4
**DETAIL,ELSET=E3
**CENTER
825.0,0.0,0.0
**VIEW POINT,DEFINITION=MODEL AXIS ROTATION
135.0
**CONTOUR
S11,4
**DETAIL,ELSET=E4
**CENTER

```

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	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80
CARD 350	825.0,0.0,0.0															
	*VIEW POINT,DEFINITION=MODEL AXIS ROTATION															
	150.0															
	*CONTOUR															
	S11,q															
	*ERASE															
CARD 355	*DETAIL,ELSET=ANGLE															
	*ZOOM,FACTOR=1.0															
	*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION															
	0.0															
	*DISPLACED															
CARD 360	U															
	*DETAIL,ELSET=ANGLE															
	*ZOOM,FACTOR=1.0															
	*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION															
	90.0															
CARD 365	*DISPLACED															
	U															
	*DETAIL,ELSET=ANGLE															
	*ZOOM,FACTOR=1.0															
	*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION															
CARD 370	0.0,90.0															
	*DISPLACED															
	U															
	*END STEP															

OPTIONS BEING PROCESSED

•HEADING

60 DEG. 5x5x5/16" SHELL ELEMENTS-2ND PLATES LOAD-TORSIONAL BUCKLING
 SCHIFFERLEISED 60-DEG. HOT ROLLED ANGLE - 65.125" long
 modelled with 8-node rectangular shell elements (curves at root and toe neglected). Constant element thickness = leg thickness of the element. Length of unbent original 90-deg. angle taken as per industry standards.
 Residual stress patterns are taken from ECCS recommendations. Through the thickness variation is estimated as poisson's ratio times the superimposition of full section plastic stress and full section elastic unloading stress around the bend line of schifflerisation. The residual stresses are input as initial stresses through user defined subroutine SIGINI. All residual stress is given at the Gauss integration points.
 Boundary conditions : the top and bottom centricidal points are prevented from lateral translation and twisting rotation along the member axis. Loading : the member is loaded concentrically at section centricid point located an end plate.
 Initial out of straightness : the member buckling is achieved through usage of a nonlinear geometry option. For this to function, an initial crookedness in the geometry is introduced through triqar loads designed to create the desired buckling mode.

•NODE
 •NGEN,MSET=D1
 •NGEN,MSET=D2
 •NGEN,MSET=D3
 •NFILL,MSET=D4

THE FOLLOWING NODES WILL BE USED IN THE NFILL GENERATION

BOUND 1	1	3	5	7	9	11	13	15	17
BOUND 2	161	163	165	167	169	171	173	175	177
•NFILL,MSET=D5									

THE FOLLOWING NODES WILL BE USED IN THE NFILL GENERATION

BOUND 1	161	163	165	167	169	171	173	175	177
BOUND 2	321	323	325	327	329	331	333	335	337

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

*HSET, HSET=BOT
 *NCOPY, CHANGE NUMBER=10000, OLDSET=BOT, SHIFT, NEW SET=TOP
 *HSET, HSET=END1, GENERATE
 *HSET, HSET=END2, GENERATE
 *HFILE, HSET=JANGLE

THE FOLLOWING NODES WILL BE USED IN THE HPILL GENERATION

BOUND	1	3	5	7	9	11	13	15	17	57	97	137	177	217	257
BOUND 1	1	3	5	7	9	11	13	15	17	57	97	137	177	217	257
	297	337													
BOUND 2	10001	10003	10005	10007	10009	10011	10013	10015	10017	10057	10097	10137	10177	10217	10257
	10297	10337													

*ELEMENT, TYPE=S8R
 *ELGEN, ELSET=ANGLE
 *ELSET, ELSET=E1, GENERATE
 *ELSET, ELSET=E2, GENERATE
 *ELSET, ELSET=E3, GENERATE
 *ELSET, ELSET=E4, GENERATE
 *ELSET, ELSET=FIGURE, GENERATE
 *ELEMENT, TYPE=S8R, ELSET=PLATE
 *ELGEN, ELSET=PLATE
 *ECOPY, ELEMENT SHIFT=50, OLD SET=PLATE, NEW SET=PLATE, SHIFT NODES=10000
 *MATERIAL, NAME=M1
 *ELASTIC
 *PLASTIC
 *MATERIAL, NAME=M2
 *ELASTIC
 *SHELL SECTION, ELSET=ANGLE, MATERIAL=M1
 *SHELL SECTION, ELSET=PLATE, MATERIAL=M2
 *INITIAL CONDITIONS, TYPE=STRESS, USER
 *INITIAL CONDITIONS, TYPE=STRESS, USER
 *INITIAL CONDITIONS, TYPE=STRESS, USER
 *STEP, NLGEOM
 *STATIC, PTOL=200., NTOL=200.
 *ELPRINT, FREQ=0
 *DETAIL, ELSET=ANGLE
 *VIEW POINT, DEFINITION=MODEL AXIS ROTATION
 *DISPLACED
 *END STEP
 *STEP, NLGEOM, INC=500
 *STATIC, PTOL=500.0, NTOL=500.0
 *ELPRINT, FREQ=2
 *ELFILE, FREQ=0
 *PRINT, RESIDUAL=NO
 *PLOT, FREQ=3
 *PLOTMODE, PLOTSIZE=0.005

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

```

*SHRINK,FACTOR=0.0
*ZOOM,FACTOR=1.5
*DETAIL,ELSET=E1
*CENTER
*VIEW POINT,DEFINITION=MODEL AXIS ROTATION
*NOERASE
*CONTOUR
*DETAIL,ELSET=E2
*CENTER
*VIEW POINT,DEFINITION=MODEL AXIS ROTATION
*CONTOUR
*DETAIL,ELSET=E3
*CENTER
*VIEW POINT,DEFINITION=MODEL AXIS ROTATION
*CONTOUR
*DETAIL,ELSET=E4
*CENTER
*VIEW POINT,DEFINITION=MODEL AXIS ROTATION
*CONTOUR
*ERASE
*DETAIL,ELSET=ANGLE
*ZOOM,FACTOR=1.0
*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION
*DISPLACED
*DETAIL,ELSET=ANGLE
*ZOOM,FACTOR=1.0
*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION
*DISPLACED
*DETAIL,ELSET=ANGLE
*ZOOM,FACTOR=1.0
*VIEWPOINT,DEFINITION=MODEL AXIS ROTATION
*DISPLACED
*END STEP
*BOUNDARY
*STPP,NLGEOM
*STATIC,PTOL=200.,MTOL=200.
*MODE PRINT,FREQ=1
*CLOAD
*STEP,NLGEOM,INC=500
*STATIC,PTOL=500.0,MTOL=500.0
*MODE PRINT,FREQ=1
*MODE FILE,FREQ=0
*CLOAD

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

E L E M E N T . D E F I N I T I O N S

NUMBER	TYPE	PROPERTY REFERENCE	NODES FORMING ELEMENT									
1	S8R	2	1	81	85	5	41	83	45	3		
2	S8R	2	5	85	89	9	45	87	49	7		
3	S8R	2	9	89	93	13	49	91	53	11		
4	S8R	2	13	93	97	17	53	95	57	15		
11	S8R	2	81	161	165	85	121	163	125	83		
12	S8R	2	85	165	169	89	125	167	129	87		
13	S8R	2	89	169	173	93	129	171	133	91		
14	S8R	2	93	173	177	97	133	175	137	95		
21	S8R	2	161	241	245	165	201	243	205	163		
22	S8R	2	165	245	249	169	205	247	209	167		
23	S8R	2	169	249	253	173	209	251	213	171		
24	S8R	2	173	253	257	177	213	255	217	175		
31	S8R	2	241	321	325	245	281	323	285	243		
32	S8R	2	245	325	329	249	285	327	289	247		
33	S8R	2	249	329	333	253	289	331	293	251		
34	S8R	2	253	333	337	257	293	335	297	255		
51	S8R	2	10001	10081	10085	10005	10041	10083	10045	10003		
52	S8R	2	10005	10085	10089	10009	10045	10087	10049	10007		
53	S8R	2	10009	10089	10093	10013	10049	10091	10053	10011		
54	S8R	2	10013	10093	10097	10017	10053	10095	10057	10015		
61	S8R	2	10081	10161	10165	10085	10121	10163	10125	10083		
62	S8R	2	10085	10165	10169	10089	10125	10167	10129	10087		
63	S8R	2	10089	10169	10173	10093	10129	10171	10133	10091		
64	S8R	2	10093	10173	10177	10097	10133	10175	10137	10095		
71	S8R	2	10161	10241	10245	10165	10201	10243	10205	10163		
72	S8R	2	10165	10245	10249	10169	10205	10247	10209	10167		
73	S8R	2	10169	10249	10253	10173	10209	10251	10213	10171		
74	S8R	2	10173	10253	10257	10177	10213	10255	10217	10175		
81	S8R	2	10241	10321	10325	10245	10281	10323	10285	10243		
82	S8R	2	10245	10325	10329	10249	10285	10327	10289	10247		
83	S8R	2	10249	10329	10333	10253	10289	10331	10293	10251		
84	S8R	2	10253	10333	10337	10257	10293	10335	10297	10255		
101	S8R	1	1	2001	2005	5	1001	2003	1005	3		
102	S8R	1	5	2005	2009	9	1005	2007	1009	7		
103	S8R	1	9	2009	2013	13	1009	2011	1013	11		
104	S8R	1	13	2013	2017	17	1013	2015	1017	15		
105	S8R	1	17	2017	2021	21	1017	2019	1021	19		
106	S8R	1	21	2021	2025	25	1021	2023	1025	23		
107	S8R	1	25	2025	2029	29	1025	2027	1029	27		
108	S8R	1	29	2029	2033	33	1029	2031	1033	31		
109	S8R	1	33	2033	2037	37	1033	2035	1037	35		
201	S8R	1	2001	4001	4005	2005	3001	4003	3005	2003		

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING		DATE MAY 90	
PROPERTY NUMBER	1	2005	2009
202 58R	1	2005	2009
203 58R	1	2009	4013
204 58R	1	2013	3013
205 58R	1	2017	4017
206 58R	1	2097	4097
207 58R	1	2177	4177
208 58R	1	2257	4257
301 58R	1	4001	6001
302 58R	1	4005	6005
303 58R	1	4009	6009
304 58R	1	4013	6013
305 58R	1	4017	6017
306 58R	1	4097	6097
307 58R	1	4177	6177
308 58R	1	4257	6257
401 58R	1	6001	8001
402 58R	1	6005	8005
403 58R	1	6009	8009
404 58R	1	6013	8013
405 58R	1	6017	8017
406 58R	1	6097	8097
407 58R	1	6177	8177
408 58R	1	6257	8257
501 58R	1	8001	10001
502 58R	1	8005	10005
503 58R	1	8009	10009
504 58R	1	8013	10013
505 58R	1	8017	10017
506 58R	1	8097	10097
507 58R	1	8177	10177
508 58R	1	8257	10257

S H E L L S E C T I O N (S)

PROPERTY NUMBER 1

NUMBER OF INTEGRATION POINTS 13
 NUMBER OF LAYERS 1

LAYER	THICKNESS	POINTS	MATERIAL	ORIENTATION
1	7.833	13	M1	

TRANSVERSE SHEAR STIFFNESSES FOR THE SECTION

K(13) K(23)

5.02137E+05 5.02137E+05

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FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
60 DEG. 5x5xS/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

PROPERTY NUMBER 2
NUMBER OF INTEGRATION POINTS 5
NUMBER OF LAYERS 1
LAYER THICKNESS POINTS MATERIAL ORIENTATION,
1 150.0 5 M2

TRANSVERSE SHEAR STIFFNESSES FOR THE SECTION
K(13) K(23)
9.61538E+06 9.61538E+06

M A T E R I A L D E S C R I P T I O N

MATERIAL NAME: M1

ELASTIC YOUNGS POISSONS
MODULUS RATIO
2.00000E+05 0.30000

PLASTICITY - MISES YIELD SURFACE WITH
PERFECT PLASTICITY

STRESS

332.00

MATERIAL NAME: M2

60 DEG. 5x5x5/16" SHELL ELEMENTS-ENO PLATES LOAD-TORSIONAL BUCKLING

ELASTIC YOUNGS POISSONS
 MODULUS RATIO
 2.00000E+05 0.30000

E L E M E N T S E T S

SET	ANGLE	MEMBERS	101 205 401 505	102 206 402 506	103 207 403 507	104 208 404 508	105 301 405	106 302 406	107 303 407	109 304 408	201 305 501	202 306 502
SET	E1	MEMBERS	1	2	101	102	201	202	301	302	401	402
SET	E2	MEMBERS	3	4	103	104	203	204	303	304	403	404
SET	E3	MEMBERS	105	106	205	206	305	306	405	406	505	506
SET	E4	MEMBERS	107	108	207	208	307	308	407	408	507	508
SET	FIGURE	MEMBERS	1	2	3	4						
SET	PLATE	MEMBERS	1 31 71	2 32 72	3 33 73	4 34 74	11 51 81	12 52 82	13 53 83	14 54 84	21 61	22 62

N O D E S E T S

SET	D1	MEMBERS	1	3	5	7	9	11	13	15	17	
SET	D2	MEMBERS	161	163	165	167	169	171	173	175	177	
SET	D3	MEMBERS	321	323	325	327	329	331	333	335	337	
SET	D4	MEMBERS	1 53 125 177	3 57 129	5 81 133	7 83 137	9 85 161	11 87 163	13 89 165	15 91 167	17 93 169	41 95 171

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

SET	DS	MEMBERS	161	163	165	167	169	171	173	175	177	201	203	205	207	209	211	213	215	217	219	221	223	225	227	229	231	233	235	237	239	241	243	245	247	249	251	253	255	257	259	261	263	265	267	269	271	273	275	277	279	281	283	285	287	289	291	293	295	297	299	301	303	305	307	309	311	313	315	317	319	321	323	325	327	329	331	333	335	337	339	341	343	345	347	349	351	353	355	357	359	361	363	365	367	369	371	373	375	377	379	381	383	385	387	389	391	393	395	397	399	401	403	405	407	409	411	413	415	417	419	421	423	425	427	429	431	433	435	437	439	441	443	445	447	449	451	453	455	457	459	461	463	465	467	469	471	473	475	477	479	481	483	485	487	489	491	493	495	497	499	501	503	505	507	509	511	513	515	517	519	521	523	525	527	529	531	533	535	537	539	541	543	545	547	549	551	553	555	557	559	561	563	565	567	569	571	573	575	577	579	581	583	585	587	589	591	593	595	597	599	601	603	605	607	609	611	613	615	617	619	621	623	625	627	629	631	633	635	637	639	641	643	645	647	649	651	653	655	657	659	661	663	665	667	669	671	673	675	677	679	681	683	685	687	689	691	693	695	697	699	701	703	705	707	709	711	713	715	717	719	721	723	725	727	729	731	733	735	737	739	741	743	745	747	749	751	753	755	757	759	761	763	765	767	769	771	773	775	777	779	781	783	785	787	789	791	793	795	797	799	801	803	805	807	809	811	813	815	817	819	821	823	825	827	829	831	833	835	837	839	841	843	845	847	849	851	853	855	857	859	861	863	865	867	869	871	873	875	877	879	881	883	885	887	889	891	893	895	897	899	901	903	905	907	909	911	913	915	917	919	921	923	925	927	929	931	933	935	937	939	941	943	945	947	949	951	953	955	957	959	961	963	965	967	969	971	973	975	977	979	981	983	985	987	989	991	993	995	997	999	1001	1003	1005	1007	1009	1011	1013	1015	1017	1019	1021	1023	1025	1027	1029	1031	1033	1035	1037	1039	1041	1043	1045	1047	1049	1051	1053	1055	1057	1059	1061	1063	1065	1067	1069	1071	1073	1075	1077	1079	1081	1083	1085	1087	1089	1091	1093	1095	1097	1099	1101	1103	1105	1107	1109	1111	1113	1115	1117	1119	1121	1123	1125	1127	1129	1131	1133	1135	1137	1139	1141	1143	1145	1147	1149	1151	1153	1155	1157	1159	1161	1163	1165	1167	1169	1171	1173	1175	1177	1179	1181	1183	1185	1187	1189	1191	1193	1195	1197	1199	1201	1203	1205	1207	1209	1211	1213	1215	1217	1219	1221	1223	1225	1227	1229	1231	1233	1235	1237	1239	1241	1243	1245	1247	1249	1251	1253	1255	1257	1259	1261	1263	1265	1267	1269	1271	1273	1275	1277	1279	1281	1283	1285	1287	1289	1291	1293	1295	1297	1299	1301	1303	1305	1307	1309	1311	1313	1315	1317	1319	1321	1323	1325	1327	1329	1331	1333	1335	1337	1339	1341	1343	1345	1347	1349	1351	1353	1355	1357	1359	1361	1363	1365	1367	1369	1371	1373	1375	1377	1379	1381	1383	1385	1387	1389	1391	1393	1395	1397	1399	1401	1403	1405	1407	1409	1411	1413	1415	1417	1419	1421	1423	1425	1427	1429	1431	1433	1435	1437	1439	1441	1443	1445	1447	1449	1451	1453	1455	1457	1459	1461	1463	1465	1467	1469	1471	1473	1475	1477	1479	1481	1483	1485	1487	1489	1491	1493	1495	1497	1499	1501	1503	1505	1507	1509	1511	1513	1515	1517	1519	1521	1523	1525	1527	1529	1531	1533	1535	1537	1539	1541	1543	1545	1547	1549	1551	1553	1555	1557	1559	1561	1563	1565	1567	1569	1571	1573	1575	1577	1579	1581	1583	1585	1587	1589	1591	1593	1595	1597	1599	1601	1603	1605	1607	1609	1611	1613	1615	1617	1619	1621	1623	1625	1627	1629	1631	1633	1635	1637	1639	1641	1643	1645	1647	1649	1651	1653	1655	1657	1659	1661	1663	1665	1667	1669	1671	1673	1675	1677	1679	1681	1683	1685	1687	1689	1691	1693	1695	1697	1699	1701	1703	1705	1707	1709	1711	1713	1715	1717	1719	1721	1723	1725	1727	1729	1731	1733	1735	1737	1739	1741	1743	1745	1747	1749	1751	1753	1755	1757	1759	1761	1763	1765	1767	1769	1771	1773	1775	1777	1779	1781	1783	1785	1787	1789	1791	1793	1795	1797	1799	1801	1803	1805	1807	1809	1811	1813	1815	1817	1819	1821	1823	1825	1827	1829	1831	1833	1835	1837	1839	1841	1843	1845	1847	1849	1851	1853	1855	1857	1859	1861	1863	1865	1867	1869	1871	1873	1875	1877	1879	1881	1883	1885	1887	1889	1891	1893	1895	1897	1899	1901	1903	1905	1907	1909	1911	1913	1915	1917	1919	1921	1923	1925	1927	1929	1931	1933	1935	1937	1939	1941	1943	1945	1947	1949	1951	1953	1955	1957	1959	1961	1963	1965	1967	1969	1971	1973	1975	1977	1979	1981	1983	1985	1987	1989	1991	1993	1995	1997	1999	2001	2003	2005	2007	2009	2011	2013	2015	2017	2019	2021	2023	2025	2027	2029	2031	2033	2035	2037	2039	2041	2043	2045	2047	2049	2051	2053	2055	2057	2059	2061	2063	2065	2067	2069	2071	2073	2075	2077	2079	2081	2083	2085	2087	2089	2091	2093	2095	2097	2099	2101	2103	2105	2107	2109	2111	2113	2115	2117	2119	2121	2123	2125	2127	2129	2131	2133	2135	2137	2139	2141	2143	2145	2147	2149	2151	2153	2155	2157	2159	2161	2163	2165	2167	2169	2171	2173	2175	2177	2179	2181	2183	2185	2187	2189	2191	2193	2195	2197	2199	2201	2203	2205	2207	2209	2211	2213	2215	2217	2219	2221	2223	2225	2227	2229	2231	2233	2235	2237	2239	2241	2243	2245	2247	2249	2251	2253	2255	2257	2259	2261	2263	2265	2267	2269	2271	2273	2275	2277	2279	2281	2283	2285	2287	2289	2291	2293	2295	2297	2299	2301	2303	2305	2307	2309	2311	2313	2315	2317	2319	2321	2323	2325	2327	2329	2331	2333	2335	2337	2339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ABAQUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90 TIME 17:26:15 PAGE 20
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES	LOAD-TORSIONAL BUCKLING
5	0.00000E+00 58.385 -40.007 1.0000 0.00000E+00 0.00000E+00
7	0.00000E+00 36.644 -27.455 1.0000 0.00000E+00 0.00000E+00
9	0.00000E+00 14.902 -14.902 1.0000 0.00000E+00 0.00000E+00
11	0.00000E+00 11.177 -11.177 1.0000 0.00000E+00 0.00000E+00
13	0.00000E+00 7.4511 -7.4511 1.0000 0.00000E+00 0.00000E+00
15	0.00000E+00 3.7256 -3.7256 1.0000 0.00000E+00 0.00000E+00
17	0.00000E+00 0.00000E+00 0.00000E+00 1.0000 0.00000E+00 0.00000E+00
41	0.00000E+00 108.06 -58.919 1.0000 0.00000E+00 0.00000E+00
45	0.00000E+00 65.813 -35.048 1.0000 0.00000E+00 0.00000E+00
49	0.00000E+00 23.564 -11.177 1.0000 0.00000E+00 0.00000E+00
53	0.00000E+00 13.545 -3.7256 1.0000 0.00000E+00 0.00000E+00
57	0.00000E+00 3.7256 -52.725 1.0000 0.00000E+00 0.00000E+00
81	0.00000E+00 114.26 -41.406 1.0000 0.00000E+00 0.00000E+00
83	0.00000E+00 93.749 -30.088 1.0000 0.00000E+00 0.00000E+00
85	0.00000E+00 73.241 -7.4511 1.0000 0.00000E+00 0.00000E+00
87	0.00000E+00 52.734 -3.7256 1.0000 0.00000E+00 0.00000E+00
89	0.00000E+00 32.226 -7.4511 1.0000 0.00000E+00 0.00000E+00
91	0.00000E+00 26.032 -3.7256 1.0000 0.00000E+00 0.00000E+00
93	0.00000E+00 19.839 2.22045E-16 1.0000 0.00000E+00 0.00000E+00
95	0.00000E+00 13.645 3.7256 1.0000 0.00000E+00 0.00000E+00
97	0.00000E+00 7.4511 7.4511 1.0000 0.00000E+00 0.00000E+00
121	0.00000E+00 120.45 -46.531 1.0000 0.00000E+00 0.00000E+00
125	0.00000E+00 80.669 -25.128 1.0000 0.00000E+00 0.00000E+00
129	0.00000E+00 40.888 -3.7256 1.0000 0.00000E+00 0.00000E+00
133	0.00000E+00 26.032 3.7256 1.0000 0.00000E+00 0.00000E+00
137	0.00000E+00 11.177 11.177 1.0000 0.00000E+00 0.00000E+00
161	0.00000E+00 126.64 -40.337 1.0000 0.00000E+00 0.00000E+00
163	0.00000E+00 107.37 -30.253 1.0000 0.00000E+00 0.00000E+00
165	0.00000E+00 88.097 -20.169 1.0000 0.00000E+00 0.00000E+00
167	0.00000E+00 68.823 -10.084 1.0000 0.00000E+00 0.00000E+00
169	0.00000E+00 49.550 0.00000E+00 1.0000 0.00000E+00 0.00000E+00
171	0.00000E+00 40.888 3.7256 1.0000 0.00000E+00 0.00000E+00
173	0.00000E+00 32.226 7.4511 1.0000 0.00000E+00 0.00000E+00
175	0.00000E+00 23.564 11.177 1.0000 0.00000E+00 0.00000E+00
177	0.00000E+00 14.902 14.902 1.0000 0.00000E+00 0.00000E+00
201	0.00000E+00 136.73 -30.253 1.0000 0.00000E+00 0.00000E+00
205	0.00000E+00 102.78 -10.084 1.0000 0.00000E+00 0.00000E+00
209	0.00000E+00 68.823 10.084 1.0000 0.00000E+00 0.00000E+00
213	0.00000E+00 52.734 18.770 1.0000 0.00000E+00 0.00000E+00
217	0.00000E+00 36.644 27.455 1.0000 0.00000E+00 0.00000E+00
241	0.00000E+00 146.81 -20.169 1.0000 0.00000E+00 0.00000E+00
243	0.00000E+00 132.13 -10.094 1.0000 0.00000E+00 0.00000E+00
245	0.00000E+00 117.45 0.00000E+00 1.0000 0.00000E+00 0.00000E+00
247	0.00000E+00 102.78 10.084 1.0000 0.00000E+00 0.00000E+00
249	0.00000E+00 88.097 20.169 1.0000 0.00000E+00 0.00000E+00
251	0.00000E+00 80.669 25.128 1.0000 0.00000E+00 0.00000E+00
253	0.00000E+00 73.241 30.088 1.0000 0.00000E+00 0.00000E+00
255	0.00000E+00 65.813 35.048 1.0000 0.00000E+00 0.00000E+00

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES	LOAD-TORSIONAL BUCKLING
257 0.00000E+00 58.385 40.007 1.0000 0.00000E+00 0.00000E+00	
281 0.00000E+00 156.90 -10.084 1.0000 0.00000E+00 0.00000E+00	
285 0.00000E+00 132.13 10.084 1.0000 0.00000E+00 0.00000E+00	
289 0.00000E+00 107.37 30.253 1.0000 0.00000E+00 0.00000E+00	
293 0.00000E+00 93.749 41.406 1.0000 0.00000E+00 0.00000E+00	
297 0.00000E+00 80.127 52.560 1.0000 0.00000E+00 0.00000E+00	
321 0.00000E+00 166.98 0.00000E+00 1.0000 0.00000E+00 0.00000E+00	
323 0.00000E+00 156.90 10.084 1.0000 0.00000E+00 0.00000E+00	
325 0.00000E+00 146.81 20.169 1.0000 0.00000E+00 0.00000E+00	
327 0.00000E+00 136.73 30.253 1.0000 0.00000E+00 0.00000E+00	
329 0.00000E+00 126.64 40.337 1.0000 0.00000E+00 0.00000E+00	
331 0.00000E+00 120.45 46.531 1.0000 0.00000E+00 0.00000E+00	
333 0.00000E+00 114.26 52.725 1.0000 0.00000E+00 0.00000E+00	
335 0.00000E+00 108.06 58.919 1.0000 0.00000E+00 0.00000E+00	
337 0.00000E+00 101.87 65.112 1.0000 0.00000E+00 0.00000E+00	
1001 165.42 101.87 -65.112 0.00000E+00 -0.50000 -0.86603	
1005 165.42 58.385 -40.007 0.00000E+00 -0.50000 -0.86603	
1009 165.42 14.902 -14.902 0.00000E+00 -0.60876 -0.79335	
1013 165.42 7.4511 -7.4511 0.00000E+00 -0.70711 -0.70711	
1017 165.42 0.00000E+00 0.00000E+00 0.00000E+00 -0.70711 -0.70711	
1097 165.42 7.4511 7.4511 0.00000E+00 -0.70711 0.70711	
1177 165.42 14.902 14.902 0.00000E+00 -0.60876 0.79335	
1257 165.42 58.385 40.007 0.00000E+00 -0.50000 0.86603	
1337 165.42 101.87 65.112 0.00000E+00 -0.50000 0.86603	
2001 330.83 101.87 -65.112 0.00000E+00 -0.50000 -0.86603	
2003 330.83 80.127 -52.560 0.00000E+00 -0.50000 -0.86603	
2005 330.83 58.385 -40.007 0.00000E+00 -0.50000 -0.86603	
2007 330.83 36.644 -27.455 0.00000E+00 -0.50000 -0.86603	
2009 330.83 14.902 -14.902 0.00000E+00 -0.60876 -0.79335	
2011 330.83 11.177 -11.177 0.00000E+00 -0.70711 -0.70711	
2013 330.83 7.4511 -7.4511 0.00000E+00 -0.70711 -0.70711	
2015 330.83 3.7256 -3.7256 0.00000E+00 -0.70711 -0.70711	
2017 330.83 0.00000E+00 0.00000E+00 0.00000E+00 -0.70711 0.70711	
2057 330.83 3.7256 3.7256 0.00000E+00 -0.70711 0.70711	
2097 330.83 7.4511 7.4511 0.00000E+00 -0.70711 0.70711	
2137 330.83 11.177 11.177 0.00000E+00 -0.70711 0.70711	
2177 330.83 14.902 14.902 0.00000E+00 -0.60876 0.79335	
2217 330.83 36.644 27.455 0.00000E+00 -0.50000 0.86603	
2257 330.83 58.385 40.007 0.00000E+00 -0.50000 0.86603	
2297 330.83 80.127 52.560 0.00000E+00 -0.50000 0.86603	
2337 330.83 101.87 65.112 0.00000E+00 -0.50000 0.86603	
3001 496.25 101.87 -65.112 0.00000E+00 -0.50000 -0.86603	
3005 496.25 58.385 -40.007 0.00000E+00 -0.50000 -0.86603	
3009 496.25 14.902 -14.902 0.00000E+00 -0.70711 -0.79335	
3013 496.25 7.4511 -7.4511 0.00000E+00 -0.70711 -0.70711	
3017 496.25 0.00000E+00 0.00000E+00 0.00000E+00 -0.70711 0.70711	
3097 496.25 7.4511 7.4511 0.00000E+00 -0.70711 0.79335	
3177 496.25 14.902 14.902 0.00000E+00 -0.60876 0.79335	

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 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING	0.0000E+00-0.50000	0.86603
3257	496.25	58.385
3337	496.25	101.87
4001	661.67	101.87
4003	661.67	80.127
4005	661.67	58.385
4007	661.67	36.644
4009	661.67	14.902
4011	661.67	11.177
4013	661.67	7.4511
4015	661.67	3.7256
4017	661.67	0.0000E+00
4057	661.67	3.7256
4097	661.67	7.4511
4137	661.67	11.177
4177	661.67	14.902
4217	661.67	18.644
4257	661.67	22.385
4297	661.67	26.127
4337	661.67	29.869
5001	827.09	101.87
5005	827.09	58.385
5009	827.09	14.902
5013	827.09	7.4511
5017	827.09	0.0000E+00
5097	827.09	7.4511
5177	827.09	14.902
5257	827.09	22.385
5337	827.09	29.869
6001	992.50	101.87
6003	992.50	80.127
6005	992.50	58.385
6007	992.50	36.644
6009	992.50	14.902
6011	992.50	11.177
6013	992.50	7.4511
6015	992.50	3.7256
6017	992.50	0.0000E+00
6057	992.50	3.7256
6059	992.50	7.4511
6137	992.50	11.177
6177	992.50	14.902
6217	992.50	18.644
6257	992.50	22.385
6297	992.50	26.127
6337	992.50	29.869
7001	1157.9	101.87
7005	1157.9	58.385
7009	1157.9	14.902

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60 DEG. 545x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
7013 1157.9 7.4511 0.0000E+00 -0.70711 -0.70711
7017 1157.9 0.0000E+00 0.0000E+00 0.0000E+00 -0.70711 -0.70711
7097 1157.9 7.4511 0.0000E+00 -0.70711 0.70711
7177 1157.9 14.902 0.0000E+00 -0.60876 0.79335
7257 1157.9 58.385 40.007 0.0000E+00 -0.50000 0.86603
7337 1157.9 101.87 65.112 0.0000E+00 -0.50000 0.86603
8001 1323.3 101.87 -65.112 0.0000E+00 -0.50000 -0.86603
8003 1323.3 80.127 -52.560 0.0000E+00 -0.50000 -0.86603
8005 1323.3 58.385 -40.007 0.0000E+00 -0.50000 -0.86603
8007 1323.3 36.684 -27.455 0.0000E+00 -0.50000 -0.86603
8009 1323.3 14.902 -14.902 0.0000E+00 -0.60876 -0.79335
8011 1323.3 11.177 -11.177 0.0000E+00 -0.70711 -0.70711
8013 1323.3 7.4511 -7.4511 0.0000E+00 -0.70711 -0.70711
8015 1323.3 3.7256 -3.7256 0.0000E+00 -0.70711 -0.70711
8017 1323.3 0.0000E+00 0.0000E+00 0.0000E+00 -0.70711 0.70711
8057 1323.3 3.7256 3.7256 0.0000E+00 -0.70711 0.70711
8097 1323.3 7.4511 7.4511 0.0000E+00 -0.70711 0.70711
8137 1323.3 11.177 11.177 0.0000E+00 -0.70711 0.70711
8177 1323.3 14.902 14.902 0.0000E+00 -0.60876 0.79335
8217 1323.3 36.684 27.455 0.0000E+00 -0.50000 0.86603
8257 1323.3 58.385 40.007 0.0000E+00 -0.50000 0.86603
8297 1323.3 80.127 52.560 0.0000E+00 -0.50000 0.86603
8337 1323.3 101.87 65.112 0.0000E+00 -0.50000 0.86603
9001 1488.8 101.87 -65.112 0.0000E+00 -0.50000 -0.86603
9005 1488.8 58.385 -40.007 0.0000E+00 -0.50000 -0.86603
9009 1488.8 14.902 -14.902 0.0000E+00 -0.60876 -0.79335
9013 1488.8 7.4511 -7.4511 0.0000E+00 -0.70711 -0.70711
9017 1488.8 0.0000E+00 0.0000E+00 0.0000E+00 -0.70711 0.70711
9097 1488.8 7.4511 7.4511 0.0000E+00 -0.70711 0.79335
9177 1488.8 14.902 14.902 0.0000E+00 -0.60876 0.86603
9257 1488.8 58.385 40.007 0.0000E+00 -0.50000 0.86603
9337 1488.8 101.87 65.112 0.0000E+00 -0.50000 0.86603
10001 1654.2 101.87 -65.112 1.0000 0.0000E+00 0.0000E+00
10003 1654.2 80.127 -52.560 1.0000 0.0000E+00 0.0000E+00
10005 1654.2 58.385 -40.007 1.0000 0.0000E+00 0.0000E+00
10007 1654.2 36.684 -27.455 1.0000 0.0000E+00 0.0000E+00
10009 1654.2 14.902 -14.902 1.0000 0.0000E+00 0.0000E+00
10011 1654.2 11.177 -11.177 1.0000 0.0000E+00 0.0000E+00
10013 1654.2 7.4511 -7.4511 1.0000 0.0000E+00 0.0000E+00
10015 1654.2 3.7256 -3.7256 1.0000 0.0000E+00 0.0000E+00
10017 1654.2 0.0000E+00 0.0000E+00 1.0000 0.0000E+00 0.0000E+00
10041 1654.2 108.06 -58.919 1.0000 0.0000E+00 0.0000E+00
10045 1654.2 65.813 -35.048 1.0000 0.0000E+00 0.0000E+00
10049 1654.2 23.564 -11.177 1.0000 0.0000E+00 0.0000E+00
10053 1654.2 13.645 -3.7256 1.0000 0.0000E+00 0.0000E+00
10057 1654.2 3.7256 -3.7256 1.0000 0.0000E+00 0.0000E+00
10081 1654.2 114.26 -52.725 1.0000 0.0000E+00 0.0000E+00
10083 1654.2 93.749 -41.406 1.0000 0.0000E+00 0.0000E+00

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60 DEG.	5x5x5/16" SHELL ELEMENTS-END PLATES	LOAD-TORSIONAL BUCKLING
10085	1654.2	1.0000
10086	73.241	0.00000E+00
10087	52.734	0.00000E+00
10088	32.226	0.00000E+00
10089	26.032	0.00000E+00
10090	19.839	0.00000E+00
10091	13.645	0.00000E+00
10092	7.4511	0.00000E+00
10093	2.22045E-16	0.00000E+00
10094	3.7256	0.00000E+00
10095	7.4511	0.00000E+00
10096	46.531	0.00000E+00
10097	120.45	0.00000E+00
10098	80.669	0.00000E+00
10099	40.888	0.00000E+00
10100	26.032	0.00000E+00
10101	11.177	0.00000E+00
10102	126.64	0.00000E+00
10103	107.37	0.00000E+00
10104	88.097	0.00000E+00
10105	68.823	0.00000E+00
10106	49.550	0.00000E+00
10107	40.888	0.00000E+00
10108	32.226	0.00000E+00
10109	23.564	0.00000E+00
10110	14.902	0.00000E+00
10111	136.73	0.00000E+00
10112	102.78	0.00000E+00
10113	52.734	0.00000E+00
10114	36.644	0.00000E+00
10115	146.81	0.00000E+00
10116	132.13	0.00000E+00
10117	117.45	0.00000E+00
10118	102.78	0.00000E+00
10119	88.097	0.00000E+00
10120	80.669	0.00000E+00
10121	73.241	0.00000E+00
10122	65.813	0.00000E+00
10123	58.385	0.00000E+00
10124	156.90	0.00000E+00
10125	132.13	0.00000E+00
10126	107.37	0.00000E+00
10127	93.749	0.00000E+00
10128	80.127	0.00000E+00
10129	166.98	0.00000E+00
10130	156.90	0.00000E+00
10131	146.81	0.00000E+00
10132	136.73	0.00000E+00
10133	126.64	0.00000E+00
10134	120.45	0.00000E+00
10135	114.26	0.00000E+00
10136	108.06	0.00000E+00

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ADAPUS PRODUCTION VERSION 4-7-22

FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL DUCKLING

101.87

65.112

1.0000

0.00000E+00

0.00000E+00

N O R M A L D E F I N I T I O N S

ELEMENT	NODE	NORMAL	ELEMENT	MODE	NORMAL
101	1	0.0000E+00 -0.5000	101	5	0.0000E+00 -0.5000
101	3	0.0000E+00 -0.5000	102	5	0.0000E+00 -0.5000
102	9	0.0000E+00 -0.6088	102	7	0.0000E+00 -0.5000
103	9	0.0000E+00 -0.6088	103	13	0.0000E+00 -0.7071
103	11	0.0000E+00 -0.7071	104	13	0.0000E+00 -0.7071
104	17	0.0000E+00 -0.7071	104	15	0.0000E+00 -0.7071
105	17	0.0000E+00 -0.7071	105	2017	0.0000E+00 -0.7071
105	97	0.0000E+00 -0.7071	105	1017	0.0000E+00 -0.7071
105	57	0.0000E+00 -0.7071	106	97	0.0000E+00 -0.7071
106	177	0.0000E+00 -0.6088	106	137	0.0000E+00 -0.7071
107	177	0.0000E+00 -0.6088	107	257	0.0000E+00 -0.5000
107	417	0.0000E+00 -0.5000	108	257	0.0000E+00 -0.5000
108	337	0.0000E+00 -0.5000	108	297	0.0000E+00 -0.5000
205	2017	0.0000E+00 -0.7071	205	4017	0.0000E+00 -0.7071
205	3017	0.0000E+00 -0.7071	305	4017	0.0000E+00 -0.7071
305	6017	0.0000E+00 -0.7071	305	5017	0.0000E+00 -0.7071
405	6017	0.0000E+00 -0.7071	405	8017	0.0000E+00 -0.7071
405	7017	0.0000E+00 -0.7071	501	10001	0.0000E+00 -0.5000
501	10005	0.0000E+00 -0.5000	501	10003	0.0000E+00 -0.5000
502	10005	0.0000E+00 -0.5000	502	10009	0.0000E+00 -0.6088
502	10007	0.0000E+00 -0.5000	503	10009	0.0000E+00 -0.6088
503	10013	0.0000E+00 -0.7071	503	10011	0.0000E+00 -0.7071
504	10013	0.0000E+00 -0.7071	504	10017	0.0000E+00 -0.7071
504	10015	0.0000E+00 -0.7071	505	8017	0.0000E+00 -0.7071
505	10017	0.0000E+00 -0.7071	505	10097	0.0000E+00 -0.7071
505	9017	0.0000E+00 -0.7071	505	10057	0.0000E+00 -0.7071
506	10097	0.0000E+00 -0.7071	506	10177	0.0000E+00 -0.6088
506	10137	0.0000E+00 -0.7071	507	10177	0.0000E+00 -0.6088
507	10257	0.0000E+00 -0.5000	507	10217	0.0000E+00 -0.5000
508	10257	0.0000E+00 -0.5000	508	10337	0.0000E+00 -0.5000
508	10297	0.0000E+00 -0.5000			

-0.8660
-0.8660
-0.8660
-0.7071
-0.7071
-0.7071
0.7071
0.7071
0.7071
0.8660
0.8660
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0.7071
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-0.8660
-0.8660
-0.7934
-0.7934
-0.7071
-0.7071
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0.8660
0.7934
0.7934
0.9660
0.8660

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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

I N I T I A L S T R E S S E S

(NOT INCLUDING STRESSES DEFINED IN USER SUBROUTINE SIGINI)

ELEMENT NUMBER	INT-PT.	REBAR NAME	STRESSES
-------------------	---------	---------------	----------

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

STEP 1 STATIC ANALYSIS

AUTOMATIC TIME CONTROL WITH -
A SUGGESTED INITIAL TIME INCREMENT OF 1.00
AND A TOTAL TIME PERIOD OF 1.00
THE MINIMUM TIME INCREMENT ALLOWED IS 1.000E-05
THE MAXIMUM TIME INCREMENT ALLOWED IS 1.00

THE CONVERGENCE TOLERANCE MEASURES ARE -
TOLERANCE ON INDIVIDUAL FORCE COMPONENTS 200.
TOLERANCE ON INDIVIDUAL MOMENT COMPONENTS 200.

THE MAXIMUM NUMBER OF INCREMENTS IN THIS STEP IS 10
THE MAXIMUM NUMBER OF ITERATIONS PER INCREMENT IS 6

LARGE DISPLACEMENT THEORY WILL BE USED

PRINT OF INCREMENT NUMBER, TIME, ETC., EVERY 1 INCREMENTS

ABAQUS PRODUCTION VERSION 6-7-22 DATE 5MAY 90
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

N O D E P R I N T

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES AT EVERY 1 INCREMENT

SUMMARIES WILL BE PRINTED

TABLE 1	RP1	RP2	RP3	RM1	RM2	RM3
---------	-----	-----	-----	-----	-----	-----

P L O T O U T P U T

PLOT FRAME 1 CONSISTS OF ELSET ANGLE

THE FRAME WILL BE GENERATED EVERY 1 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE :

ALL SIZES ARE IN PLOTTER UNITS

X-DIRECTION Y-DIRECTION

FRAME SIZE	10.000	10.000
PICTURE SIZE	7.0000	7.0000
POSITION OF LOWER LEFT HAND CORNER OF PICTURE	3.0000	2.0000
POSITION OF START OF TITLE	1.5000	1.3000
POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST	0.10000	0.0000
POSITION OF AXIS	1.5000	1.5000

SIZE OF CHARACTERS	0.16000
WIDTH OF PAPER STRIP BETWEEN FRAMES	5.0000

MODEL AXIS ROTATION	0.785	0.000E+00	0.000E+00
---------------------	-------	-----------	-----------

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 DISPLACED SHAPE OF U WILL BE DRAWN
 THE UNDEFORMED CONFIGURATION WILL BE DRAWN IN DOTTED LINES

BOUNDARY CONDITIONS

NODE	DOF	AMP. REF.	MAGNITUDE	NODE	DOF	AMP. REF.	MAGNITUDE
169	1		0.00000E+00	169	2		0.00000E+00
169	3		0.00000E+00	169	4		0.00000E+00
10169	2		0.00000E+00	10169	3		0.00000E+00
10169	4		0.00000E+00				

CONCENTRATED LOADS

NODE	DOF	AMP. REF.	AMPLITUDE	NODE	DOF	AMP. REF.	AMPLITUDE	NODE	DOF	AMP. REF.
169	6		-500.00	169	5		-500.00	10169	6	
10169	5		500.00							

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ABAQUS PRODUCTION VERSION 4-7-22
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60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

S T E P 2 S T A T I C A N A L Y S I S

AUTOMATIC TIME CONTROL WITH - 1.000E-01
A SUGGESTED INITIAL TIME INCREMENT OF 1.00
AND A TOTAL TIME PERIOD OF 1.000E-03
THE MINIMUM TIME INCREMENT ALLOWED IS 1.000E-01
THE MAXIMUM TIME INCREMENT ALLOWED IS

THE CONVERGENCE TOLERANCE MEASURES ARE - 500.
TOLERANCE ON INDIVIDUAL FORCE COMPONENTS 500.
TOLERANCE ON INDIVIDUAL MOMENT COMPONENTS 500
THE MAXIMUM NUMBER OF INCREMENTS IN THIS STEP IS 6
THE MAXIMUM NUMBER OF ITERATIONS PER INCREMENT IS

LARGE DISPLACEMENT THEORY WILL BE USED

PRINTOUT OF RESIDUALS DURING EQUILIBRIUM ITERATION IS SUPPRESSED

PRINT OF INCREMENT NUMBER, TIME, ETC., EVERY 1 INCREMENTS

E L E M E N T P R I N T

THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION :

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 5
 SUMMARIES WILL BE PRINTED

TABLE 1	S11	S22	S12	MISES
---------	-----	-----	-----	-------

THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION :

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 13
 SUMMARIES WILL BE PRINTED

TABLE 2	S11	S22	S12	MISES
---------	-----	-----	-----	-------

THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION :

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 5
 SUMMARIES WILL BE PRINTED

TABLE 3	E11	E22	E12
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THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION :

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 13
 SUMMARIES WILL BE PRINTED

TABLE 4	E11	E22	E12
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ABAQUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90 TIME 17:26:15 PAGE 32
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM "KS, INC."
 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL DUCKLING

THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 5
 SUMMARIES WILL BE PRINTED

TABLE 5 IE11 IE22 IE12 IEHAG

THE FOLLOWING TABLE IS PRINTED FOR ALL ELEMENTS WITH TYPE S8R AT EVERY 2 INCREMENT AT THE INTEGRATION

VALUES ARE PRINTED AT THE FOLLOWING BEAM/SHELL SECTION POINTS 1 13
 SUMMARIES WILL BE PRINTED

TABLE 6 IE11 IE22 IE12 IEHAG

N O D E P R I N T

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES AT EVERY 1 INCREMENT

SUMMARIES WILL BE PRINTED

TABLE 1 U1 U2 U3 UR1 UR2 UR3

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES AT EVERY 1 INCREMENT

SUMMARIES WILL BE PRINTED

TABLE 2 RF1 RF2 RF3 RM1 RM2 RM3

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES AT EVERY 1 INCREMENT

SUMMARIES WILL BE PRINTED

TABLE 3	CF1	CF2	CF3	CM1	CM2	CM3
---------	-----	-----	-----	-----	-----	-----

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES AT EVERY 1 INCREMENT

SUMMARIES WILL BE PRINTED

TABLE 4	RF1	RF2	RF3	RM1	RM2	RM3
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P L O T O U T P U T

PLOT FRAME 1 CONSISTS OF ELSET E1

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

	X-DIRECTION	Y-DIRECTION
FRAME SIZE	10.000	10.000
PICTURE SIZE	7.0000	7.0000
POSITION OF LOWER LEFT HAND CORNER OF PICTURE	3.0000	2.0000
POSITION OF START OF TITLE	1.5000	1.0000
POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST	0.10000	8.0000
POSITION OF AXIS	1.5000	1.5000

SIZE OF CHARACTERS 0.16000
WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

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TIME 17:26:15

DATE 5MAY 90

ABAQUS PRODUCTION VERSION: 4-7-22

FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 MODEL AXIS ROTATION 0.524 0.000E+00 0.000E+00

CONTOURS OF S11 ARE PLOTTED
 NUMBER OF CONTOURS 4
 FACE NUMBER 1
 SECTION POINT 1
 ONLY THE OUTSIDE OF THE MESH WILL BE PLOTTED

PLOT FRAME 2 CONSISTS OF ELSET E2

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST

POSITION OF AXIS

SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN FRAMES

MODEL AXIS ROTATION 0.785 0.000E+00 0.000E+00

X-DIRECTION	Y-DIRECTION
10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	8.0000
1.5000	1.5000

0.16000
 5.0000

CONTOURS OF S11 ARE PLOTTED
 NUMBER OF CONTOURS 4
 FACE NUMBER 1
 SECTION POINT 1
 ONLY THE OUTSIDE OF THE MESH WILL BE PLOTTED

PLOT FRAME 3 CONSISTS OF ELSET E3

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE 1

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TIME 17:26:15

DATE MAY 90

ABAVUS PRODUCTION VERSION 4-7-22

FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM IKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

ALL SIZES ARE IN PLOTTER UNITS

X-DIRECTION Y-DIRECTION

FRAME SIZE

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND

POSITION OF AXIS

SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN

SIZE OF CHARACTERS
WIDTH OF PAPER STRIP BETWEEN FRAMES
0.16000
5.00000

SIZE OF CHARACTERS
WIDTH OF PAPER STRIP BETWEEN FRAMES

MODEL AXIS ROTATION	2.36	0.000E+00	0.000E+00
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CONTOURS OF \$11 ARE PLOTTED

CONTOURS OF 311	NUMBER OF CONTOURS	4
1	1	1
2	2	2
3	3	3
4	4	4
5	5	5
6	6	6
7	7	7
8	8	8
9	9	9
10	10	10
11	11	11
12	12	12
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14	14	14
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98	98	98
99	99	99
100	100	100

NUMBER OF CONTROLS	FACE NUMBER
1	1

SECTION POINT 1

ONLY THE OUTSIDE OF THE MESH WILL BE PLOTTED

PLOT FRAME 4 CONSISTS OF ELSET EQ

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
NUMBER 274111AVALA580705 1

NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

X-DIRECTION Y-DIRECTION

FRAME SIZE

FRAME SIZE

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POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND

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SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN

SIZE OF CHARACTERS	WIDTH OF PAPER STRIP	NUMBER OF FRAMES
0.16000		
5.00000		

SIZE OF CHARACTERS

MODEL AXIS ROTATION	2.62	0.000E+00	0.000E+00
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TIME 17:26:15

DATE 5MAY 90

AAUQUS PRODUCTION VERSION 4-7-22
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

CONTOURS OF S11 ARE PLOTTED
 NUMBER OF CONTOURS 4
 FACE NUMBER 1
 SECTION POINT 1
 ONLY THE OUTSIDE OF THE MESH WILL BE PLOTTED

PLOT FRAME 5 CONSISTS OF ELSET ANGLE

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST

POSITION OF AXIS

SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN FRAMES

DISPLACED SHAPE OF U WILL BE DRAWN

THE UNDEFORMED CONFIGURATION WILL BE DRAWN IN DOTTED LINES

X-DIRECTION	Y-DIRECTION
10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	8.0000
1.5000	1.5000
0.16000	
5.0000	

PLOT FRAME 6 CONSISTS OF ELSET ANGLE

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST

POSITION OF AXIS

X-DIRECTION	Y-DIRECTION
10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	8.0000
1.5000	1.5000

AUAGUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90 TIME 17:26:15 PAGE 37
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 SIZE OF CHARACTERS 0.16000
 WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

MODEL AXIS ROTATION 1.57 0.000E+00 0.000E+00
 DISPLACED SHAPE OF U WILL BE DRAWN
 THE UNDEFORMED CONFIGURATION WILL BE DRAWN IN DOTTED LINES

PLOT FRAME 7 CONSISTS OF ELSET ANGLE

THE FRAME WILL BE GENERATED EVERY 3 INCREMENTS

TITLE - 60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 NUMBER OF COLORS AVAILABLE 1

ALL SIZES ARE IN PLOTTER UNITS

X-DIRECTION Y-DIRECTION

FRAME SIZE 10.000 10.000
 PICTURE SIZE 7.0000 7.0000
 POSITION OF LOWER LEFT HAND CORNER OF PICTURE 3.0000 2.0000
 POSITION OF START OF TITLE 1.5000 1.0000
 POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST 0.10000 8.0000
 POSITION OF AXIS 1.5000 1.5000

SIZE OF CHARACTERS 0.16000
 WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

MODEL AXIS ROTATION 0.000E+00 1.57 0.000E+00

DISPLACED SHAPE OF U WILL BE DRAWN
 THE UNDEFORMED CONFIGURATION WILL BE DRAWN IN DOTTED LINES

ABAQUS PRODUCTION VERSION 4-7-22 DATE MAY 90 TIME 17:26:15 PAGE 39
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

BOUNDARY CONDITIONS

NODE	DOF	AMP. REF.	MAGNITUDE	NODE	DOF	AMP. REF.	MAGNITUDE
169	1		0.00000E+00	169	2		0.00000E+00
169	3		0.00000E+00	169	4		0.00000E+00
10169	2		0.00000E+00	10169	3		0.00000E+00
10169	4		0.00000E+00				

CONCENTRATED LOADS

NODE	DOF	AMP. REF.	AMPLITUDE	NODE	DOF	AMP. REF.	AMPLITUDE	NODE	DOF	AMP. REF.
169	6		-500.00	169	5		-500.00	10169	6	
10169	5		500.00	10169	1		-9.00000E+05			

ABAQUS PRODUCTION VERSION 4-7-22 DATE MAY 90 TIME 17:26:15 PAGE 39
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

M E S H P L O T T I N G

*PLOT
 *HIDEASE
 *DETAIL,ELSET=ANGLE,SECTION SCALING=20.
 *VIEW POINT,DEFINITION=MODEL AXIS ROTATION
 *DRAW

PLOT FRAME 1 CONSISTS OF ELSET ANGLE

ALL SIZES ARE IN PLOTTER UNITS

	X-DIRECTION	Y-DIRECTION
FRAME SIZE	10.000	10.000
PICTURE SIZE	7.0000	7.0000
POSITION OF LOWER LEFT HAND CORNER OF PICTURE	3.0000	2.0000
POSITION OF START OF TITLE	1.5000	1.0000
POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST	0.10000	8.0000
POSITION OF AXIS	1.5000	1.5000

SIZE OF CHARACTERS 0.20000

WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

THE VIEW ANGLES ARE 0.000E+00 1.57 0.000E+00

NUMBER OF COLORS AVAILABLE 1

*DETAIL,ELSET=PLATE,SECTION SCALING=20.

*SHRINK,FACTOR=0.1

*VIEW POINT,DEFINITION=MODEL AXIS ROTATION

*DRAW

PLOT FRAME 2 CONSISTS OF ELSET PLATE

ALL SIZES ARE IN PLOTTER UNITS

	X-DIRECTION	Y-DIRECTION
FRAME SIZE	10.000	10.000
PICTURE SIZE	7.0000	7.0000
POSITION OF LOWER LEFT HAND CORNER OF PICTURE	3.0000	2.0000
POSITION OF START OF TITLE	1.5000	1.0000
POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST	0.10000	8.0000
POSITION OF AXIS	1.5000	1.5000

SIZE OF CHARACTERS 0.20000

PAGE 00

TIME 17:26:15

ADAPUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING
 WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

THE VIEW ANGLES ARE 0.000E+00 1.57 0.000E+00

NUMBER OF COLORS AVAILABLE 1

•VIEW POINT

•SHRINK FACTOR=0.2

•DETAIL.ELSET=ANGLE

•DRAW

PLOT FRAME 3 CONSISTS OF ELSET ANGLE

ALL SIZES ARE IN PLOTTER UNITS

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST

POSITION OF AXIS

SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN FRAMES

NUMBER OF COLORS AVAILABLE 1

X-DIRECTION Y-DIRECTION

10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	8.0000
1.5000	1.5000

0.20000
5.0000

•DETAIL.ELSET=FIGURE

•DRAW

PLOT FRAME 4 CONSISTS OF ELSET FIGURE

ALL SIZES ARE IN PLOTTER UNITS

FRAME SIZE

PICTURE SIZE

POSITION OF LOWER LEFT HAND CORNER OF PICTURE

POSITION OF START OF TITLE

POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST

POSITION OF AXIS

SIZE OF CHARACTERS

WIDTH OF PAPER STRIP BETWEEN FRAMES

NUMBER OF COLORS AVAILABLE 1

X-DIRECTION Y-DIRECTION

10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	8.0000
1.5000	1.5000

0.20000
5.0000

ADAPUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90 TIME 17:26:15 PAGE 41
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEC. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

*DETAIL,INSET=JANGLE
 *PLOT MODE,DOTSIZE=0.002
 *DRAW,MODENUM

PLOT FRAME 5 CONSISTS OF ALL ELEMENTS

ALL SIZES ARE IN PLOTTER UNITS

	X-DIRECTION	Y-DIRECTION
FRAME SIZE	10.000	10.000
PICTURE SIZE	7.0000	7.0000
POSITION OF LOWER LEFT HAND CORNER OF PICTURE	3.0000	2.0000
POSITION OF START OF TITLE	1.5000	1.0000
POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST	0.10000	8.0000
POSITION OF AXIS	1.5000	1.5000

SIZE OF CHARACTERS 0.20000
 WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

NUMBER OF COLORS AVAILABLE 1

*SHRINK

ABAQUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5X5X5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

WAVEFRONT MINIMIZATION

NUMBER OF NODES 243
NUMBER OF ELEMENTS 72
ORIGINAL MAXIMUM D.O.F WAVEFRONT ESTIMATED AS 270
ORIGINAL RMS D.O.F WAVEFRONT ESTIMATED AS 201

SEARCH FOR POSSIBLE STARTING NODES IS COMPLETED

PERIPHERAL DIAMETER IS DEFINED BY NODES 321 10321

WAVEFRONT OPTIMIZED BY CHOOSING 10321 AS THE STARTING NODE

PROBLEM SIZE

NUMBER OF ELEMENTS IS 72
NUMBER OF NODES IS 243
TOTAL NUMBER OF VARIABLES IN THE MODEL 1058
(DEGREES OF FREEDOM PLUS ANY LAGRANGE MULTIPLIER VARIABLES)
MAXIMUM D.O.F. WAVEFRONT ESTIMATED AS 132
RMS WAVEFRONT ESTIMATED AS 111

FILE SIZES - THESE VALUES ARE IN WORDS AND ARE CONSERVATIVE UPPER BOUNDS

UNIT	LENGTH
2	127717
19	38200
21	113336
22	113336
25	12888
26	12888
28	3672

IF THE RESTART FILE IS WRITTEN, ITS LENGTH WILL BE APPROXIMATELY
29242 WORDS WRITTEN IN THE PRE PROGRAM
PLUS 14176 WORDS WRITTEN AT THE BEGINNING OF EACH STEP
PLUS 136496 WORDS FOR EACH INCREMENT WRITTEN TO THE RESTART FILE

PAGE 43

TIME 17:26:15

ABAQUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 5x5x5/16" SHELL ELEMENTS-END PLATES LOAD-TORSIONAL BUCKLING

228948

ALLOCATED WORKSPACE

THIS IS A DATA CHECK RUN. ANALYSIS ENDS.

Appendix E
TYPICAL RESULTS OF FINITE ELEMENT
ANALYSIS FOR SCHIFFLERIZED
4X4X1/4 IN. (100X100X6MM) ANGLE
PART A - OPTIONS BEING PROCESSED

ADAQUS PRODUCTION VERSION 4-7-22

DATE MAY 90

TIME 9:42:56

PAGE 1

A D A Q U S

THIS PROGRAM HAS BEEN DEVELOPED BY

HIDHITT, KARLSSON AND SORENSON, INC.
100 MEDWAY STREET
PROVIDENCE, R.I. 02906

THIS IS A PROPRIETARY PROGRAM AND IS MADE
AVAILABLE FOR INTERNAL USE AT UNIVERSITY OF WINDSOR,
UNDER THE TERMS OF THE ACADEMIC LICENSE AGREEMENT
WITH H.K.S. ALL USAGE MUST BE UNDER THE DIRECT
SUPERVISION AND CONTROL OF THE DESIGNATED USER.
THE DESIGNATED USER IS DR. GEORGE ARDEL-SAYED.
ANY NON-ACADEMIC USAGE OF THE PROGRAM REQUIRES
PAYMENT OF A MONTHLY CHARGE. ASSISTANCE AND
OTHER INFORMATION MAY BE OBTAINED FROM THE
DESIGNATED USER.

FOR ASSISTANCE OR ANY OTHER INFORMATION CALL
401-861-0820

H O T I C E

THIS IS ADAQUS VERSION 4-7.

SOME INPUT DATA OPTIONS AND USER SUBROUTINE INTERFACES
ARE INCOMPATIBLE WITH VERSION 4-5.

PLEASE MAKE SURE YOU ARE USING VERSION
4-6 OR 4-7 MANUALS.

APACUS: PERMISSION VERSION 4-7-22
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
END: PRINT ECHO=YES, MIDDLE=NO, HISTORY=NO

TIME 0:42:56

PAGE 2

ANALYSIS PRODUCTION VERSION 4-7-72 DATE 5 MAY 90 TIME 0:42:00 PAGE 1
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	
CARD 130	**RESTART,WRITE,FREQ=50 **STATIC,ALGEBRA,INC=500 **STATIC,PYOL=10.0,MTUL=10.0 0.1,1.0,0.001,0.1 **CLPRINT,FREQ=0 **S **E **SF **CE,CEEQ **HIDE PRINT,FREQ=1 **U **FILELL,FREQ=0 **SF **CF **HDL FILE,FREQ=0 **PRINT,RESIDUAL=NO **DLOAD **ETOP,BX,-15.000L3 **CLDAD 102.11,200.001 **PLOT,MODL,OUTSIZE=0.005 **SHRINK,FACTOR=0.0 **ZOOM,FACTOR=1.5 **DITAIL,ELSET=E1 **CENTER 37.900,0.000 **VIEW POINT,DEFINITION=MODEL AXIS ROTATION -15.0 **HIDE CASE **CONTOUR 511.0 **DITAIL,ELSET=E2 **CENTER 15.0,0.0,0.0 **VIEW POINT,DEFINITION=MODEL AXIS ROTATION **CONTOUR 511.0 **DITAIL,ELSET=E3 **CENTER 30.0,0.0,0.0															
CARD 135																
CARD 140																
CARD 145																
CARD 150																
CARD 155																
CARD 160																
CARD 165																
CARD 170																

ANALOGUS PRODUCTION VERSION 4.0-1-22 DATE 5 MAY 90
FOR USE AT UNIVERSITY OF WISCONSIN ORDER ACADEMIC LICENSE FROM HKS, INC. TIME 0:42:56 PAGE

••••• OPTIONS BEING PROCESSED •••••

•HEADING, C. 662.74-65-125M AND RESIDUAL STRESS, TORSIONAL BUCKLING

```

%HIDE
%HIGH, HST=DOT
%OCCUPY, CHANGE NUMBER=1000, OLDSET=DOT, SHIFT, NEW SET=TOP
%NST, HST=NU1, GENERATE
%NST, NEW SET=NU2, GENERATE
%NET1, HST=JANGLE

```

THE FOLLOWING NAMES WILL BE USED IN THE NFLL GENERATION

	1	2	3	4	5	6	7	8	9
100000	1								
100000	1001	1002	1003	1004	1005	1006	1007	1008	1009
100000	2								

[illegible]

[illegible]

AVANTUS PRODUCTION VERSION 4-7-22 DATE: MAY 90
 FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

TIME 0:42:56

PAGE 1

60 DUG. 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING

M E S H P L O T T I N G

*PLOT
 *OUTPLOT
 *DETAIL,ELSET=ANGLE,SECTION SCALING=20,
 *VIEW POINT,DEFINITION=MODEL AXIS ROTATION
 *DRAW

PLUT FRAME 1 CONSISTS OF ELSET ANGLE
 ALL SIZES ARE IN PLOTTER UNITS
 FRAME SIZE
 PICTURE SIZE
 POSITION OF LOWER LEFT HAND CORNER OF PICTURE
 POSITION OF START OF TITLE
 POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST
 POSITION OF AXIS
 SIZE OF CHARACTERS
 WIDTH OF PAPER STRIP BETWEEN FRAMES
 THE VIEW ANGLES ARE 0.000E+00 1.57 0.000E+00
 NUMBER OF COLORS AVAILABLE 1

X-DIRECTION	Y-DIRECTION
10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	0.10000
1.50000	1.50000

*DETAIL,ELSET=PLATE,SECTION SCALING=20.
 *VIEW POINT,DEFINITION=MODEL AXIS ROTATION
 *DRAW

PLUT FRAME 2 CONSISTS OF ELSET PLATE
 ALL SIZES ARE IN PLOTTER UNITS
 FRAME SIZE
 PICTURE SIZE
 POSITION OF LOWER LEFT HAND CORNER OF PICTURE
 POSITION OF START OF TITLE
 POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST
 POSITION OF AXIS
 SIZE OF CHARACTERS

X-DIRECTION	Y-DIRECTION
10.000	10.000
7.0000	7.0000
3.0000	2.0000
1.5000	1.0000
0.10000	0.10000
1.50000	1.50000

PLANT PRODUCTION VERSION 4-7-22 DATE MAY 90 TIME 0:42:56 PAGE 11
 OF US AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

60 DEG. 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL DUCKLING
 WIDTH OF PAPER STRIP BETWEEN FRAMES 5.0000

THE VIEW ANGLES ARE 0.000E+00 1.57 0.000E+00
 NUMBER OF COLORS AVAILABLE 1

VIEW 4 POINT
 CONTOUR FACTOR=0.2
 DETAIL ALL SET=ANGLE
 CGRAM, CLENH

PLOT FRAME 3 CONSISTS OF ELSET ANGLE
 ALL SIZES ARE IN PLOTTER UNITS
 FRAME SIZE 10.0000
 PICTURE SIZE 7.0000
 POSITION OF LOWER LEFT HAND CORNER OF PICTURE 2.0000
 POSITION OF START OF TITLE 3.0000
 POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST 1.5000
 POSITION OF AXIS 0.10000
 SIZE OF CHARACTERS 1.5000
 WIDTH OF PAPER STRIP BETWEEN FRAMES 0.16000
 NUMBER OF COLORS AVAILABLE 5.0000

DETAIL SET=ANGLE
 PLOT NODE, OUT SIZE=0.002
 CGRAM, NODE NUM

PLOT FRAME 4 CONSISTS OF ALL ELEMENTS
 ALL SIZES ARE IN PLOTTER UNITS
 FRAME SIZE 10.0000
 PICTURE SIZE 7.0000
 POSITION OF LOWER LEFT HAND CORNER OF PICTURE 2.0000
 POSITION OF START OF TITLE 3.0000
 POSITION OF UPPER LEFT HAND CORNER OF VARIABLE LIST 1.5000
 POSITION OF AXIS 0.10000
 SIZE OF CHARACTERS 1.5000
 WIDTH OF PAPER STRIP BETWEEN FRAMES 0.16000
 NUMBER OF COLORS AVAILABLE 5.0000

PAGE 17

TIME 0:42:56

ALTAQUS PRODUCTION VERSION 4-7-22 DATE 5MAY 90
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
60 DEG. 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING
SHRINK

DIST: ADLURI

FOR USER: KLO

PRINT COMPLETED AT 01:00:30

PAGE 13

TIME 0:42:50

DATE 5MAY 90

ADAMS PRODUCTION VERSION 4-7-22
FOR USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.

6.0 DLG. 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING

MINIMUM AVEFRONT MINIMIZATION

NUMBER OF NODES 120
NUMBER OF ELEMENTS 109
ORIGINAL RMS D.O.F. WAVEFRONT ESTIMATED AS 120
ORIGINAL RMS D.O.F. WAVEFRONT ESTIMATED AS 109

SEARCH FOR POSSIBLE STARTING NODES IS COMPLETED
PERIPHERAL DIAMETER IS DEFINED BY NODES 23 1023
WAVEFRONT OPTIMIZED BY CHOOSING 1023 AS THE STARTING NODE

PROBLEM SIZE

NUMBER OF ELEMENTS IS 96
NUMBER OF NODES IS 115
TOTAL NUMBER OF VARIABLES IN THE MODEL 690
TOTAL NUMBER OF FREEDOM PLUS ANY LAGRANGE MULTIPLIER VARIABLES 100
MAXIMUM D.O.F. WAVEFRONT ESTIMATED AS 106
WAS WAVEFRONT ESTIMATED AS

FILE SIZES - THESE VALUES ARE IN WORDS AND ARE CONSERVATIVE UPPER BOUNDS

UNIT	LENGTH
2	10379
21	21600
22	21600
23	21600
26	21600
20	2592

IF THE RESTART FILE IS WRITTEN, ITS LENGTH WILL BE APPROXIMATELY
14080 WORDS WRITTEN TO THE RESTART PROGRAM OF EACH STEP
PLUS 6336 WORDS WRITTEN AT THE BEGINNING OF EACH STEP
PLUS 29110 WORDS FOR EACH INCREMENT WRITTEN TO THE RESTART FILE

ANALYSIS PRODUCTION VERSION 4-7-22
NO USE AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
NO DEC. 4441/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING
DATE MAY 90
TIME 0:42:56
PAGE 14
160034
ALLOCATED WORKSPACE

Appendix F
TYPICAL RESULTS OF FINITE ELEMENT
ANALYSIS FOR SCHIFFLERIZED
4X4X1/4 IN. (100X100X6MM) ANGLE
PART B - NONLINEAR ANALYSIS

ACADEMICS PRODUCTION VERSION 4-7-72
 FOR USE AT UNIVERSITY OF WISCONSIN UNDER ACADEMIC LICENSE FROM IKS, INC.
 65 DEG. 44X41/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING

PAGE 1

TIME 0:43:49

DATE MAY 90

TIME 0:43:49

STEP 1

TIME COMPLETED IN THIS

STEP 1

STATISTICAL ANALYSIS

AUTOMATIC CONTROL WITH -
 A SUGGESTED INITIAL TIME INCREMENT OF 1.00
 AND A TOTAL TIME PERIOD OF 1.00
 THE MINIMUM TIME INCREMENT ALLOWED IS 1.0000E-05
 THE MAXIMUM TIME INCREMENT ALLOWED IS 1.00

EQUILIBRIUM TOLERANCES -
 TOLERANCE ON INDIVIDUAL FORCE COMPONENTS 10.0
 TOLERANCE ON INDIVIDUAL MOMENT COMPONENTS 10.0
 LARGE DISPLACEMENT THEORY WILL BE USED

MAXIMUM NUMBER OF INCREMENTS ALLOWED IN THIS STEP IS 10
 MAXIMUM NUMBER OF ITERATIONS ALLOWED PER INCREMENT IS 6
 PRINT OF INCREMENT NUMBER, TIME, ETC., EVERY 1 INCREMENTS

INCREMENT NUMBER 1 ATTEMPT NUMBER 1

TIME INCREMENT = 1.00

PRODUCTION VERSION 4-7-22 DATE 5MAY 90 PAGE 2
 UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING

ITERATION	1	NO CONVERGENCE	2	CONVERGENT SOLUTION
MAXIMUM RESIDUALS ASSOCIATED WITH EACH O.O.F.				
MAXIMUM RESIDUAL OCCURS AT NODE				
1	9.87	8	1014	1
2	43.8	105	936	2
3	-13.6	909	934	3
4	-6.53	108	994	4
5	-0.216	379	202	5
6	0.148	305	202	6

MAXIMUM DISPLACEMENT INCREMENT ASSOCIATED WITH O.O.F.	MAXIMUM DISPLACEMENT INCREMENT OCCURS AT NODE	MAXIMUM DISPLACEMENT INCREMENT ASSOCIATED WITH O.O.F.	MAXIMUM DISPLACEMENT INCREMENT OCCURS AT NODE
1	2.447E-03	1022	1
2	2.447E-03	555	2
3	1.087E-05	16	3
4	-8.456E-05	1020	4
5	2.125E-05	20	5
6	1.222E-03	5	6

MAXIMUM DISPLACEMENT INCREMENT ASSOCIATED WITH O.O.F.	MAXIMUM DISPLACEMENT INCREMENT OCCURS AT NODE	MAXIMUM DISPLACEMENT INCREMENT ASSOCIATED WITH O.O.F.	MAXIMUM DISPLACEMENT INCREMENT OCCURS AT NODE
1	2.447E-03	1022	1
2	2.447E-03	555	2
3	1.087E-05	16	3
4	-8.456E-05	1020	4
5	2.125E-05	20	5
6	1.222E-03	5	6

TIME COMPLETED DURING THIS STEP 1.00 FRACTION OF STEP COMPLETED 1.00
 TOTAL ACCUMULATED TIME 1.00

STARTING FRAME 1

FRAME 1 SHOWS DISPLACED POSITION BASED ON U WITH MAGNIFICATION FACTOR OF 1700.

9. 0.00001001 V0051001 4-7-22
 AT UNIVERSITY OF MISSOURI UNDER ACADEMIC LICENS FROM H.S. INC.
 0. 48481/4-65.125" NO RESIDUAL STRESS, FORSADIAL BUCKLING

PAGE 1

TIME 0:43:45

STEP 2 INCREMENT 1
 TIME COMPLETED IN THIS STEP

STEP 2

STATIC ANALYSIS

AUTOMATIC CONTROL WITH - INCREMENT OF 1.000E-01
 A SUGGESTED INITIAL PERIOD OF 100
 AND A TOTAL TIME PERIOD OF 1.000E-01
 THE MINIMUM TIME INCREMENT ALLOWED IS 1.000E-01
 THE MAXIMUM TIME INCREMENT ALLOWED IS 1.000E-01

EQUILIBRIUM TOLERANCES - 10.0
 TOLERANCE ON INDIVIDUAL FORCE COMPONENTS 10.0
 TOLERANCE ON INDIVIDUAL MOMENT COMPONENTS 10.0

LARGE DISPLACEMENT THEORY WILL BE USED

MAXIMUM NUMBER OF INCREMENTS ALLOWED IN THIS STEP IS 500
 MAXIMUM NUMBER OF ITERATIONS ALLOWED PER INCREMENT IS 6

PRINT OF RESIDUALS DURING ITERATION SUPPRESSED

PRINT OF INCREMENT NUMBER, TIME, ETC., EVERY 1 INCREMENTS

INCREMENT NUMBER 1 ATTEMPT NUMBER 1

TIME INCREMENT = 1.000E-01

PRODUCTION VERSION 4-7-22 DATE MAY 90 PAGE 4
 UNIVERSITY OF WISCONSIN UNDER ACADEMIC LICENSE FROM MKS, INC.
 608X1/4-05.12% NO RESIDUAL STRESS, INITIAL HICKLING
 TIME STOPPED IN THIS STEP
 TIME COMPLETED IN THIS STEP
 ITERATION 2 CONVERGENT SOLUTION
 COMPLETED DURING THIS STEP 1.000E-01, TIME INCREMENT COMPLETED 1.000E-01, FRACTION OF STEP COMPLETED 1.0
 ACCUMULATED TIME

N O D E O U T P U T

THE FOLLOWING TABLE IS PRINTED FOR ALL NODES

TIME- STEP	RF1	RF2	RF3	RM1	RM2	RM3
2.000E+00	2.000E+00	-99.05	1.2910E-02	4.7797E-03	0.0000E+00	0.0000E+00
(2.000E+00)	2.000E+00	-99.05	1.2910E-02	4.7797E-03	0.0000E+00	0.0000E+00
2.000E+00	2.000E+00	0.0000E+00	1.2910E-02	4.7797E-03	0.0000E+00	0.0000E+00
0.000E+00	0.000E+00	-99.05	0.000E+00	0.000E+00	0.000E+00	0.000E+00

INCREMENT NUMBER 2 ATTEMPT NUMBER 1

TIME INCREMENT = 1.000E-01

H. PRODUCTION VOLUMES FOR 4-7-22 DATE MAY 90
 AT EFFICIENCY OF MENDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
 C. 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING
 TIME 0:43:45 PAGE 5
 STEP 2 INCREMENTAL
 TIME COMPLETED IN THIS STEP 1
 ITERATION 3 CONVERGENT SOLUTION
 COMPLETED DURING THIS STEP C-200 TIME INCREMENT COMPLETED 1.000E-01, FRACTION OF STEP COMPLETED 1.0
 ACCUMULATED TIME 1.20

NODE OUTPUT

LOADING TABLE IS PRINTED FOR ALL NODES

NODE	RF1	RF2	RF3	RH1	RH2	RH3
1	4.0000E+04	-99.97	4.1932E-02	-5.2571E-03	0.0000E+00	0.0000E+00
2	0.0000E+00	-99.97	4.1822E-02	-5.2565E-03	0.0000E+00	0.0000E+00
3	4.0000E+04	0.0000E+00	4.1732E-02	0.0000E+00	0.0000E+00	0.0000E+00
4	0.0000E+00	-99.97	0.0000E+00	-5.2571E-03	0.0000E+00	0.0000E+00

INCREMENT NUMBER 3 ATTEMPT NUMBER 1

TIME INCREMENT = 1.000E-01

SECTION VERSION 4-7-22
 UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
 4/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING

TIME 0:43:45
 STEP 2
 TIME COMPLETED IN THIS STEP 0.300
 FRACTION OF STEP COMPLETED 0.300

ITERATION 4 CONVERGENT SOLUTION

TIME INCREMENT COMPLETED 1.000E-01, FRACTION OF STEP COMPLETED 0.300
 TIME DURING THIS STEP 0.300
 TIME ELAPSED TIME 1.030

N O D E O U T P U T

TABLE IS PRINTED FOR ALL NODES

RF1	RF2	RF3	RM1	RM2	RM3
0.0000E+00	-100.0	-5.4965E-03	8.2399E-02	0.0000E+00	0.0000E+00
0.0000E+00	-100.0	-5.4995E-03	8.2399E-02	0.0000E+00	0.0000E+00
0.0000E+00	0.0000E+00	0.0000E+00	8.2399E-02	0.0000E+00	0.0000E+00
0.0000E+00	-100.0	-5.4995E-03	8.2399E-02	0.0000E+00	0.0000E+00

INCREMENT NUMBER 4 ATTEMPT NUMBER 1

TIME INCREMENT = 1.000E-01

COMPUTATION VERSION 4-7-22 DATE MAY 90 TIME 0:43:45 PAGE 7
 AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM IKS, INC.
 STEP 2 INCREMENT 5
 TIME COMPLETED IN THIS STEP 3.
 6. 4441/4-65.125 NO RESIDUAL STRESS, TORSIONAL BUCKLING

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES.
 EIGENVALUE EXTRACTION STEP THE NUMBER OF NEGATIVE EIGENVALUES IS EQUAL TO THE NUMBER
 OF EIGENVALUES BELOW THE CURRENT SHIFT POINT.
 MAY BE USED TO CHECK THAT EIGENVALUES HAVE NOT BEEN MISSED.
 IN ALL CASES, NEGATIVE EIGENVALUES MEAN THAT THE SYSTEM MATRIX IS NOT POSITIVE DEFINITE.
 AS AN EXAMPLE, A BIFURCATION (BUCKLING) LOAD MAY HAVE BEEN EXCEEDED.
 THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE
 THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 4 ATTEMPT NUMBER 2

TIME INCREMENT = 5.000E-02

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE
 THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE
 THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 4 ATTEMPT NUMBER 3

TIME INCREMENT = 2.500E-02

DE PROGRAM VERSION 4-7-22
 AT ONLY ASITY OF WINDSOR UNDER ACADEMIC LICENSE FROM IKS, INC.
 DATE 5 MAY 90
 TIME 0:43:45
 PAGE 0
 P.C. 444X1/4-85.125" NO RESIDUAL STRESS, FORSTURAL BUCKLING
 STEP 2 INCREMENT
 TIME COMPLETED IN THIS STEP
 ITERATION 3 CONVERGENT SOLUTION
 TIME INCREMENT COMPLETED 2.500E-02, FRACTION OF STEP COMPLETED
 TIME ACCUMULATED TIME 0.125
 1.32

N O D E O U T P U T

FOLLOWING TABLE IS PRINTED FOR ALL NODES

POINT- NODE	KF1	KF2	KF3	KH1	KH2	KH3
1	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
2	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
3	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
4	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
5	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
6	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
7	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00
8	0.0000E+00	-99.98	0.1625	2.988	0.0000E+00	0.0000E+00

STARTING FRAME 1

FRAME 1 CONTOUR LEVELS
 I.D. VALUE

1	-0.0000E+00
2	-0.7143E+04
3	-5.4200E+04
4	-5.1429E+04
5	-2.8571E+04
6	-1.5714E+04
7	-2.8571E+04
8	1.0000E+04

0005 PRODUCTION VERSION 4-7-22
 0001 AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
 0006 4X4X1/4-65.125" NO RESIDUAL STRESS, TORSIONAL BUCKLING
 DATE MAY 96
 TIME 0:43:45
 PAGE 2
 STEP 2
 TIME COMPLETED IN THIS STEP

STARTING FRAME 2

FRAME 2 CONTOUR LEVELS

I.D.	VALUE
1	-7.0000E+04
2	-5.0571E+04
3	-4.7143E+04
4	-1.5714E+04
5	-2.4286E+04
6	-1.2857E+04
7	-1429
8	1.0000E+04

STARTING FRAME 3

FRAME 3 CONTOUR LEVELS

I.D.	VALUE
1	-7.0000E+04
2	-5.0571E+04
3	-4.7143E+04
4	-1.5714E+04
5	-2.4286E+04
6	-1.2857E+04
7	-1429
8	1.0000E+04

STARTING FRAME 4

ADP. PRODUCTION VERSION 4-7-22
 000 4X4X1/4-65.125 NO RESIDUAL STRESS, TORSIONAL BUCKLING
 DATE: MAY 90
 TIME 0:43:45 PAGE 1
 STEP 2 INCREMENT
 TIME COMPLETED IN THIS STEP

FRAME 4 CONTOUR LEVELS

I.D. VALUE

1 -8.0000E+04
 2 -6.7143E+04
 3 -5.4206E+04
 4 -4.1269E+04
 5 -2.8331E+04
 6 -1.5394E+04
 7 -2857
 8 1.0000E+04

STARTING FRAME 5

FRAME 5 SHOWS DISPLACED POSITION BASED ON U

WITH MAGNIFICATION FACTOR OF 21.3

STARTING FRAME 6

FRAME 6 SHOWS DISPLACED POSITION BASED ON U

WITH MAGNIFICATION FACTOR OF 21.3

STARTING FRAME 7

FRAME 7 SHOWS DISPLACED POSITION BASED ON U

WITH MAGNIFICATION FACTOR OF 2.40

INCREMENT NUMBER 5 ATTEMPT NUMBER 1

TIME INCREMENT = 2.500E-02

THE SYSTEM MATRIX HAS 1 NACTIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF :

OF PRODUCTION VERSION 4-7-22
 AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
 DATE: 5 MAY 90
 TIME 0:43:45 PAGE 11
 STEP 2 INCREMENT
 TIME COMPLETED IN THIS STEP

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 5 ATTEMPT NUMBER 2

TIME INCREMENT = 0.250E-03

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 5 ATTEMPT NUMBER 3

TIME INCREMENT = 3.0007E-03

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 5 ATTEMPT NUMBER 4

TIME INCREMENT = 2.765E-03

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF

PRODUCTION VERSION 4-7-22 DATE 5MAY 90 TIME 0143545 PAGE 12
 AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM IKS, INC.
 STEP 2 INCREMENT 5
 TIME COMPLETED IN THIS STEP 0.0

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 5 ATTEMPT NUMBER 5

TIME INCREMENT = 1.392E-03

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

INCREMENT NUMBER 5 ATTEMPT NUMBER 6

TIME INCREMENT = 1.000E-03

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE

THE SYSTEM MATRIX HAS 1 NEGATIVE EIGENVALUES. EXPLANATIONS ARE SUGGESTED AFTER THE FIRST OCCURRENCE OF THE

CONVERGENCE JUDGED UNLIKELY - INCREMENT WILL BE ATTEMPTED AGAIN WITH A SMALLER TIME INCREMENT

TIME INCREMENT REQUIRED IS LESS THAN THE MINIMUM SPECIFIED - ANALYSIS ENDS

COMPLETED DURING THIS STEP 0.226 FRACTION OF STEP COMPLETED 0.0

ACCUMULATED TIME 1.33

PRODUCTION VERSION 4-7-22 DATE: MAY 90 TIME 0:43:45 PAGE: 13
AT UNIVERSITY OF WINDSOR UNDER ACADEMIC LICENSE FROM HKS, INC.
G. 4441/4-65-125 NO RESIDUAL STRESS, TORSIONAL BUCKLING STEP 2 INCREMENT
TIME COMPLETED IN THIS STEP

M O D E O U T P U T

LOADING TABLE IS PRINTED FOR ALL MODES

MODE	RF1	RF2	RF3	KM1	KM2	KM3
1	6.5178E+04	604.1	32.72	29.31	0.0000E+00	0.0000E+00
2	0.0000E+00	604.1	32.72	29.31	0.0000E+00	0.0000E+00
3	6.5178E+04	624.1	32.72	29.31	0.0000E+00	0.0000E+00
4	0.0000E+00	624.1	32.72	29.31	0.0000E+00	0.0000E+00
5	0.0000E+00	0.0000E+00	0.0900E+00	0.0000E+00	0.0000E+00	0.0000E+00

THE ANALYSIS IS ABORTED BECAUSE OF THE PROBLEMS ENCOUNTERED
LOOK AT THE MESSAGES SINCE THE START OF THE LAST INCREMENT FOR THE CAUSE OF THE TERMINATION

END OF RUN

VITA AUCTORIS

The author was born in 1961 at Chittoor, Andhra Pradesh, India. He completed his higher secondary education with National Merit Honours and graduated with Distinction from Jawaharlal Nehru Technological University (Kakinada Campus), Hyderabad, India in 1983. He obtained his M.Tech. from Indian Institute of Technology, Kanpur in 1985. Thereafter, he joined India's premier consulting engineering organisation, Tata Consulting Engineers at Bombay, where he gained valuable experience in the design of structures and development of related software. He was the author of three major software packages and manuals published and distributed by Tata Consulting Engineers and was author/co-author of two papers on analysis and design of nuclear power plants.

In 1989, he joined the University of Windsor, Ontario, Canada in pursuit of further studies.